

Computer Graphics

Lab 6: Advanced Texture Mapping

Dev Environment: Lab Package

Hosted on GitHub: https://github.com/jku-icg/cg_lab_2021

The repository will be updated during the lab with the new projects.

To get started (**now**):

1. Download the ZIP
2. Extract the folder
3. Open Visual Studio Code
4. Open `cg_lab_2021` folder
(*File* → *Open*)
5. Click on **Go Live** button in lower right corner

JKU-ICG / `cg_lab_2021` Notifications Star 2 Fork 8

<> Code Issues Pull requests Actions Projects Security ...

main Go to file **Code** About

Repository for the Computer Graphics Lab 2021

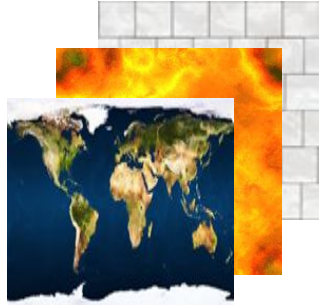
[jku-icg.github.io/cg_1...](https://github.com/jku-icg/cg_lab_2021)

Readme MIT License

Releases 2

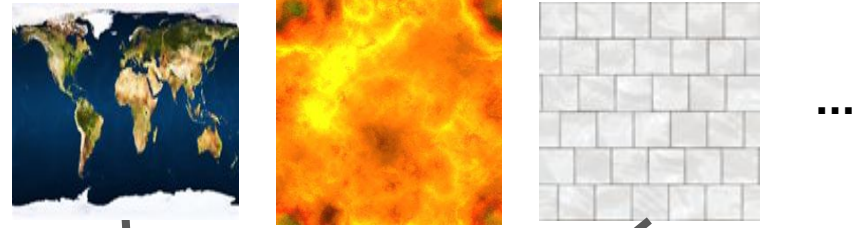
Recap: Texturing

images in
main memory



upload to GPU (once)

textures in graphics memory



bind textures for
current model

vertices +
texture
coordinates

texture units (handle
lookup + filtering)

texture
unit 0

texture
unit 1

...

shader: request texture data (e.g. color)
from texture unit at texture coordinates



Agenda for Today

Shadow Mapping

Overview

Recap: Render to Texture

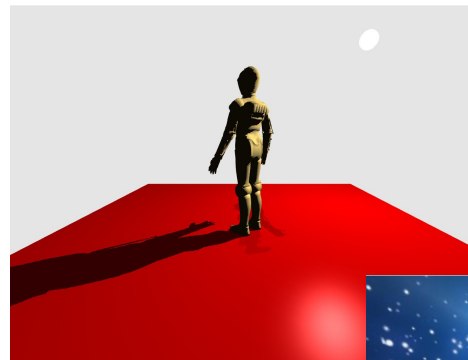
Task 1: Setup Camera for Light

Depth Comparison

Eye-to-Light Matrix

Task 2: Shadow Mapping

Extra Task: Smooth Shadows



Environment Mapping

Cube Mapping

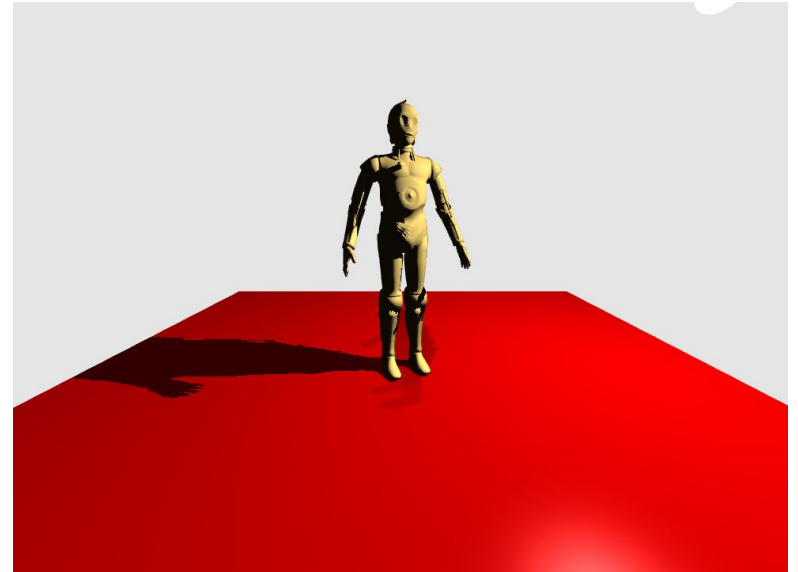
Differences to 2D Textures

Task 3: Cube Mapping

Texture Filtering

Shadow Mapping

- 05_texturing
- 05_texturing_handout
- 06_environment_mapping_handout
- 06_shadow_mapping_handout
- libs



Shadow Mapping

Generate shadows using depth textures

Pure image based technique!

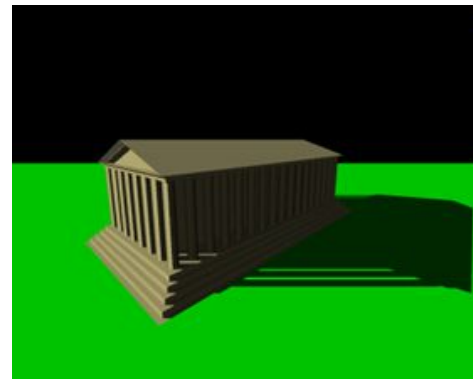
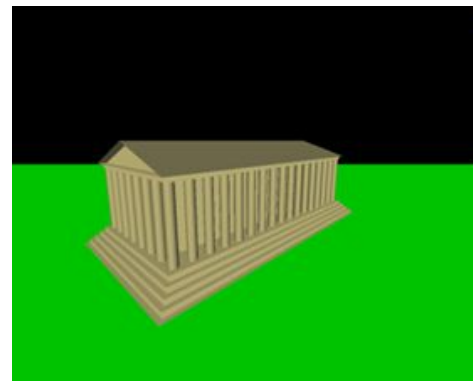
2 Render Passes:

1. Render scene from perspective of light source into texture (we need the depth map!)

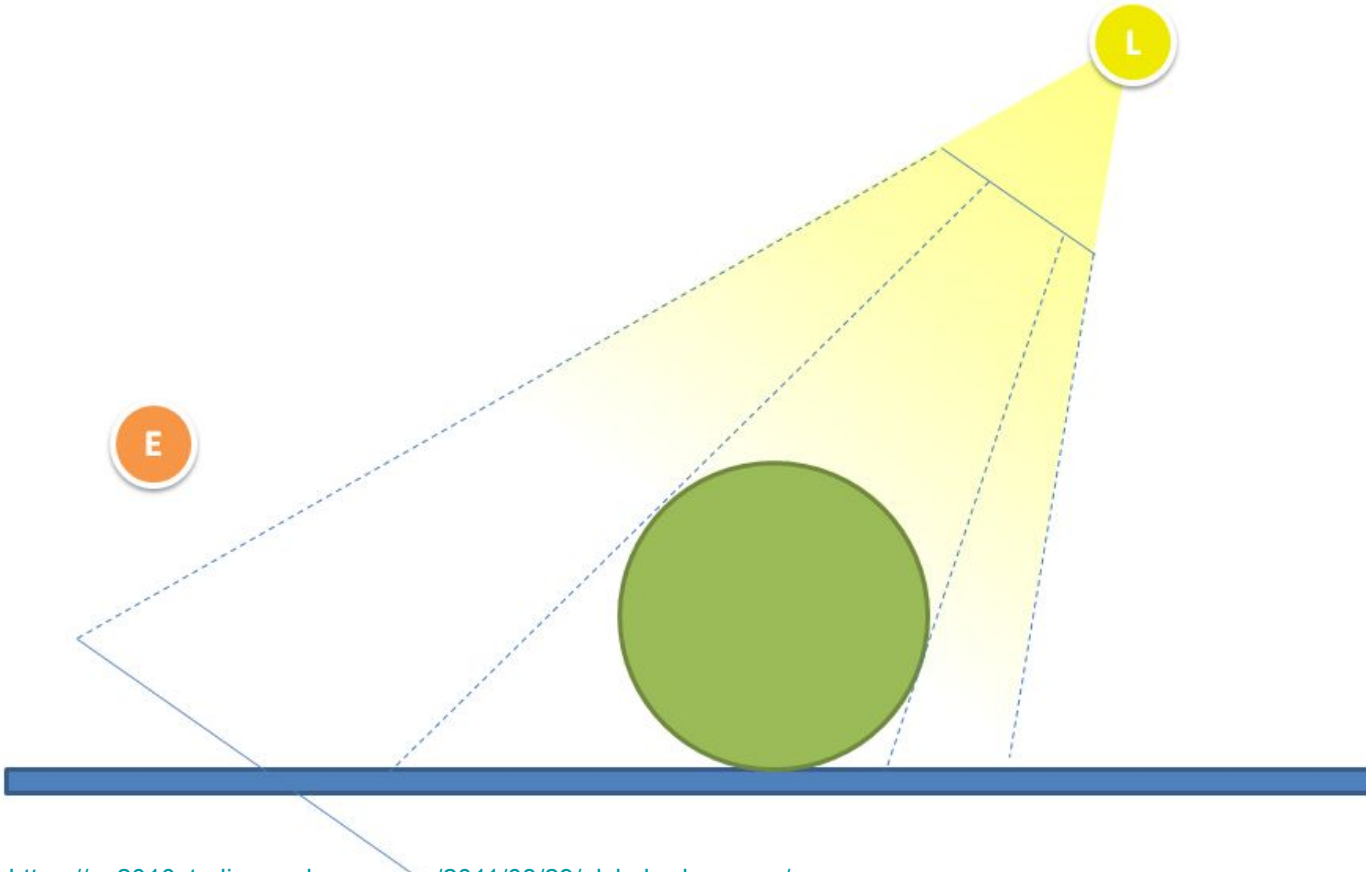
2. Render scene from perspective of camera:

For each fragment check if distance to light source is larger than stored depth in texture

If distance is larger: fragment is behind an object
→ it is in the shadow!

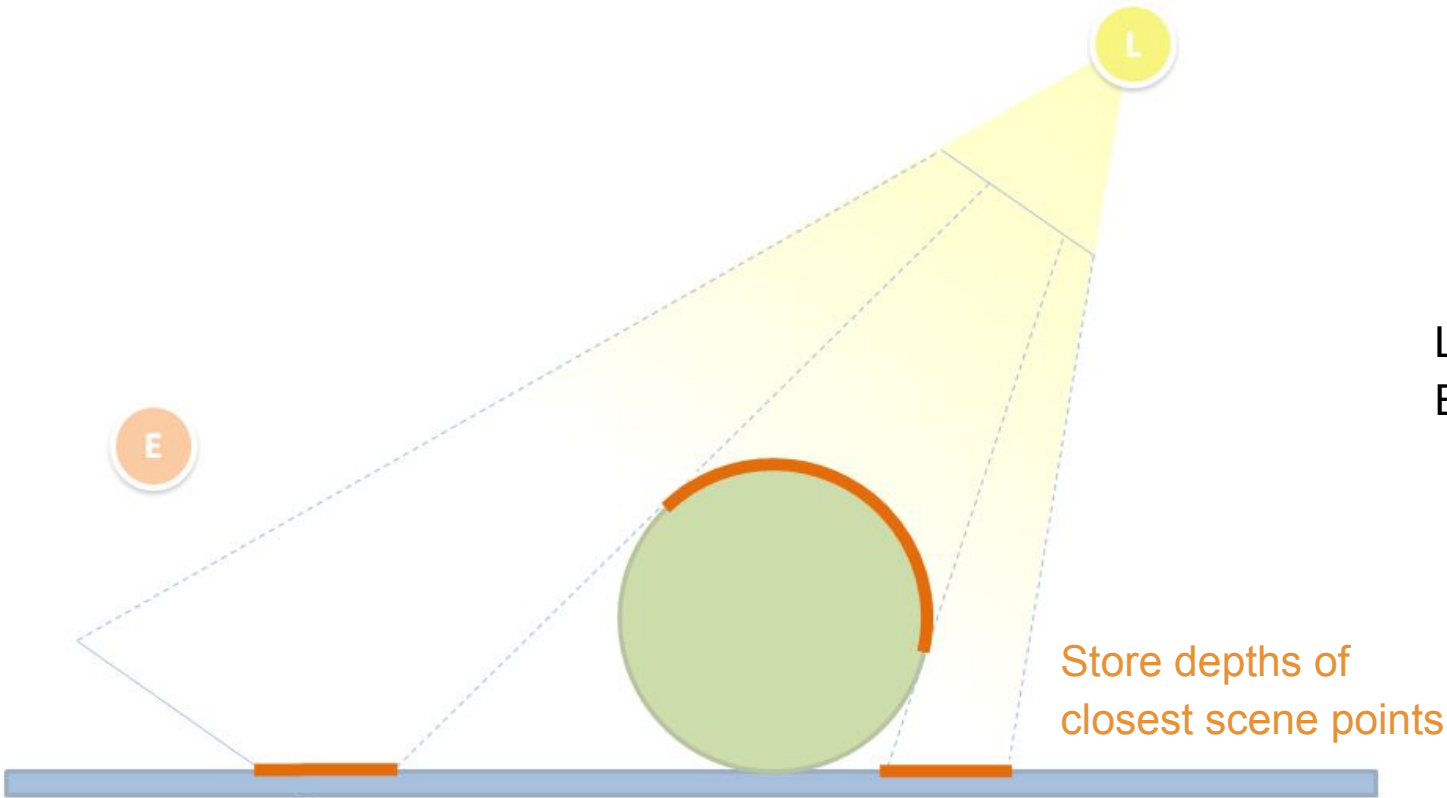


Shadow Mapping Example



L = Light source
E = Eye / Camera

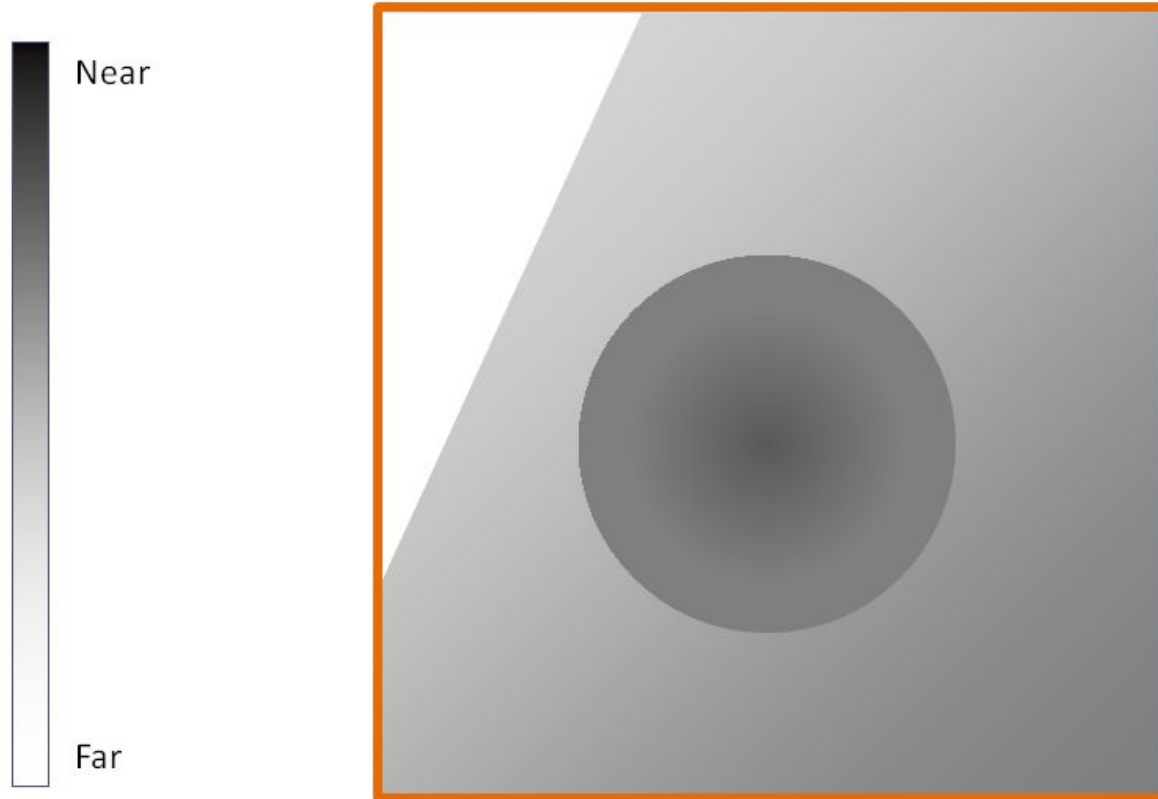
Render Scene From Light Perspective



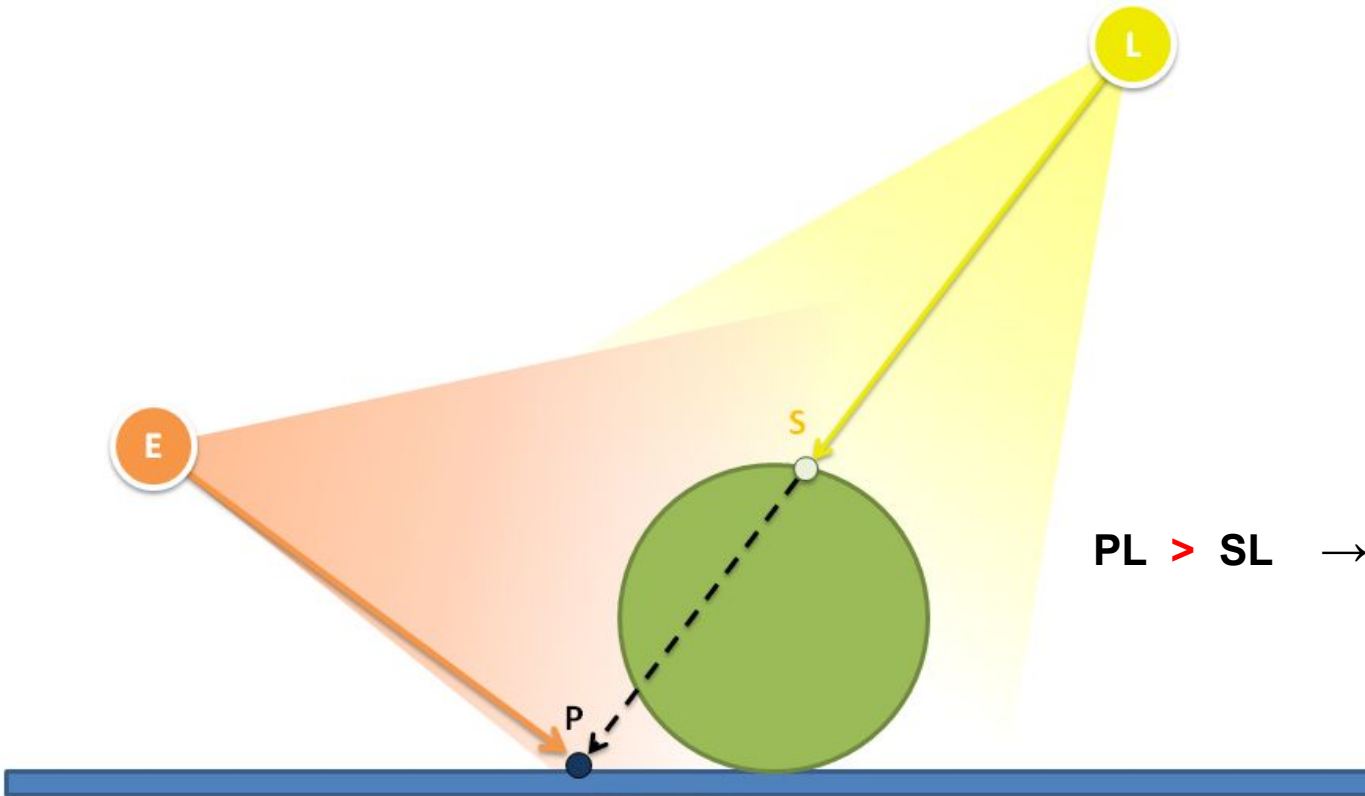
L = Light source
E = Eye / Camera

Store depths of
closest scene points

Resulting Depth Map



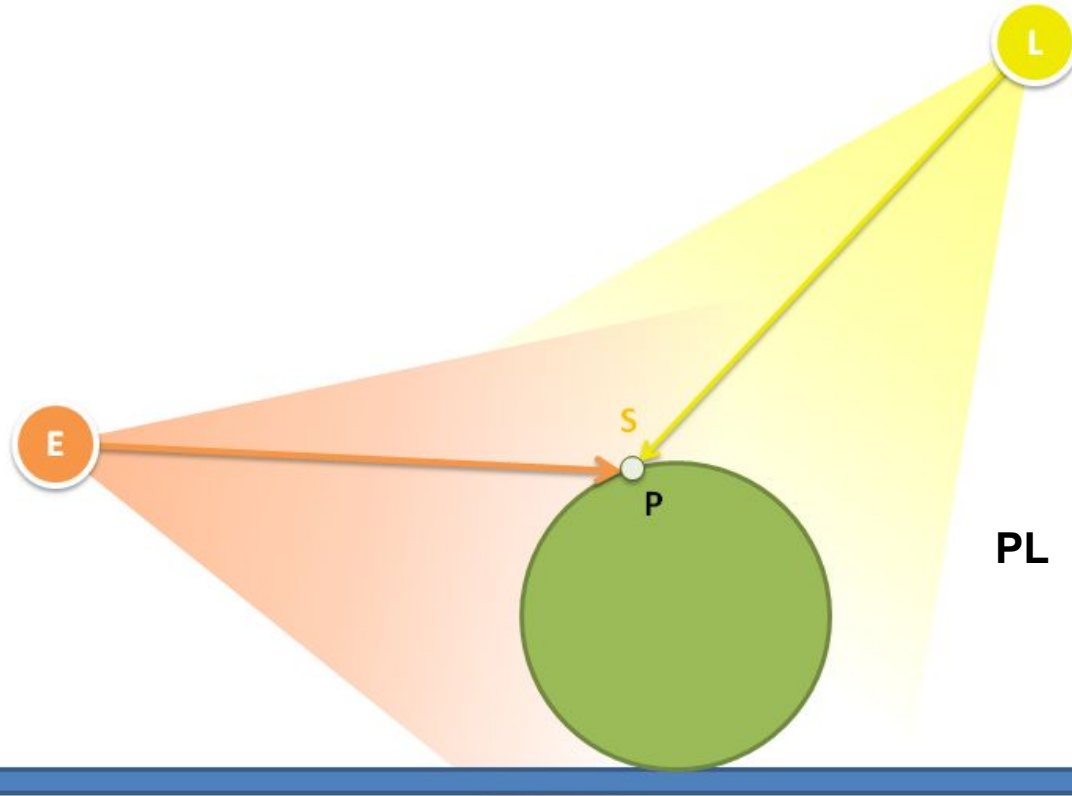
Render Scene from Camera Perspective



L = Light source
E = Eye / Camera
P = Rendered Point
S = Closest Point

$PL > SL \rightarrow$ Shadow

Render Scene from Camera Perspective



L = Light source
E = Eye / Camera
P = Rendered Point
S = Closest Point

PL = SL → No Shadow

Recap: Render to Texture

Render into framebuffer:

1. Enable framebuffer:

```
gl.bindFramebuffer(gl.FRAMEBUFFER, renderTargetFramebuffer);
```

2. Setup viewport + camera + clear buffers + render scene graph

3. Disable framebuffer:

```
gl.bindFramebuffer(gl.FRAMEBUFFER, null);
```

Nothing will be shown on screen!

Framebuffer has attached textures to render into:

```
gl.framebufferTexture2D(gl.FRAMEBUFFER, gl.COLOR_ATTACHMENT0, gl.TEXTURE_2D, renderTargetColorTexture, 0);  
gl.framebufferTexture2D(gl.FRAMEBUFFER, gl.DEPTH_ATTACHMENT, gl.TEXTURE_2D, renderTargetDepthTexture, 0);
```

See `initRenderToTexture` for complete initialization!

Recap: Render to Texture

```
function renderToTexture(timeInMilliseconds)
{
    //bind framebuffer to draw scene into texture
    gl.bindFramebuffer(gl.FRAMEBUFFER, renderTargetFramebuffer);

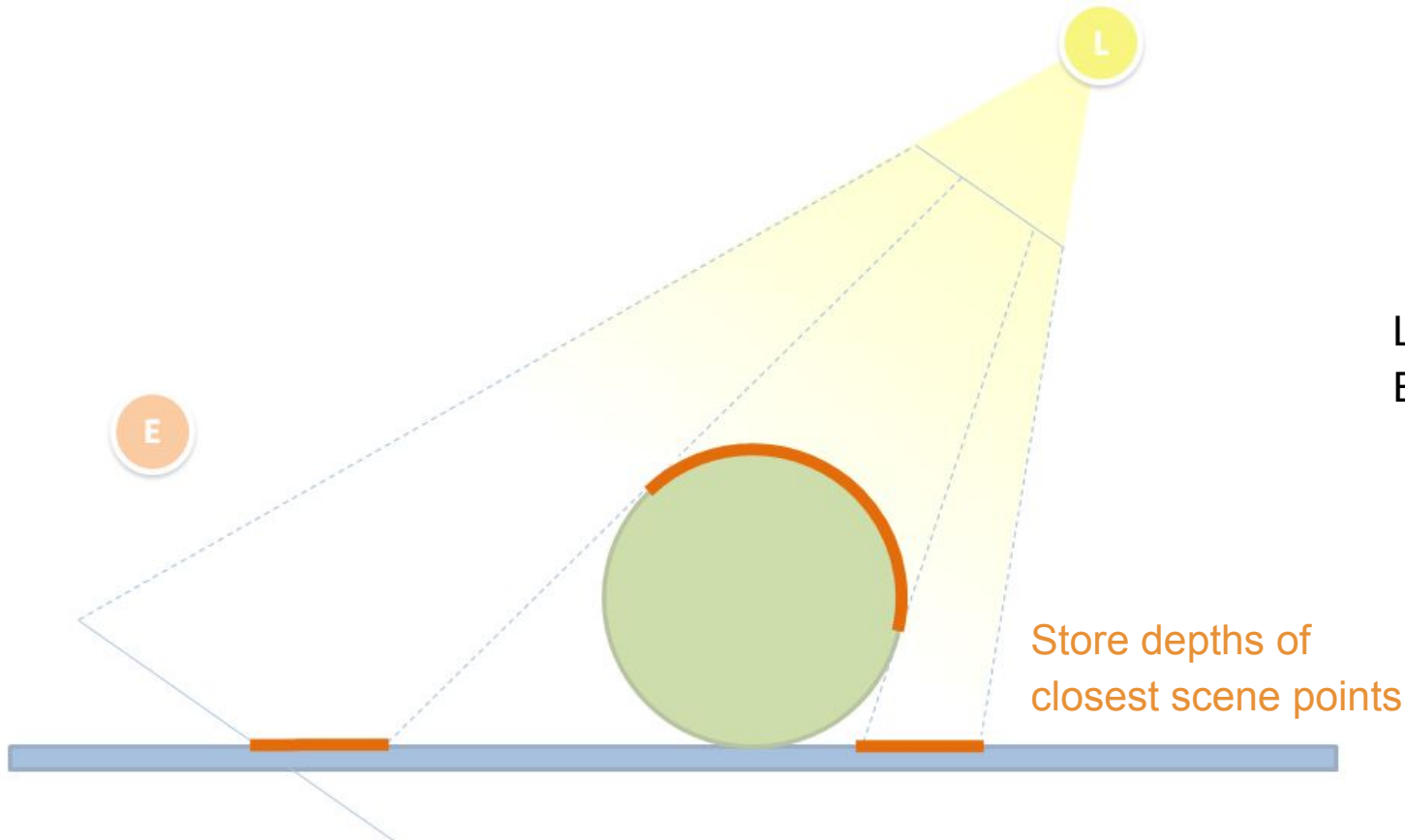
    //setup viewport
    gl.viewport(0, 0, framebufferWidth, framebufferHeight);
    gl.clearColor(0.9, 0.9, 0.9, 1.0);
    gl.clear(gl.COLOR_BUFFER_BIT | gl.DEPTH_BUFFER_BIT);

    //setup context and camera matrices
    const context = createSGContext(gl);
    context.projectionMatrix = mat4.perspective(mat4.create(), 30, framebufferWidth / framebufferHeight, 0.01, 100);
    context.viewMatrix = mat4.lookAt(mat4.create(), [0,-1,-4], [0,0,0], [0,1,0]);

    //render scenegraph
    rootnofloor.render(context);

    //disable framebuffer (to render to screen again)
    gl.bindFramebuffer(gl.FRAMEBUFFER, null);
}
```

Render Scene From Light Perspective



L = Light source
E = Eye / Camera

Store depths of
closest scene points

Task 1: Setup Light View Matrix

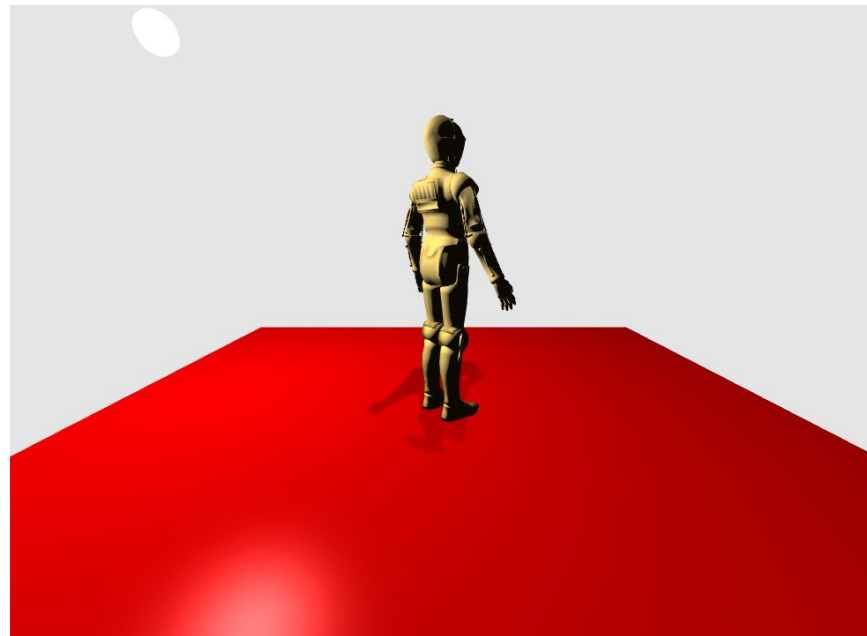
Goal:

Render scene to texture from light's perspective. Resulting depth map can be seen in the texture on the floor.

Tasks:

1.1 Adapt `viewMatrix` in `renderToTexture` function according to the light position.

Hint: Use provided light position in world space and the `mat4.lookAt` function.

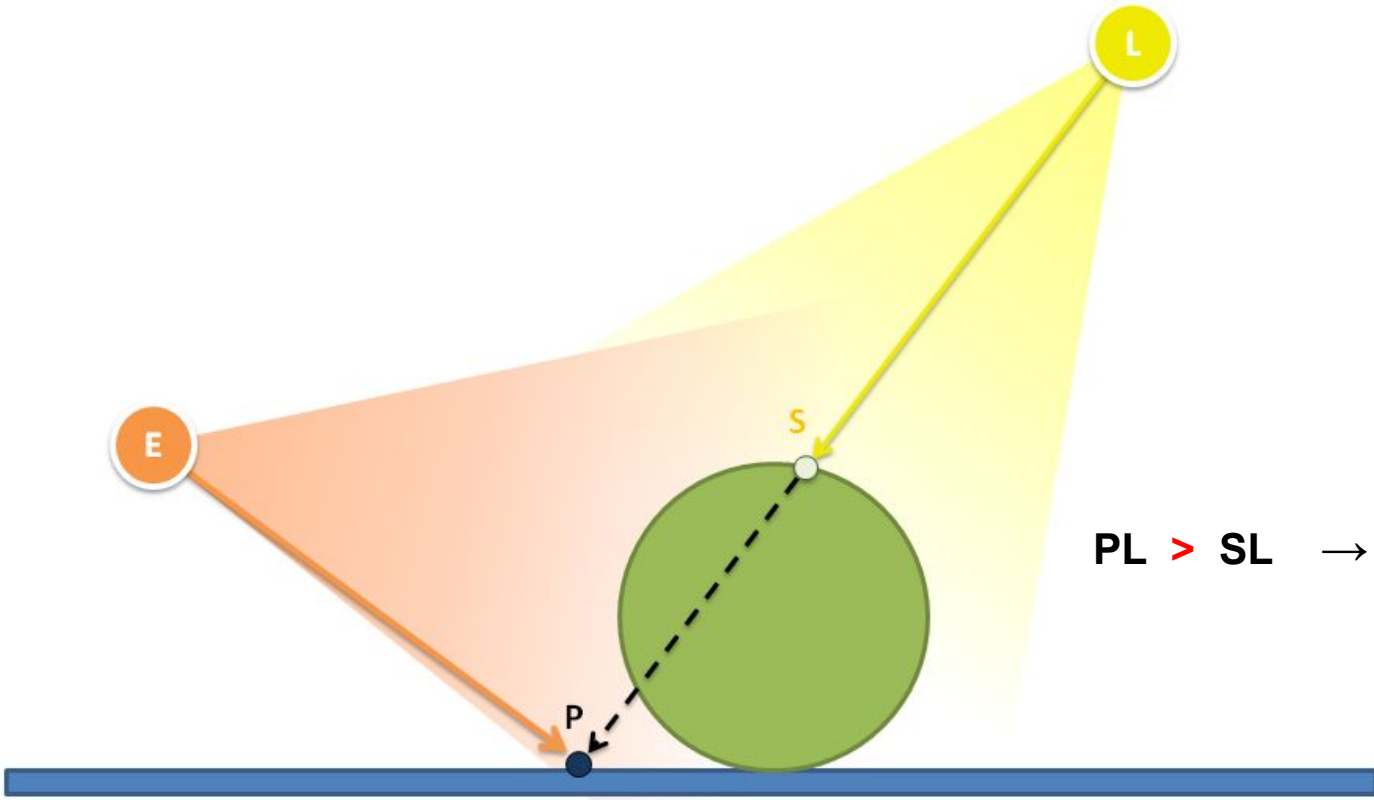


Source code in [06_shadow_mapping](#) folder!

Solution: Setup Light View Matrix

```
//TASK 1.1: setup camera to look at the scene from the light's perspective  
let lookAtMatrix = mat4.lookAt(mat4.create(), worldLightPos, worldLightLookAtPos, upVector);
```

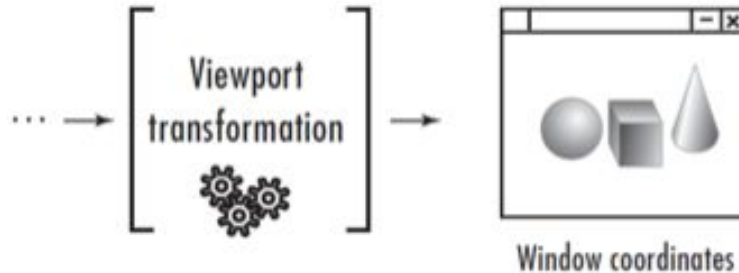
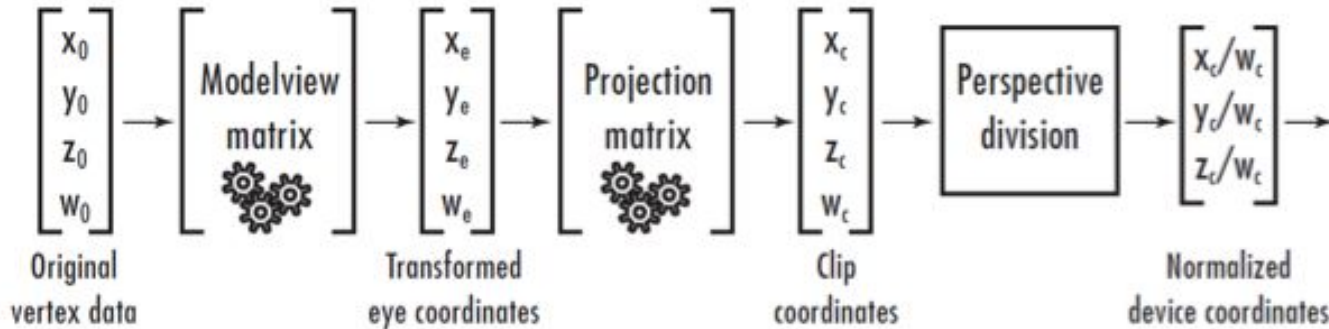

Render Scene from Camera Perspective



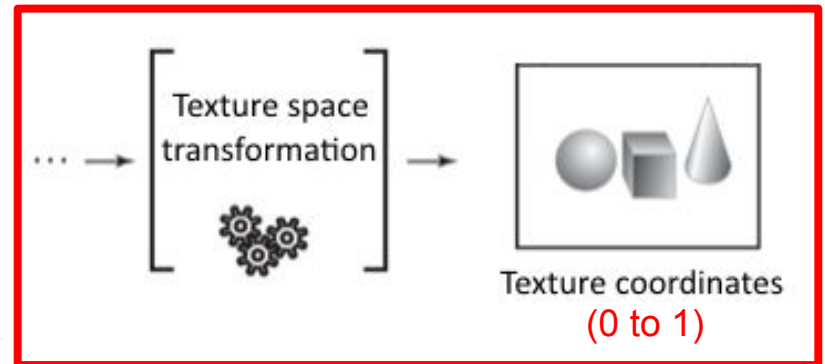
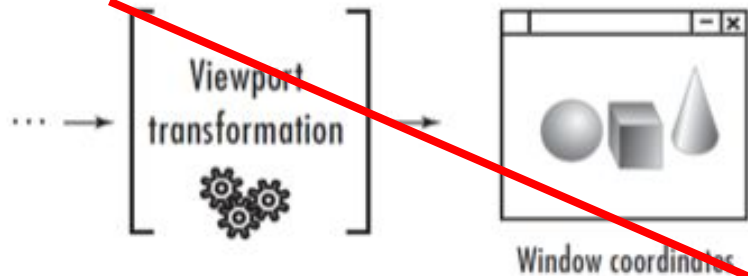
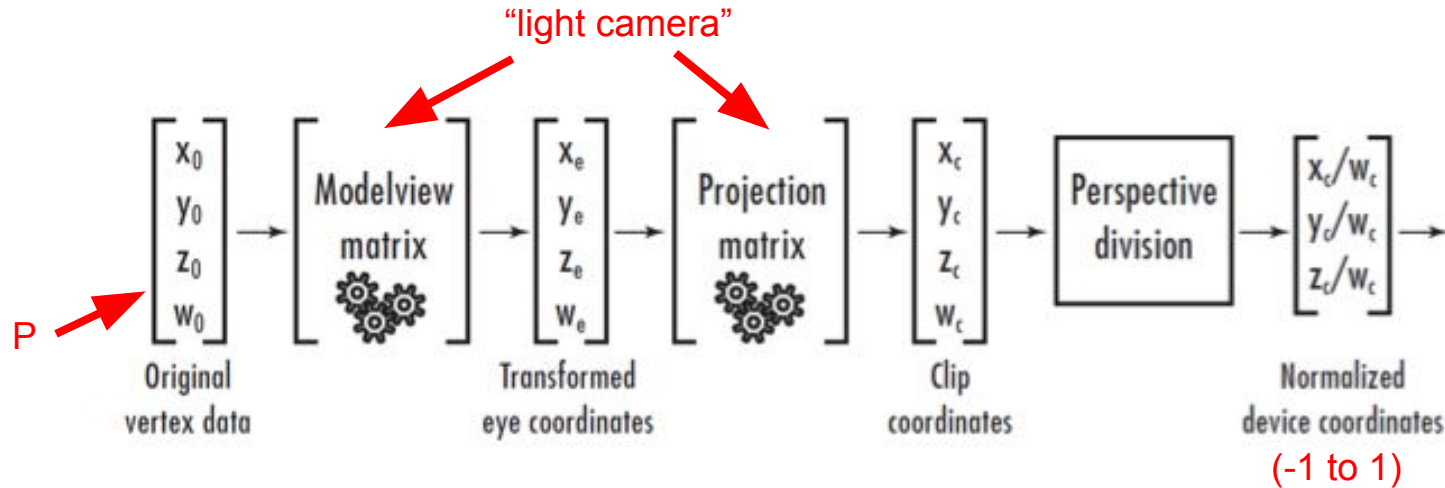
L = Light source
E = Eye / Camera
P = Rendered Point
S = Closest Point

PL > SL → Shadow

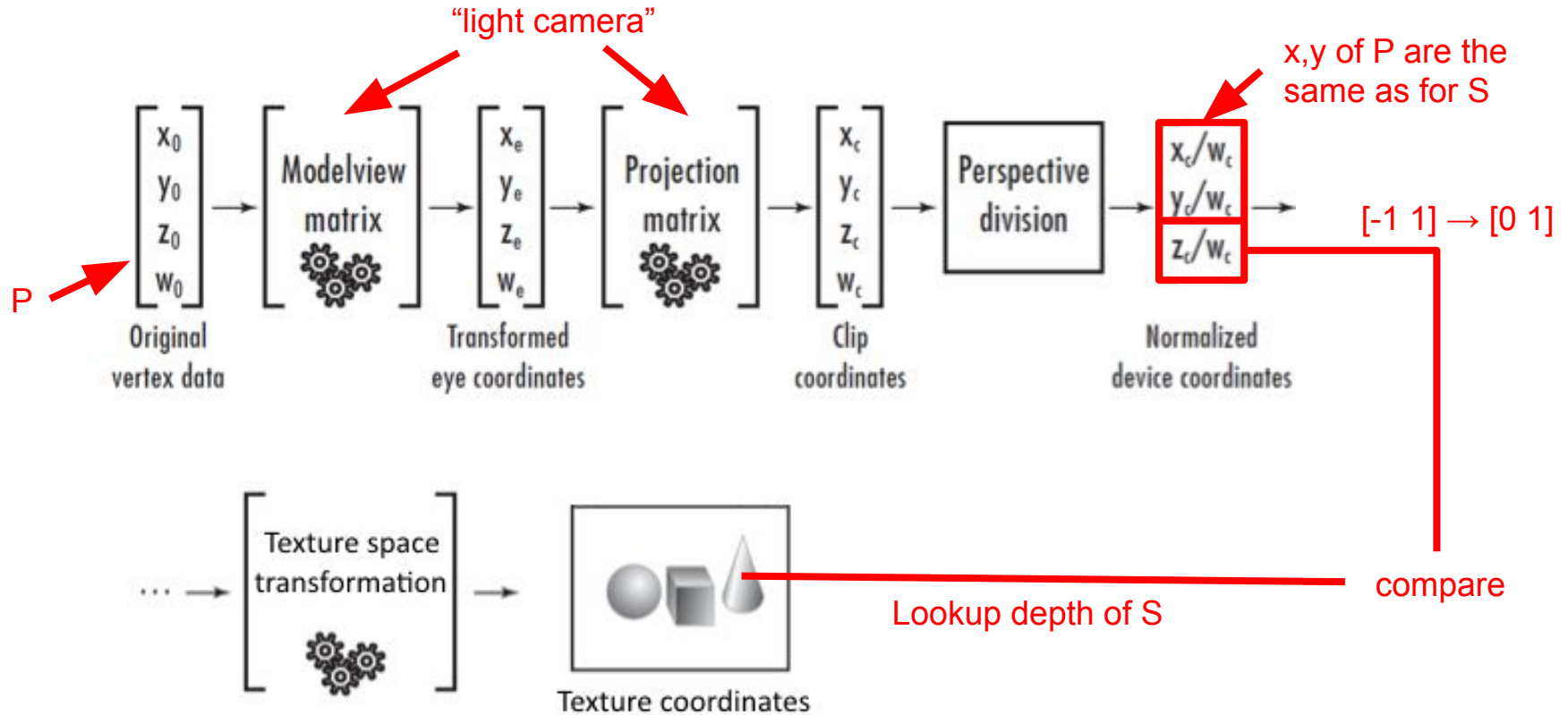
Recap: Transformation Pipeline



Depth Map Lookup For Each P

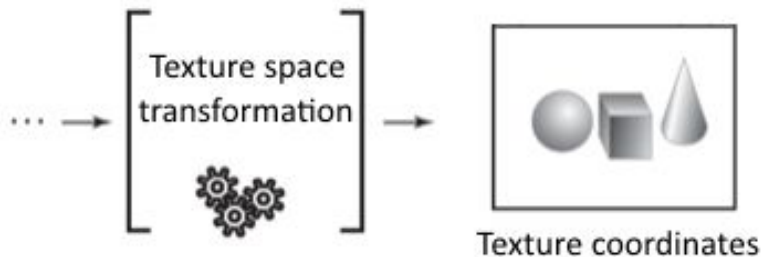
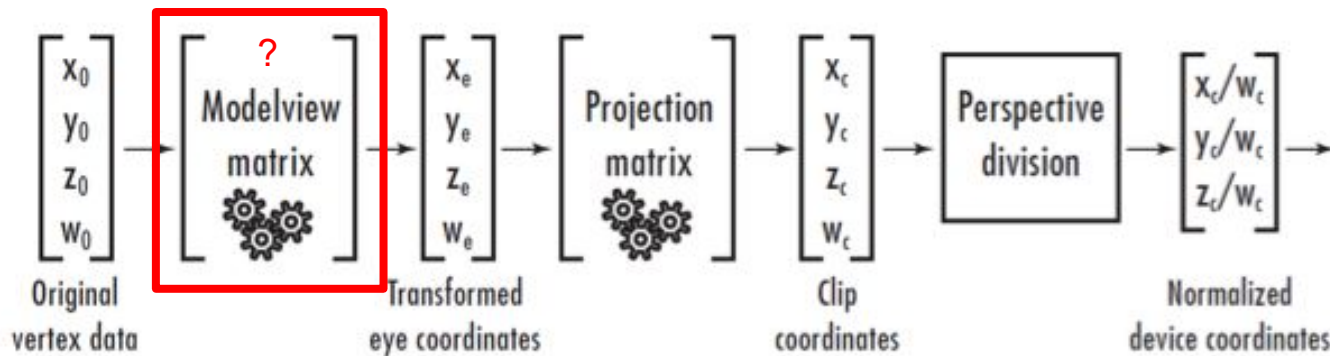


Depth Comparison

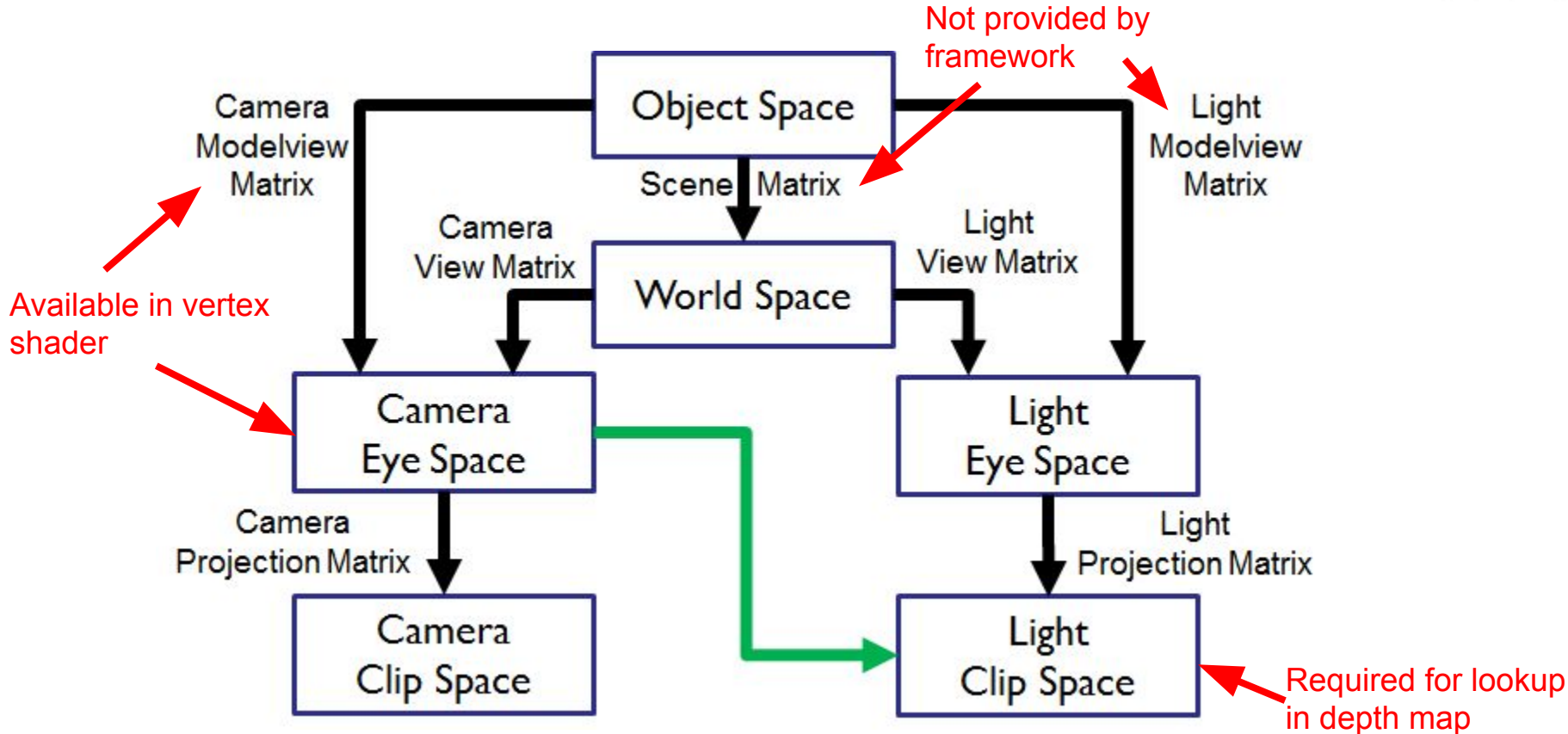


Render Scene from Camera Perspective

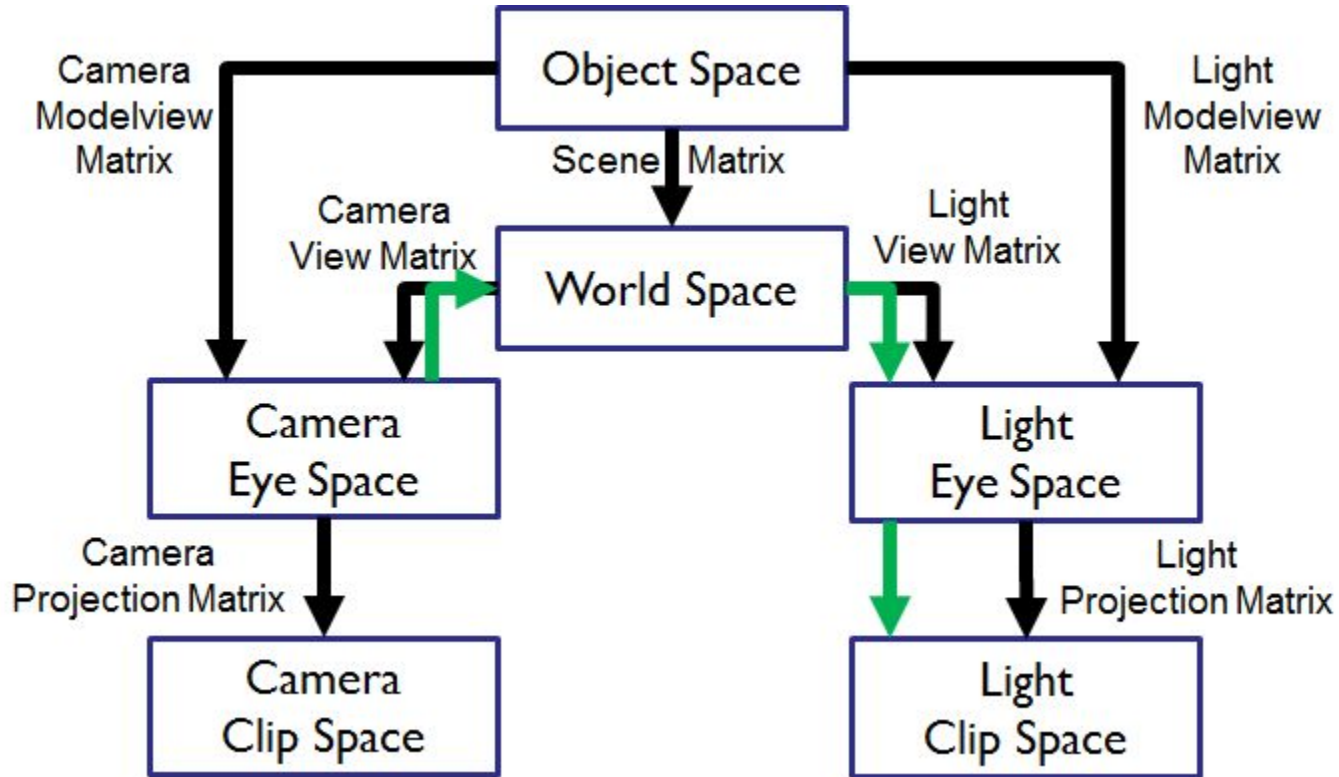
Unknown for “light camera” when rendering with “real camera” in our framework



Eye to Light Matrix



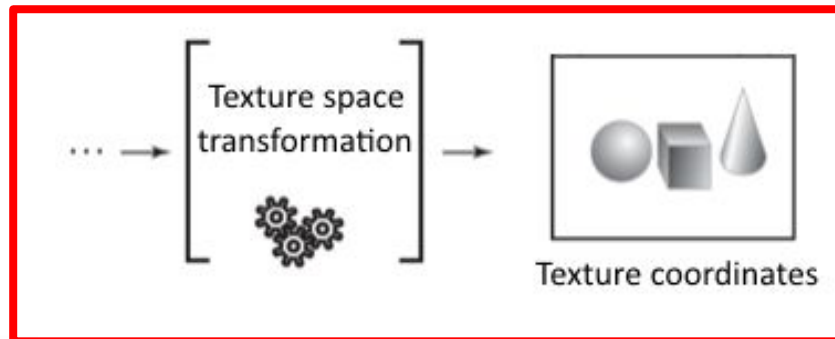
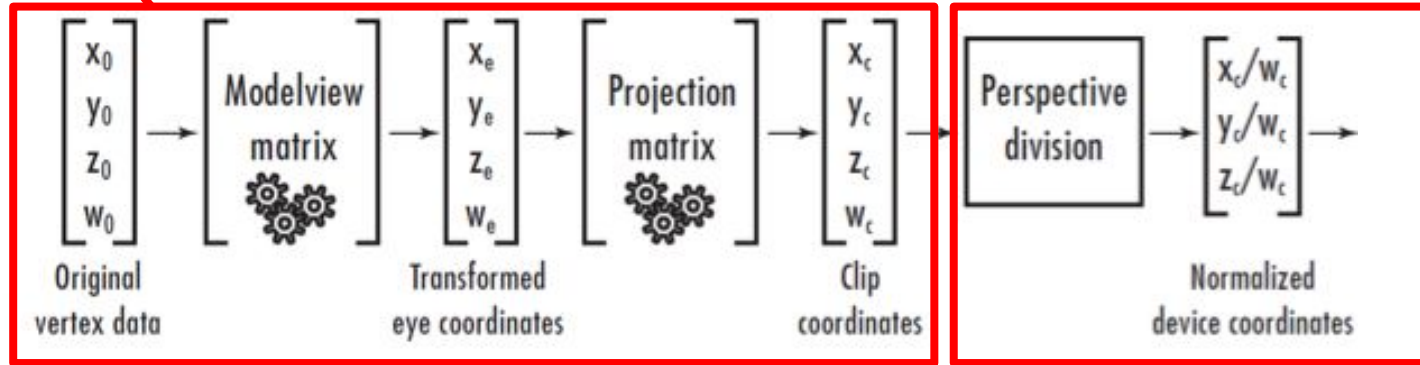
Eye to Light Matrix



Eye-to-light matrix is constant for all rendered models

Compute Texture Coordinates

Do in vertex shader (using eye-to-light matrix + model-view matrix of “real camera”)



Do in fragment shader
(otherwise wrong interpolation
because of perspective division)

Main Render Steps

Main render function:

1. Update light animation first!
2. Render scene from light's perspective into texture
 - generate shadow map
 - save light view and projection matrices (required for computing eye-to-light matrix)
3. Setup camera matrices
4. Compute inverted camera view matrix (required for computing eye-to-light matrix)
5. Render scene graph

ShadowSGNode:

1. Bind depth texture to a texture unit
2. Assign sampler in shader to depth texture unit
3. Compute eye-to-light matrix and pass to shader

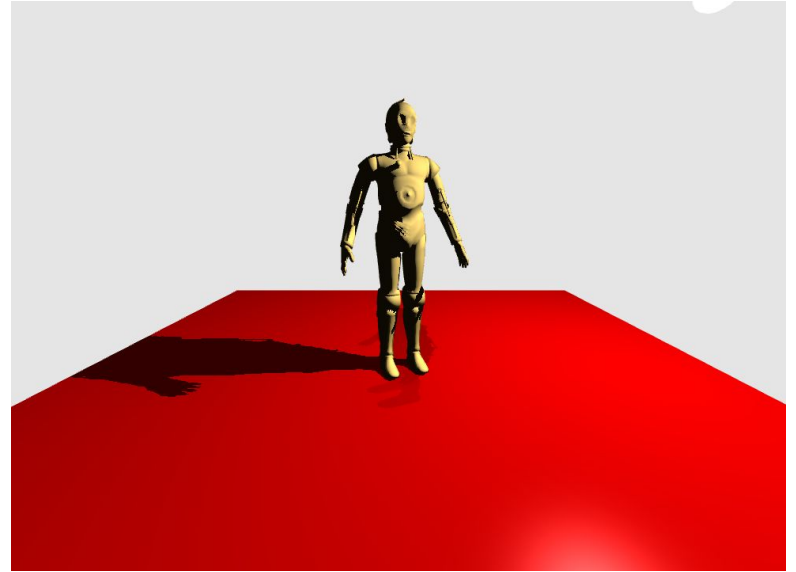
Task 2: Shadow Mapping

Goal:

C3PO should cast a shadow on the floor

Tasks:

- 2.1 Compute eye-to-light matrix in ShadowSGNode
- 2.2 Compute light clip space coordinates (in shadow.vs.glsl) using eye-to-light matrix
- 2.3 Apply perspective division to light clip space coordinates (in shadow.fs.glsl)
- 2.4 Lookup depth in texture and compute shadow coefficient
- 2.5 Apply shadow coefficient to diffuse and specular part of phong computation



Solution: Shadow Mapping

Task 2.1 - ShadowSGNode:

```
var eyeToLightMatrix = mat4.multiply(mat4.create(),this.lightViewProjectionMatrix,context.invViewMatrix);  
gl.uniformMatrix4fv(gl.getUniformLocation(context.shader, 'u_eyeToLightMatrix'), false, eyeToLightMatrix);
```

Task 2.2 - Vertex Shader (shadow.vs.glsl):

```
v_shadowMapTexCoord = u_eyeToLightMatrix*eyePosition;
```

Solution: Shadow Mapping

Task 2.3,2.4,2.5 - Fragment Shader (shadow.fs.glsl):

```

//TASK 2.3: apply perspective division to v_shadowMapTexCoord
vec3 shadowMapTexCoord3D = v_shadowMapTexCoord.xyz/v_shadowMapTexCoord.w; //do perspective division

//do texture space transformation (-1 to 1 -> 0 to 1)
shadowMapTexCoord3D = vec3(0.5,0.5,0.5) + shadowMapTexCoord3D*0.5;
//subtract small amount from z to get rid of self shadowing (EXTRA TASK: disable to see difference)
shadowMapTexCoord3D.z -= 0.003;

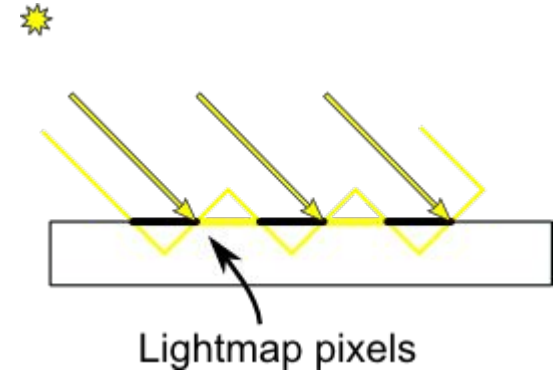
float shadowCoeff = 1.0; //set to 1 if no shadow!
//TASK 2.4: Look up depth in u_depthMap and set shadow coefficient (shadowCoeff) to 0 based on depth comparison
float zShadowMap = texture2D(u_depthMap, shadowMapTexCoord3D.xy).r;
if(shadowMapTexCoord3D.z > zShadowMap)
    shadowCoeff = 0.0;

//TASK 2.5: apply shadow coefficient to diffuse and specular part
return c_amb + shadowCoeff * (c_diff + c_spec) + c_em;

```

Self Shadowing

Try to disable subtraction of self shadowing bias in shader



<http://www.opengl-tutorial.org/intermediate-tutorials/tutorial-16-shadow-mapping/>

EXTRA TASK: Smooth Shadows

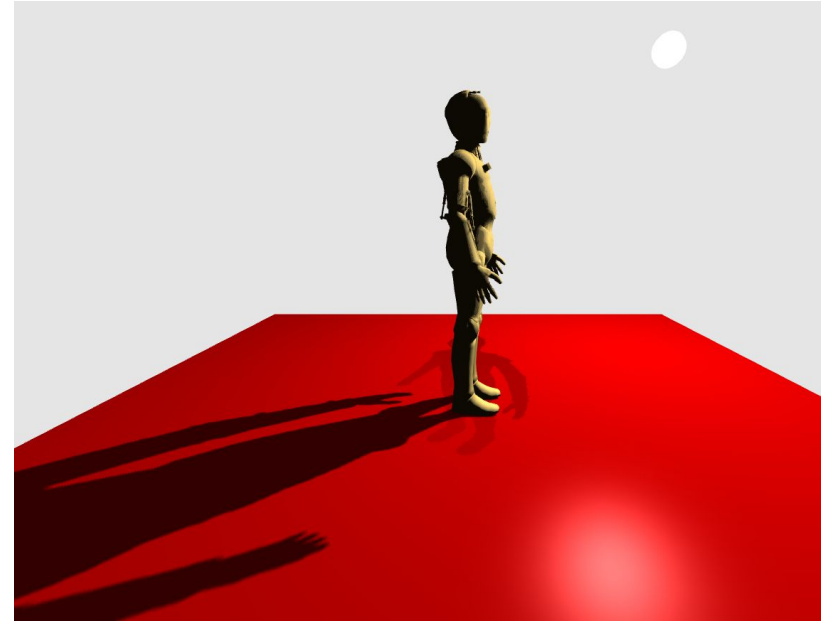
Goal:

Smooth shadow by sampling and averaging shadow coefficient over a 3x3 neighborhood in depth texture.

Hints:

You can use “for loops” in a shader!
(E.g. loop x,y offsets from -1 to 1)

Texture coordinates are normalized
(0 to 1) → Use texture size
(u_shadowMapWidth, ...) to
compute 1 step in x,y direction.

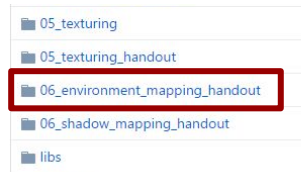


Solution: Smooth Shadows

```
//EXTRA TASK: Improve shadow quality by sampling multiple shadow coefficients (a.k.a. PCF)
float avgShadowCoeff = 0.0;
for(float dx=-1.0; dx <= 1.0; dx++)
{
    for(float dy=-1.0; dy <= 1.0; dy++)
    {
        float subShadowCoeff = 1.0; //set to 1 if no shadow!
        float zShadowMap = texture2D(u_depthMap, shadowMapTexCoord3D.xy+vec2(dx/u_shadowMapWidth,dy/u_shadowMapHeight)).r;
        if(shadowMapTexCoord3D.z > zShadowMap)
            subShadowCoeff = 0.0;

        avgShadowCoeff += subShadowCoeff;
    }
}
shadowCoeff = avgShadowCoeff/9.0;
```

Environment Mapping



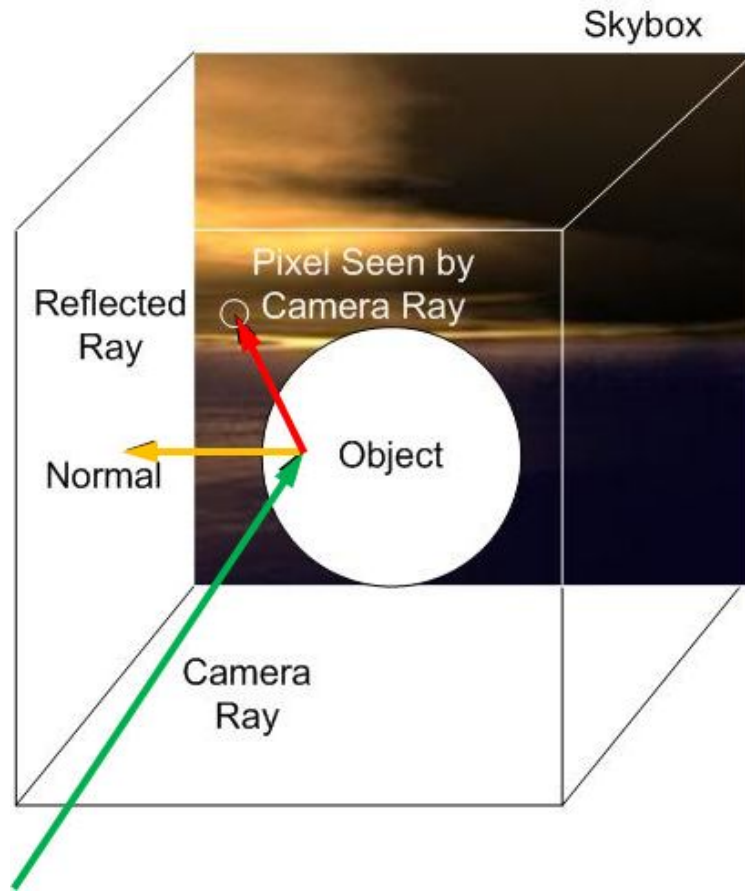
Environment Mapping

Cube Mapping

OpenGL supports cube maps

Lookup with 3D texture coordinates

We will set up a cube map containing six images forming an environment



Scene Description

First a space ship is rendered

Use **reflected** camera ray for lookup → mirror like surface

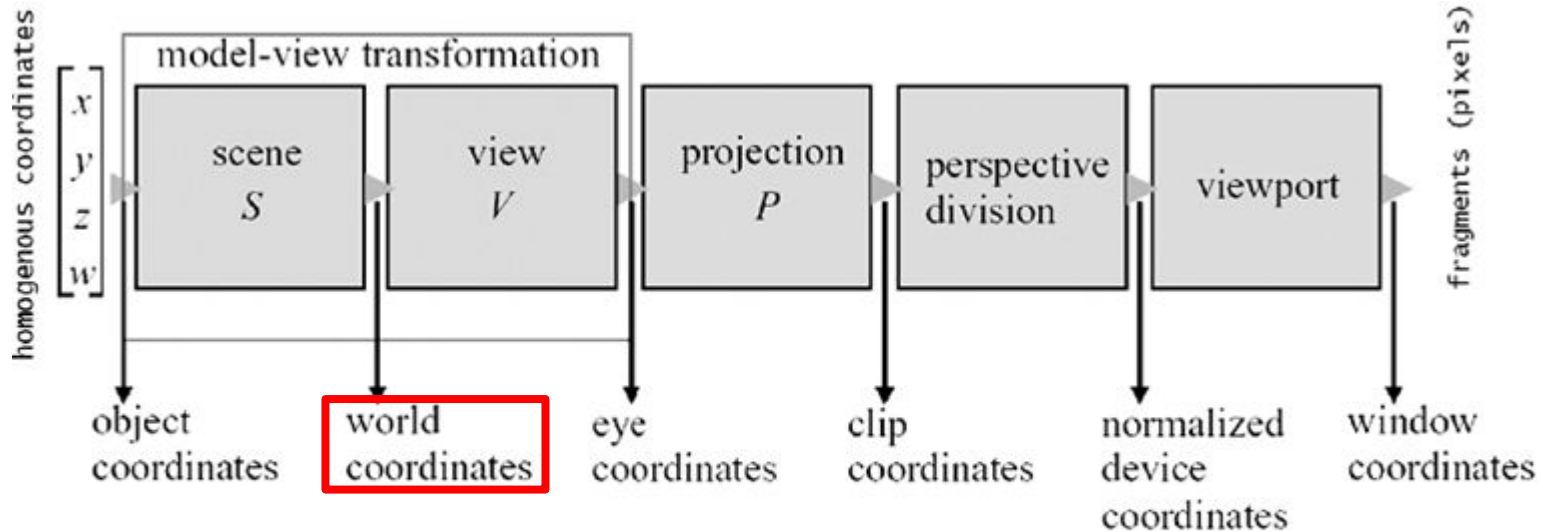
Second a sphere is rendered around the viewer

Use **non-reflected** camera ray for lookup to directly display the environment (i.e. the stars)



Reminder: Coordinates Systems

The environment map represents the world around us
For our space scenario it defines the stars



Cube Map Texture Coordinates

We need the (reflected) camera ray for lookups in the cube map

in **eye space** of our camera (model-view transformation):

camera ray direction = vertex position

The environment map represents our world:

→ we have to transform camera ray direction from eye space to world space

use **inverse view matrix** to get from eye space to world space coordinates

```
invViewMatrix = mat4.invert(mat4.create(), context.viewMatrix);
```

since we deal with direction vectors, 3x3 matrix is sufficient (translation is ignored)

```
let invView3x3 = mat3.fromMat4(mat3.create(), context.invViewMatrix);
```

Difference to 2D texture

Texture coordinates are **3D**

Sampler in shader has type **samplerCube**

Texture lookup in shader is done with **textureCube(...)**

Texture target (texture type) is **gl.TEXTURE_CUBE_MAP** instead of **gl.TEXTURE_2D**

Texture is initialized with **6 images** (one for each side of the cube)

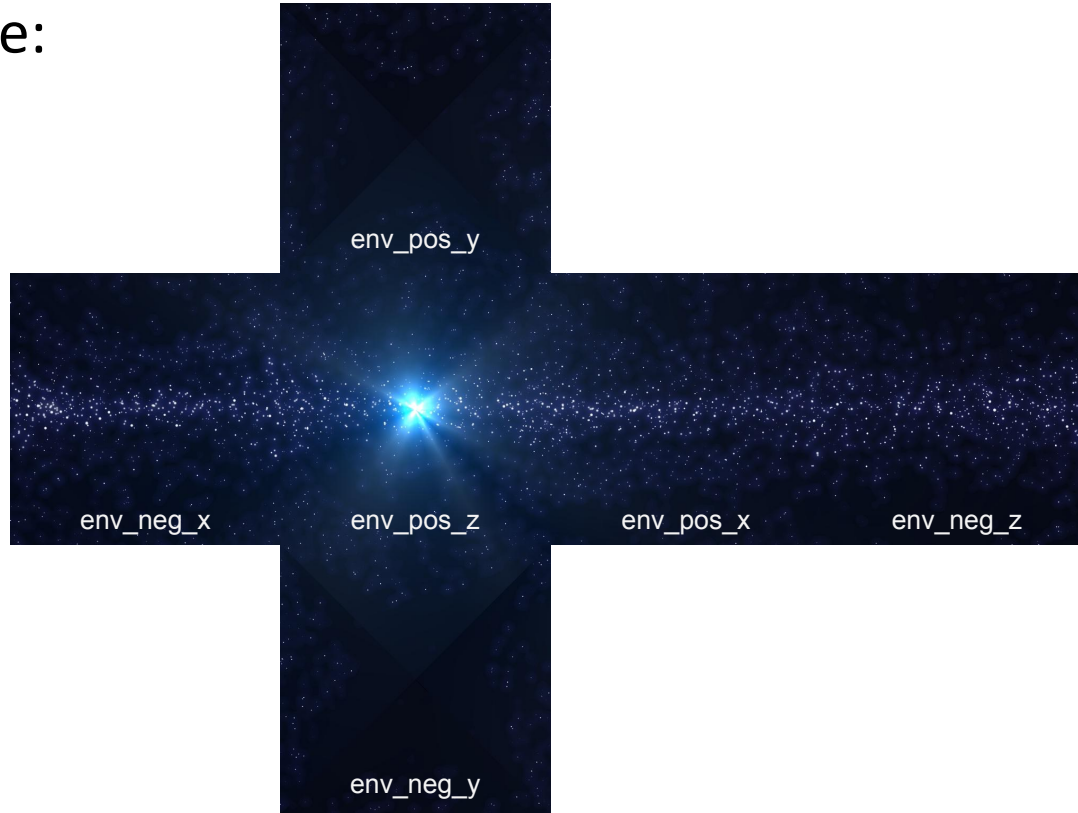
Cube Map Texture Initialization

Upload an image for each side of the cube:

```
function initCubeMap(resources) {
    //create the texture
    envcubetexture = gl.createTexture();
    //define some texture unit we want to work on
    gl.activeTexture(gl.TEXTURE0);
    //bind the texture to the texture unit
    gl.bindTexture(gl.TEXTURE_CUBE_MAP, envcubetexture);
    //set sampling parameters
    gl.texParameteri(gl.TEXTURE_CUBE_MAP, gl.TEXTURE_WRAP_S, gl.MIRRORED_REPEAT);
    gl.texParameteri(gl.TEXTURE_CUBE_MAP, gl.TEXTURE_WRAP_T, gl.MIRRORED_REPEAT);
    //gl.texParameteri(gl.TEXTURE_CUBE_MAP, gl.TEXTURE_WRAP_R, gl.MIRRORED_REPEAT); //will be available in WebGL 2
    gl.texParameteri(gl.TEXTURE_CUBE_MAP, gl.TEXTURE_MIN_FILTER, gl.LINEAR);
    gl.texParameteri(gl.TEXTURE_CUBE_MAP, gl.TEXTURE_MAG_FILTER, gl.LINEAR);
    //set correct image for each side of the cube map
    gl.pixelStorei(gl.UNPACK_FLIP_Y_WEBGL, true); //flipping required for our skybox, otherwise images don't fit together
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_POSITIVE_X, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_pos_x);
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_NEGATIVE_X, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_neg_x);
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_POSITIVE_Y, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_pos_y);
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_NEGATIVE_Y, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_neg_y);
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_POSITIVE_Z, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_pos_z);
    gl.texImage2D(gl.TEXTURE_CUBE_MAP_NEGATIVE_Z, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, resources.env_neg_z);
    //unbind the texture again
    gl.bindTexture(gl.TEXTURE_CUBE_MAP, null);
}
```

Cube Map Texture

Texture we'll use:



Task 3: Cube Mapping

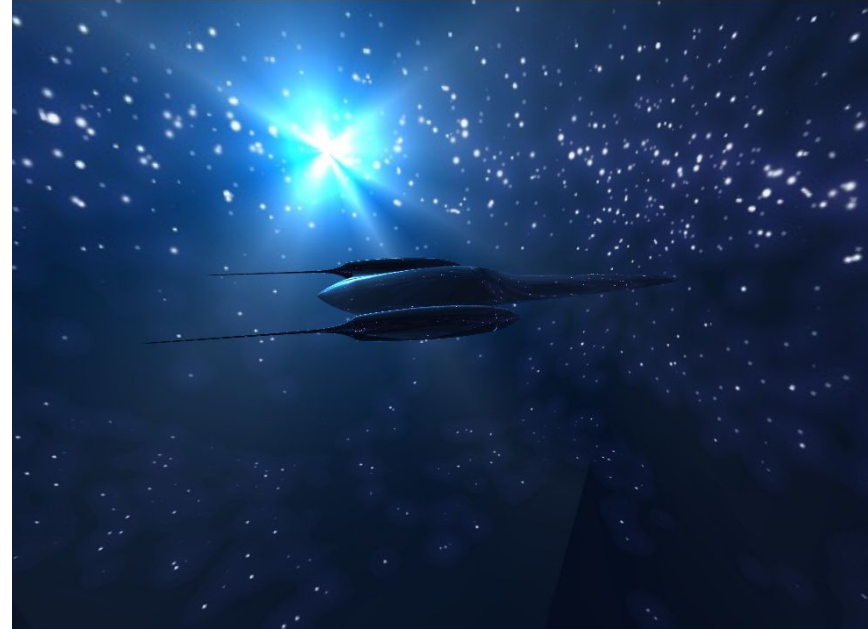
Goal:

Show stars and their reflection on spaceship.

Tasks:

- 3.1 Compute camera ray in vertex shader
- 3.2 Reflect camera ray in fragment shader
- 3.3 Do texture lookup in cube map

Source code now in [06_environment_mapping](#) folder!



Solution: Cube Mapping

Task 3.1 - Vertex Shader:

```
v_cameraRayVec = u_invView * eyePosition.xyz;
```

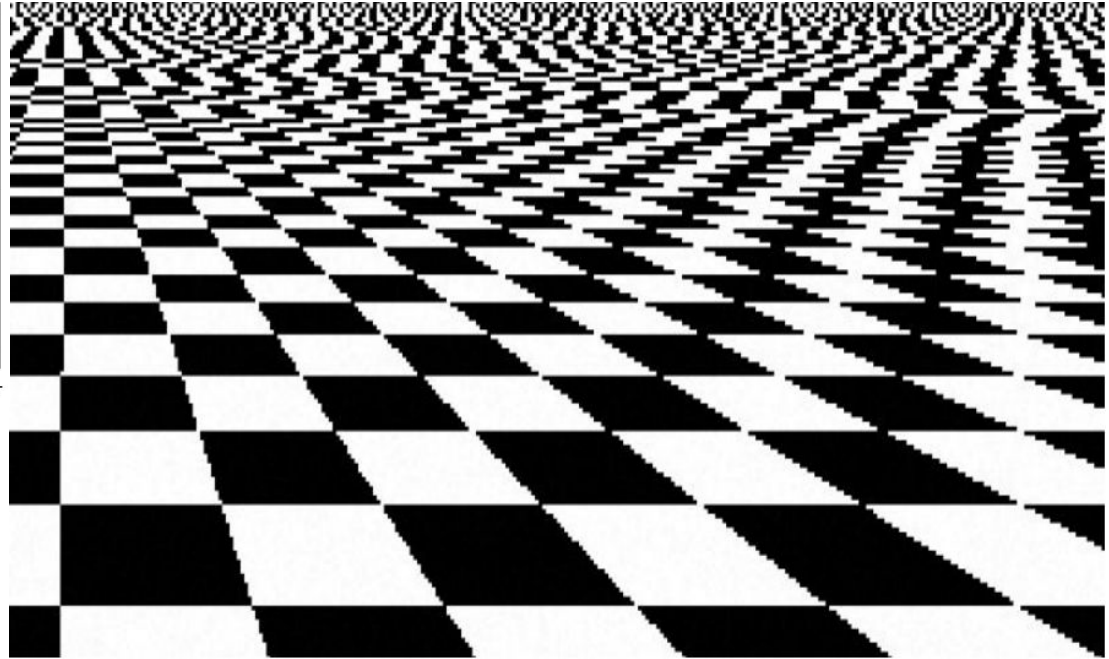
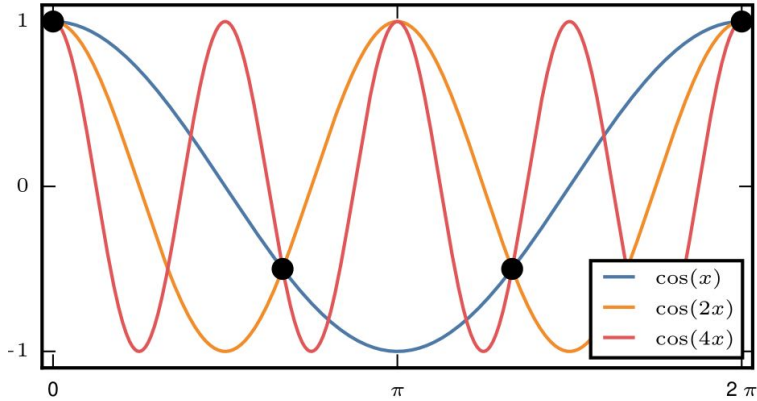
Task 3.2,3.3 - Fragment Shader:

```
vec3 texCoords;  
if(u_useReflection)  
    //TASK 3.2: compute reflected camera ray  
    texCoords = reflect(cameraRayVec, normalVec);  
    //texCoords = vec3();  
else  
    texCoords = cameraRayVec;  
  
//TASK 3.3: do texture lookup in cube map using the textureCube function  
gl_FragColor = textureCube(u_texCube, texCoords);
```

Texture Filtering



Aliasing



use texture filtering to
reduce aliasing

Demo: https://jku-icg.github.io/cg_demo/00_texturing/

Mipmapping

Low Resolution Versions of Texture

Mipmapping chooses the best texture size depending on the distance the texture is viewed from

Press “m” to enable mipmapping in our example
Avoids flickering stars, but adds blur to reflections

Generate Mipmaps:

```
gl.generateMipmap(gl.TEXTURE_CUBE_MAP);
```

 during texture definition (built by iterative downsampling)

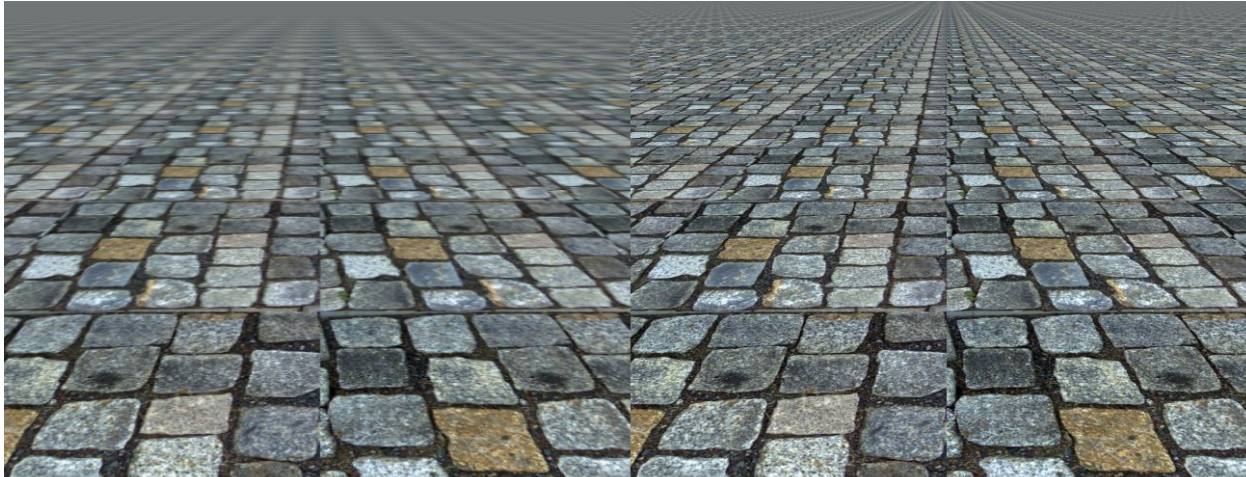
Enable Mipmaps:

```
set gl.TEXTURE_MIN_FILTER parameter to  
gl.LINEAR_MIPMAP_LINEAR
```



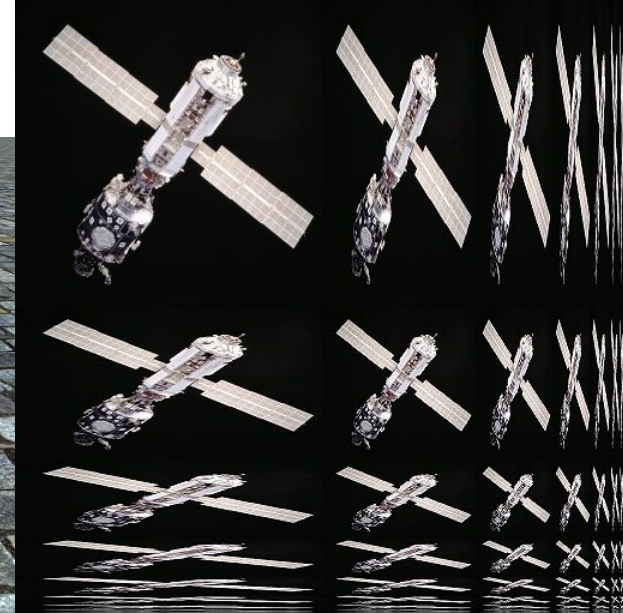
Anisotropic Filtering

Improves texture filter quality for oblique viewing angles by non-isotropic filtering:



mipmapping

mipmapping + AF



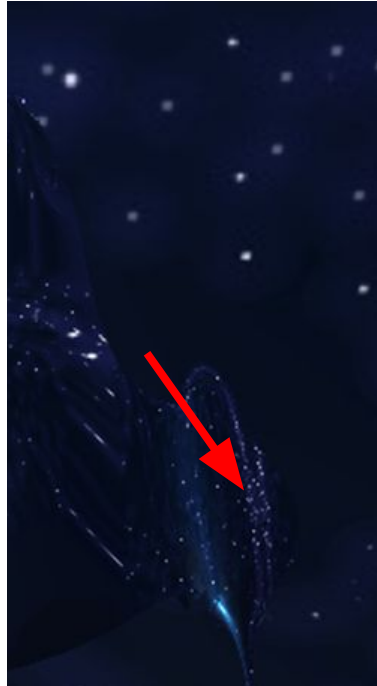
Anisotropic Filtering

Improves texture filter
quality for oblique
viewing angles

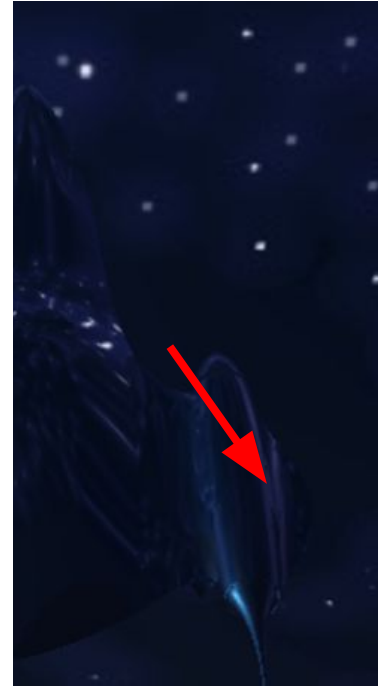
press “i”-key

This restores some
details of the reflections
but still avoids aliasing
effects.

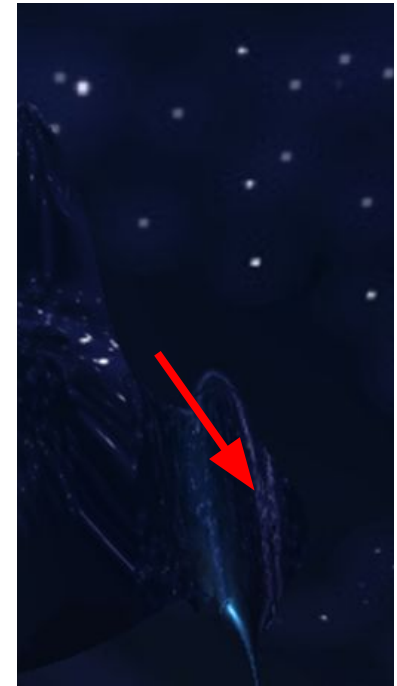
no mipmapping



mipmapping



mipmapping + AF



Recap

Shadow Mapping

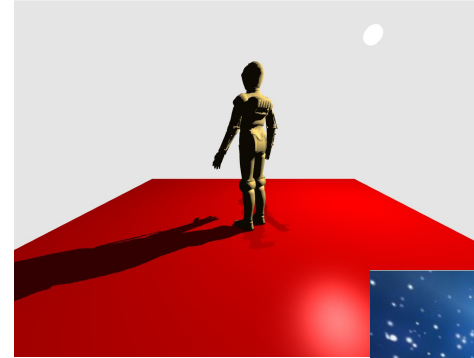
Overview

Recap: Render to Texture

Depth Comparison

Eye-to-Light Matrix

Smooth Shadows



Environment Mapping

Cube Mapping

Differences to 2D Textures

Texture Filtering

Mipmapping, Anisotropic Filtering

CG Project: Multiple Shaders in Scene

Remember:

Uniforms set for one ShaderSGNode are not transferred to another ShaderSGNode!

E.g. LightSGNode only affects one ShaderSGNode!

Important:

Make sure ShaderSGNode is added to scene graph before nodes which set any uniform parameters of the shader

E.g. LightSGNode should be child of ShaderSGNode!

Make sure to set all required uniform parameters before adding first RenderSGNode

Workaround for duplicate light specification:

MaterialSGNode allows to add light sources to .lights variable

Instead of adding lights + transformations again to other ShaderSGNode do:

- Add LightSGNode + light transformations to first ShaderSGNode
- Add **same** LightSGNode to **first** material in **second** ShaderSGNode (sets again light uniform params)

Thanks!

Have fun with your CG-Projects.

Questions / Feedback: cg-lab@jku.at

Final Submission Deadline:

22.06.2021