

Computer Graphics

Lab 3: Scene Graphs

Lab Schedule

Lab 1	Introduction to WebGL	Week from March 8
Lab 2	Transformations and Projections	Week from March 15
Lab 3	Scene Graphs	Week from March 22
Lab 4	Illumination and Shading	Week from April 12
Lab 5	Texturing	Week from April 19
Lab 6	Advanced Texture Mapping	Week from April 26
Lab 7a	Project Q&A	1.6. 15:30-17:00, 11.6. 08:30-10:00
Lab 7b	Introduction to CUDA	11.6. 10:00-11:30 & 12:15-13:45

CG Lab Project: Create a Movie

Group project in teams of 2 students

Mandatory Submissions via Github:

26.03.2021 23:59: Movie concept submission (incl. team announcement)

23.04.2021 23:59: Intermediate submission

22.06.2021 23:59: Hand-in final package

Individual interviews (alone): **24.-30.06.2021**

Dev Environment: Lab Package

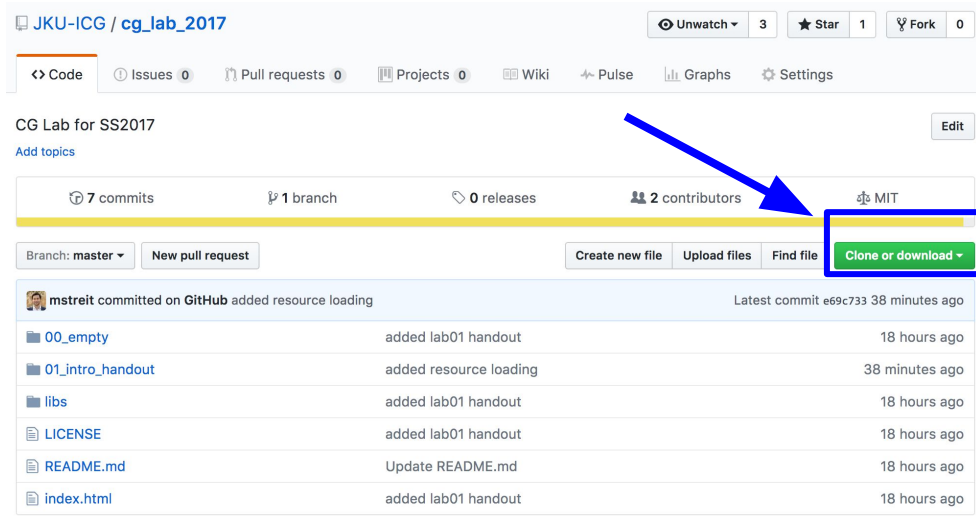
Fork me on GitHub

Hosted on GitHub: https://github.com/jku-icg/cg_lab_2021

The repository will be updated during the lab with the new projects.

To get started (**now**):

1. Download the ZIP
2. Extract the folder
3. Open Visual Studio Code
4. Open `cg_lab_2021` folder
(*File* → *Open*)
5. Click on **Go Live** button in lower right corner



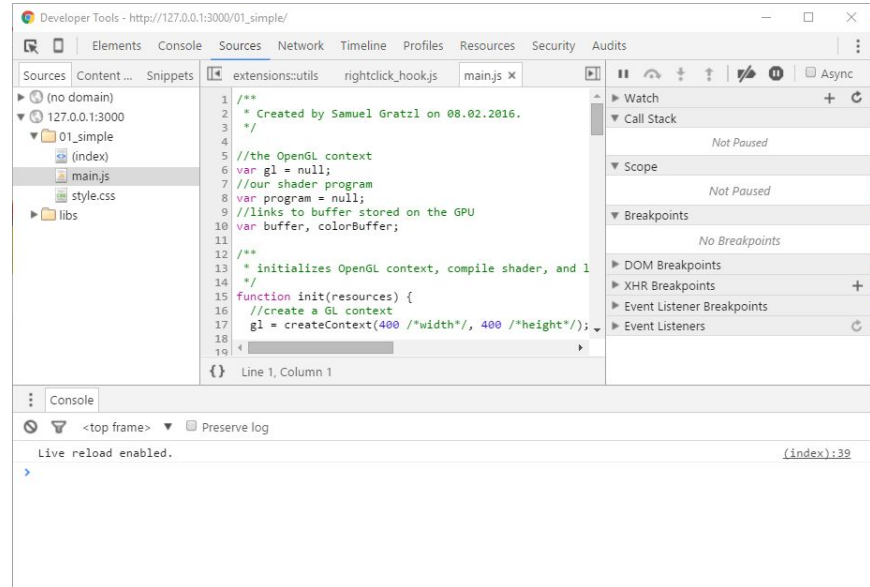
The screenshot shows the GitHub interface for the repository 'JKU-ICG / cg_lab_2021'. At the top right, there are buttons for 'Unwatch', 'Star' (3), and 'Fork' (0). Below these are navigation tabs for 'Code', 'Issues' (0), 'Pull requests' (0), 'Projects' (0), 'Wiki', 'Pulse', 'Graphs', and 'Settings'. The repository name 'CG Lab for SS2017' is displayed, along with 'Add topics' and an 'Edit' button. A yellow bar highlights the repository statistics: '7 commits', '1 branch', '0 releases', '2 contributors', and 'MIT' license. Below this bar are buttons for 'Branch: master', 'New pull request', 'Create new file', 'Upload files', 'Find file', and a green 'Clone or download' button with a dropdown arrow. A blue arrow points to this button. The commit history is shown below, with the latest commit by 'mstreit' on 'cg_lab_2021' containing files like '00_empty', '01_intro_handout', 'libs', 'LICENSE', 'README.md', and 'index.html'.

Dev Environment: Developer Tools

Know the Web Developer Tools of your favorite browser

Chrome, Firefox, Edge, Safara, ... → usually F12

Great for debugging JavaScript code, manipulating CSS & DOM, ...



Recap

Transformation pipeline

Model-view transformations

Translate, scale, rotate

Creating geometry using the index buffer

Projective transformations

Orthographic and perspective projection

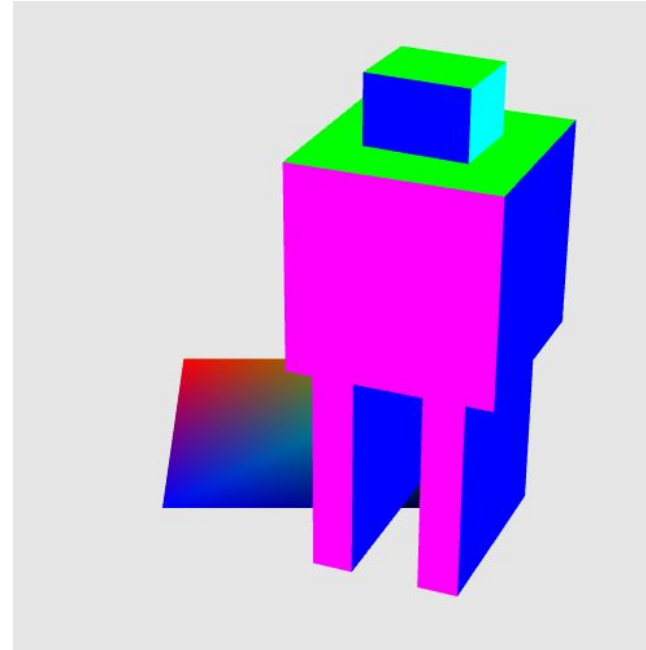
Camera transformations

Animations

Solution on GitHub:

 [02_transformations](#)

 [02_transformations_handout](#)



glmMatrix Helper Library

Library for vector and matrix manipulation: <http://glmatrix.net/>

Library supports:

Identity matrix, multiplication, inverse, clone, translation, rotation, scale, lookAt, orthographic & perspective projection, etc.

Already part of framework: `libs/glmatrix.js`

Documentation: <http://glmatrix.net/docs/>

Use it from now on!

glmMatrix Usage

Classes `vec2`, `vec3`, `vec4`, `mat2`, `mat3`, `mat4`, etc.

```
var identity = mat4.create();  
var out = mat4.scale(mat4.create(), identity, [x, y, z]);
```

For convenience in our framework:

```
var out = glm.scale(x, y, z)
```

```
{mat4} mat4.scale(out, a, v)
```

Scales the `mat4` by the dimensions in the given `vec3`

Parameters:

`{mat4} out`

the receiving matrix

`{mat4} a`

the matrix to scale

`{vec3} v`

the `vec3` to scale the matrix by

Returns:

`{mat4} out`

Recap: Structure of a WebGL Program

At initialization time `init()`

- Create all shaders and programs

- Create buffers and upload vertex data

At render time `render()`

- Set global states (enable depth testing, etc.)

- For each object you want to draw

 - Call `gl.useProgram` for the program needed to draw

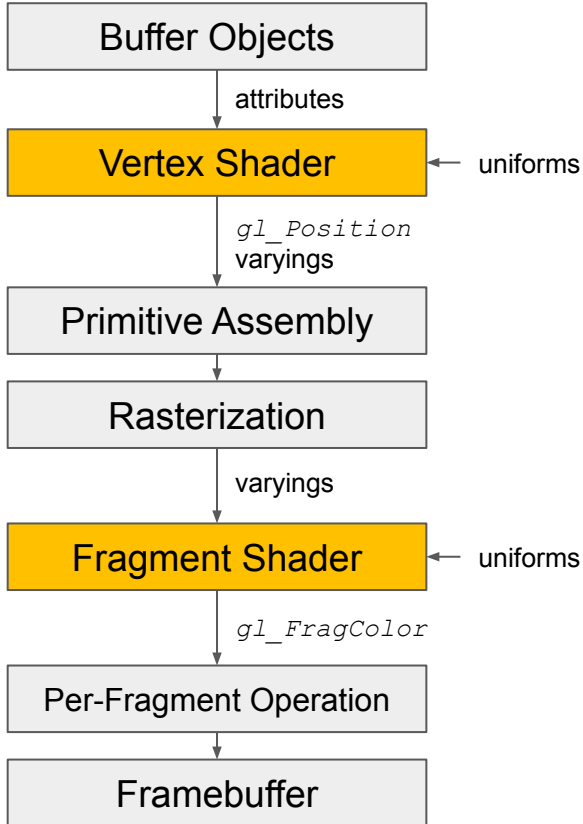
 - Setup attributes for the object you want to draw

 - For each attribute call `gl.bindBuffer`, `gl.vertexAttribPointer`,
`gl.enableVertexAttribArray`

 - Setup uniforms for the object you want to draw by calling `gl.uniformXXX`

 - Call `gl.drawArrays` or `gl.drawElements`

Recap: Programmable Pipeline



Summary

vertex: point in 2D/3D space

fragment: pixel + additional properties

shader: tiny program on the GPU

shader program: vertex + fragment shader

buffer: array on GPU

attribute: accessing the current buffer element in shader

uniform: parameter from program to shader

varying: parameter between shader

gl_Position, gl_FragColor: magic variables

rasterization: 3 vertices → N fragments

Computer Graphics

Lab 3: Per-Fragment Operations

Agenda for This Week

Per-Fragment Operations

Depth Handling

Blending

Tutorial (coding)

Scene Graphs

Abstraction into Nodes

Scene graph traversal

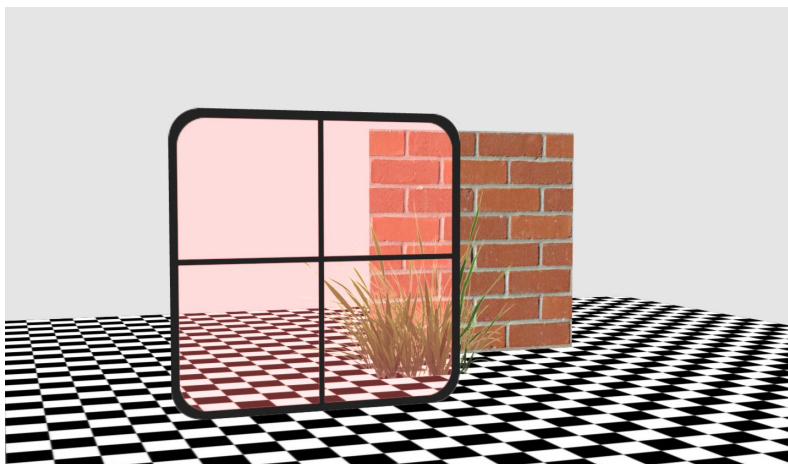
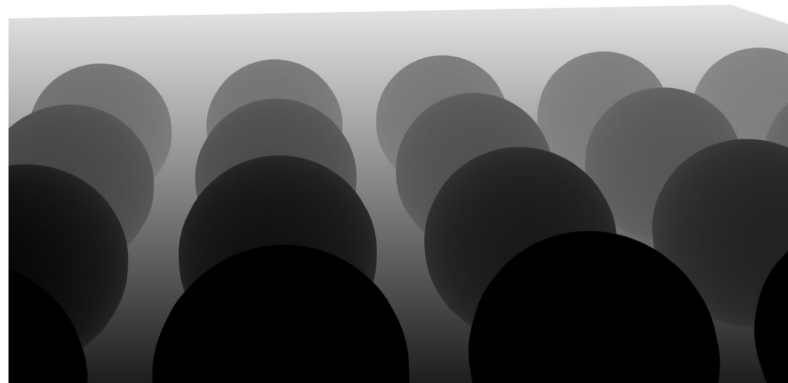
Base node class

Render nodes

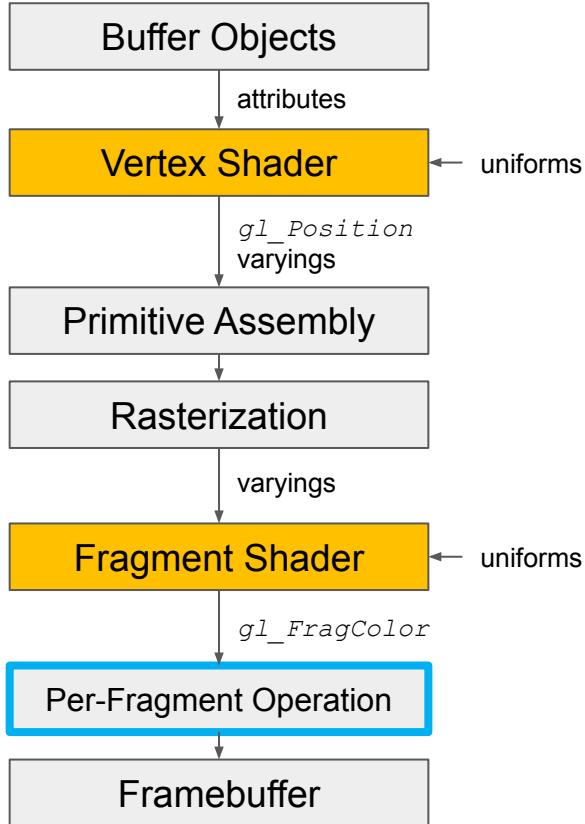
Transformation nodes

Implement robot using a scene graph

Tutorial (coding)



Programmable Pipeline

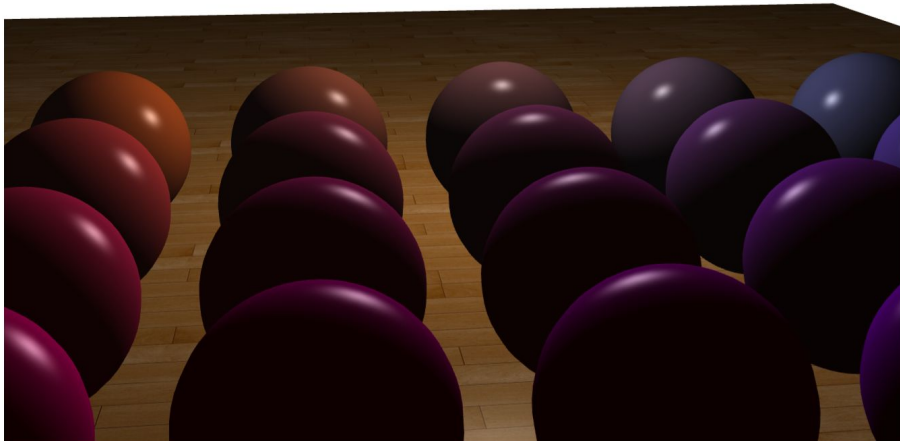


Per-Fragment Operation

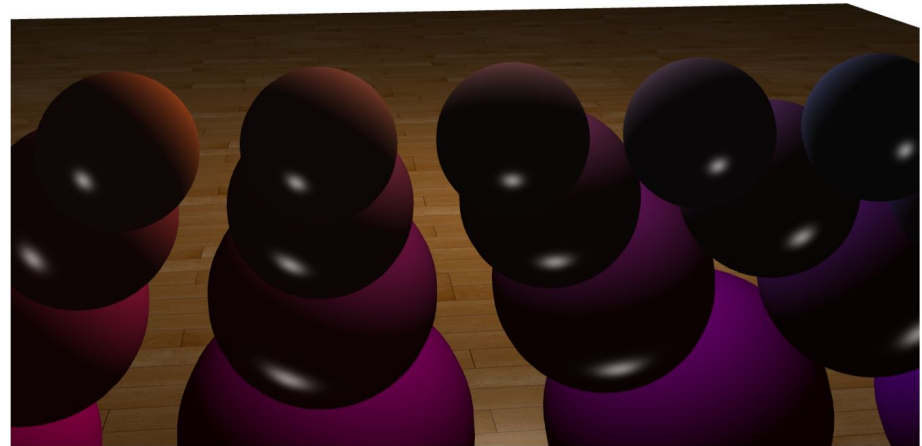
- additional tests/operations per fragment
- decides if (and how) fragments are written into the framebuffer
- examples:
 - **depth test**
the closer fragment should be drawn
 - **blending**
in case of semi transparent fragments
 - ...

Depth Handling

Allows OpenGL to decide which object is in front
Depth testing has to be enabled to tell OpenGL to perform a depth test and use the depth buffer.



Depth testing enabled



Depth testing disabled

Depth Buffer (Z-Buffer)

Contains normalized depth values (0-1) for all fragments

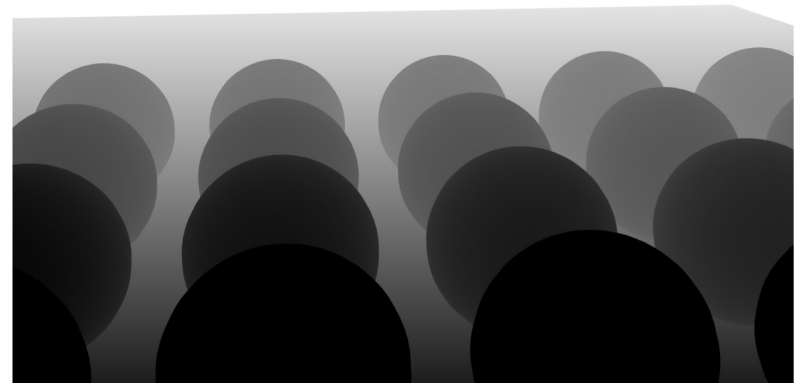
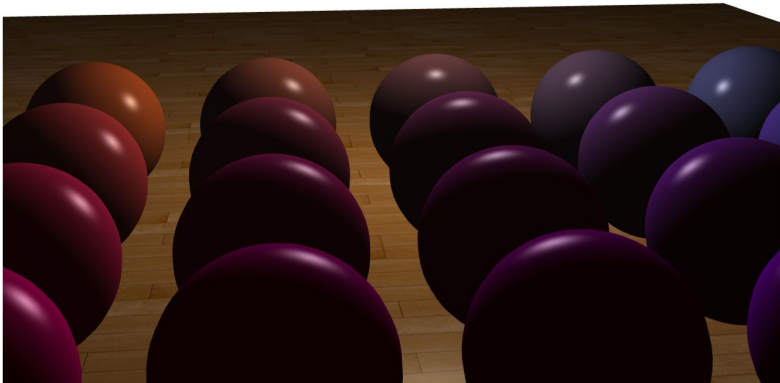
OpenGL tests depth value of a fragment against the content of the depth buffer

If test passes, the depth buffer is updated with the new depth value.

If depth test fails, the fragment is discarded.

Depth test functions (various options)

default: `gl.depthFunc (gl.LESS) ;` (the smaller value wins)



Demo: https://jku-icg.github.io/cg_demo/00_zbuffer/

Z-Fighting

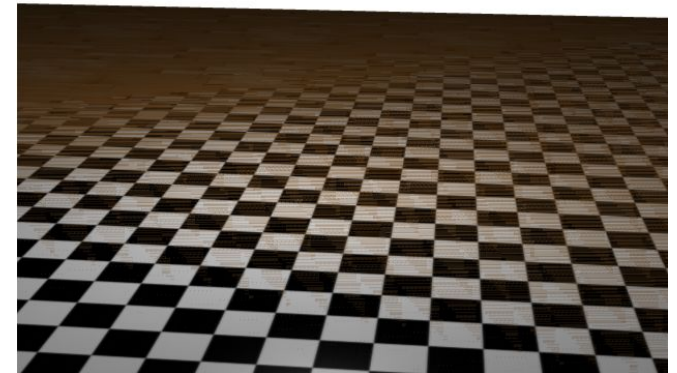
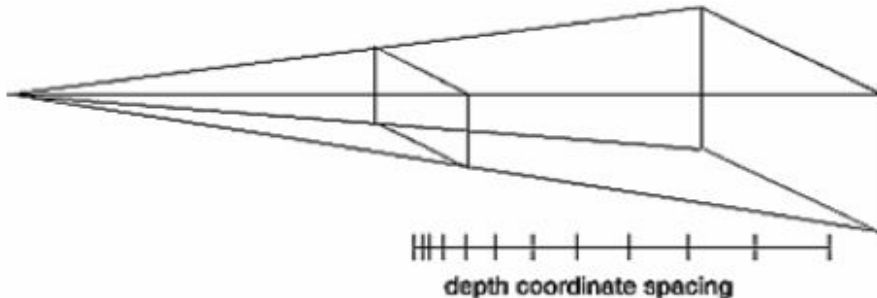
OpenGL can't decide which face is in front

Happens when primitives are too close together

We can force it to happen

By changing the near and far clipping planes' values of the projection

The closer to the near clipping plane, the denser the values get and therefore the further away, the coarser.



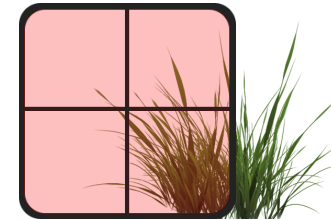
Blending: Alpha Values

The alpha value defines an object's opacity

0 ... transparent

1 ... opaque

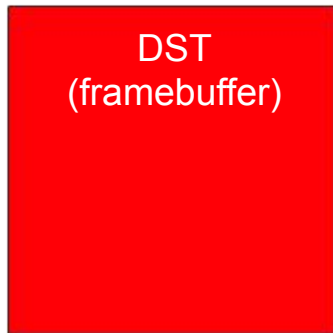
(depending on blend function)



A common blend function is:

```
gl.blendFunc(gl.SRC_ALPHA, gl.ONE_MINUS_SRC_ALPHA);
```

(will use that in the upcoming labs)



DST
(framebuffer)

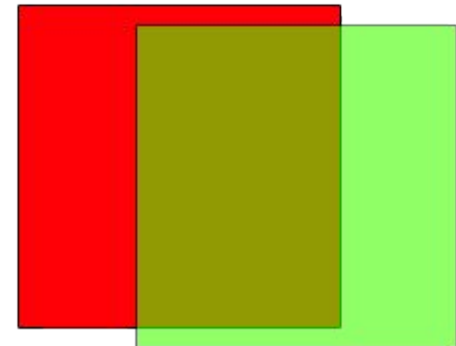
(1.0, 0.0, 0.0, 1.0)



SRC
(new fragment)

(0.0, 1.0, 0.0, 0.6)

$$\bar{C}_{result} = \begin{pmatrix} 0.0 \\ 1.0 \\ 0.0 \\ 0.6 \end{pmatrix} * 0.6 + \begin{pmatrix} 1.0 \\ 0.0 \\ 0.0 \\ 1.0 \end{pmatrix} * (1 - 0.6)$$



(0.4, 0.6, 0.0, 0.76)

<https://learnopengl.com/Advanced-OpenGL/Blending>

Blending: Order

Demo: https://jku-icg.github.io/cg_demo/00_blending/

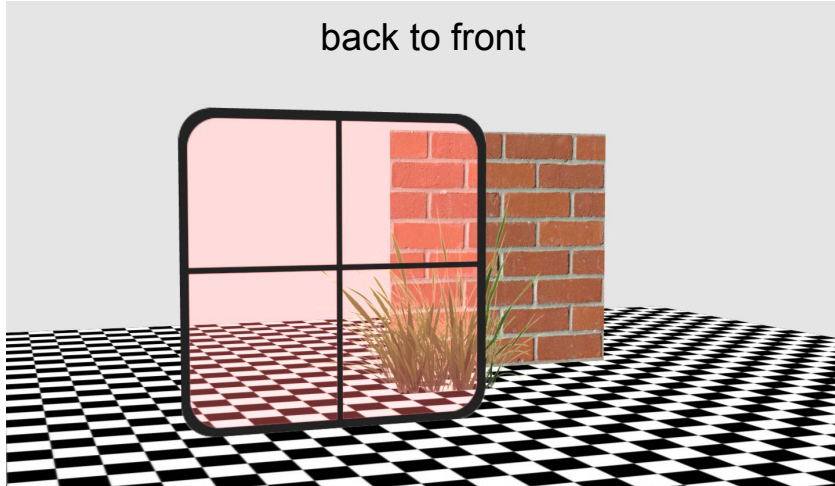
Rendering order is important (ignore it in your CG project!)

the depth test discards fragments that would be needed

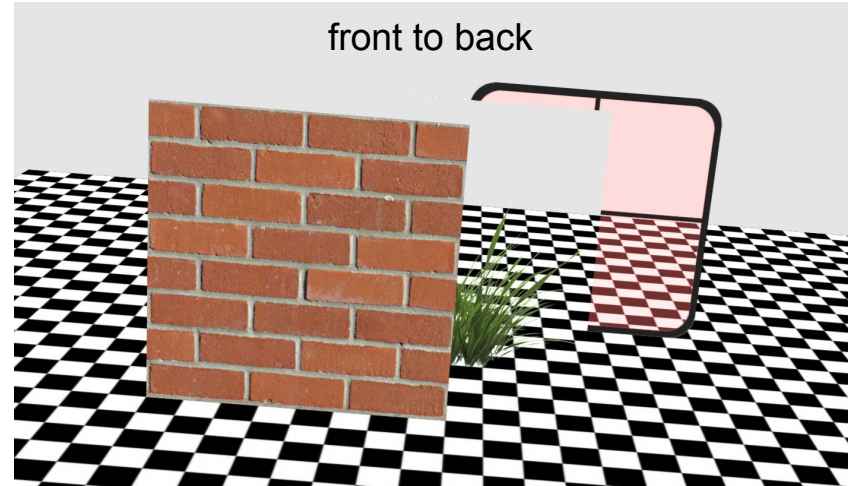
(thus, sometimes it makes sense to disable depth testing; e.g., particles)

In practice: sort objects by depth and render from back to front

back to front



front to back



Blending: Blend Functions

OpenGL offers various blend functions

Defining how pixels are blended, see learnopengl.com or <https://www.andersriggelsen.dk/glblendfunc.php>

Defines a way of blending an incoming pixel (the source) with the currently stored one (the destination):

```
gl.blendFunc(source, destination) .
```

Furthermore, the blend equation can be changed

e.g., addition (very common): `gl.blendEquation(GL_FUNC_ADD);`

Additionally, subtraction, min, max, is supported.

$$\bar{C}_{result} = \begin{pmatrix} 0.0 \\ 1.0 \\ 0.0 \\ 0.6 \end{pmatrix} * 0.6 + \begin{pmatrix} 1.0 \\ 0.0 \\ 0.0 \\ 1.0 \end{pmatrix} * (1 - 0.6)$$

Computer Graphics

Lab 3: Per-Fragment Operations Tutorial

Agenda for This Week

Per-Fragment Operations

Depth Handling

Blending

Tutorial (coding)

Scene Graphs

Abstraction into Nodes

Scene graph traversal

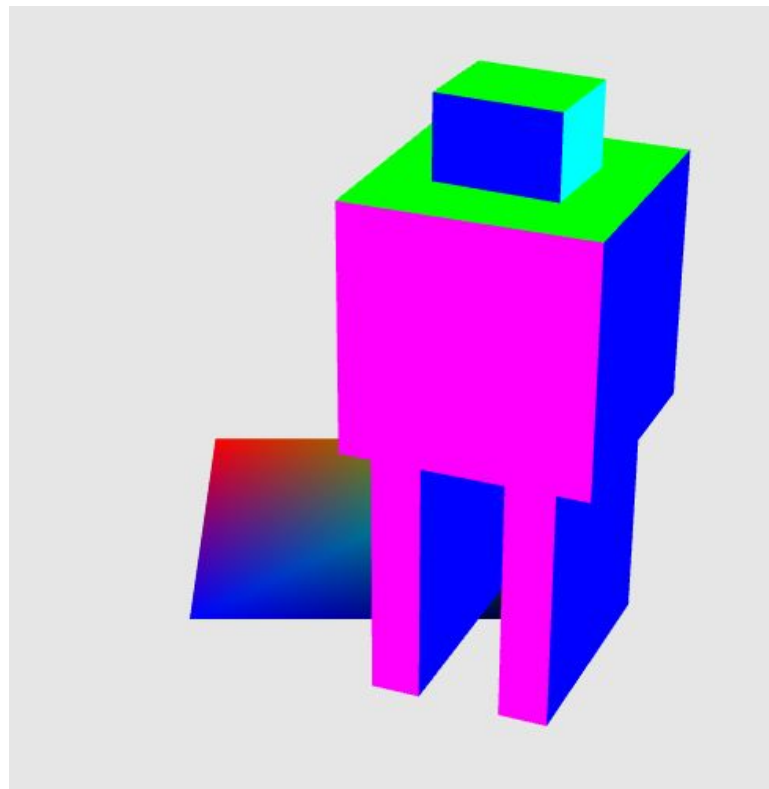
Base node class

Render nodes

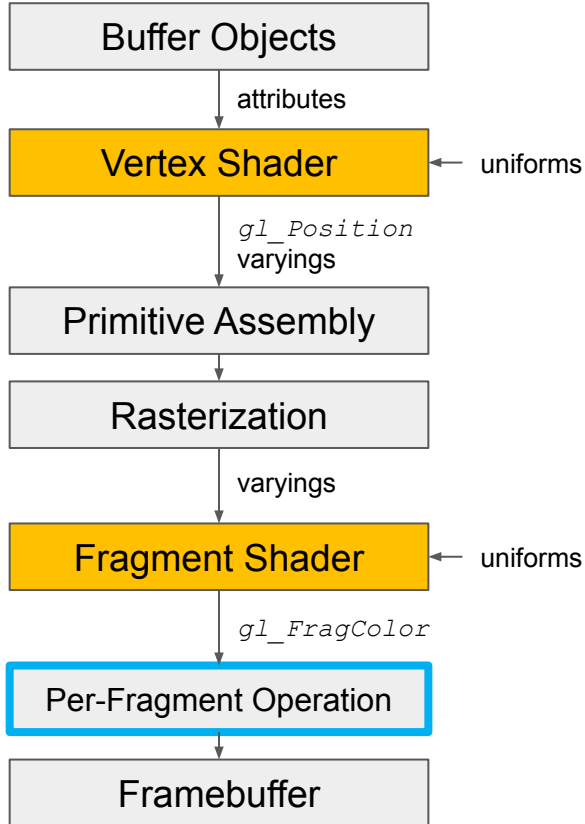
Transformation nodes

Implement robot using a scene graph

Tutorial (coding)



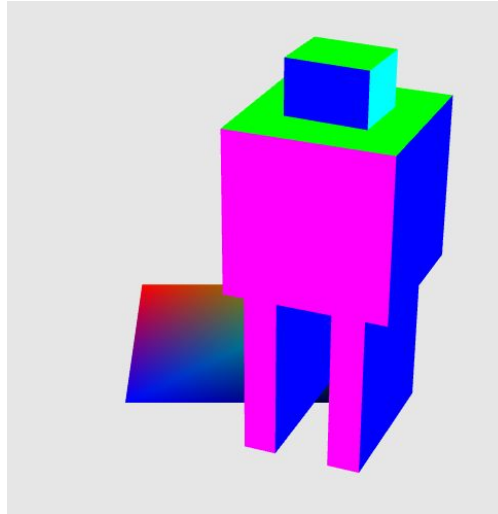
Per-Fragment Operation



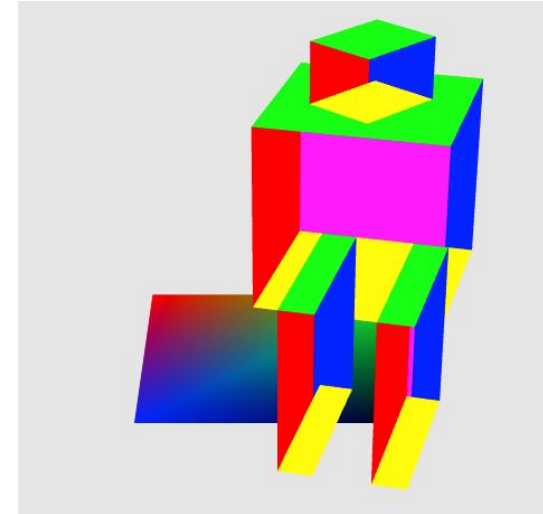
- additional tests/operations per fragment
- decides if (and how) fragments are written into the framebuffer
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 - **depth test**
the closer fragment should be drawn
 - **blending**
in case of semi transparent fragments
 - ...

Task 0: Depth Handling

Depth testing has to be enabled to tell OpenGL to perform a depth test and use the depth buffer: `gl.enable(gl.DEPTH_TEST);`
Try to turn it by: `gl.disable(gl.DEPTH_TEST);`
Then revert it, again.



Depth testing enabled



Depth testing disabled

Task 0: Solution

```
function render(timeInMilliseconds) {  
  
    //set background color to light gray  
    gl.clearColor(0.9, 0.9, 0.9, 1.0);  
    //clear the buffer  
    gl.clear(gl.COLOR_BUFFER_BIT | gl.DEPTH_BUFFER_BIT);  
    //TASK 0-1  
    //enable depth test to let objects in front occlude objects further away  
    gl.disable(gl.DEPTH_TEST);  
  
    //TASK 1-1  
    //TASK 1-2  
  
    //activate this shader program  
    gl.useProgram(shaderProgram);  
  
    //TASK 6-2  
  
    context = createSceneGraphContext(gl, shaderProgram);  
}
```

main.js

Task 1: Blending

Goal: Make the robot semi-transparent (50%)

Step 1: Enable blending by calling `gl.enable(gl.BLEND);`

Step 2: Set blend function:

```
gl.blendFunc(gl.SRC_ALPHA, gl.ONE_MINUS_SRC_ALPHA);
```

Step 3: Provide alpha value as uniform to fragment shader

Use `gl.uniform1f` to set `u_alpha` to **0.5** for **robot**

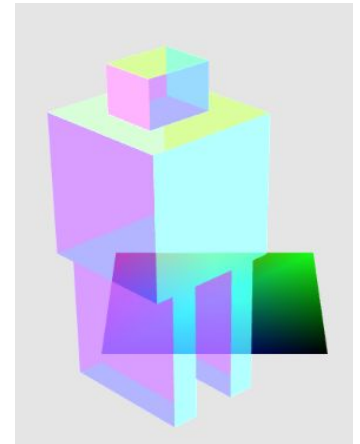
Use `gl.uniform1f` to set `u_alpha` to **1.0** for **quad**

Usage: `gl.uniform1f(location, alpha)`

Step 4: Incorporate `u_alpha` in fragment shader

Variable is already defined in fragment shader

Transparency is fourth component of the color vector (RGBA)



Task 1: Solution

```
//TASK 1-1
gl.enable(gl.BLEND);
//TASK 1-2
gl.blendFunc(gl.SRC_ALPHA, gl.ONE_MINUS_SRC_ALPHA);
```

```
//set alpha value for blending
//TASK 1-3
gl.uniform1f(gl.getUniformLocation(context.shader, "u_alpha"), 0.5);
```

main.js

```
//need to specify how "precise" float should be
precision mediump float;

//interpolate argument between vertex and fragment shader
varying vec3 v_color;

//alpha value determining transparency
uniform float u_alpha;

//entry point again
void main() {
    //gl_FragColor ... magic output variable containing the final 4D color of the fragment

    //in our case we use the provided interpolated color from our three vertices
    //TASK 1-4
    gl_FragColor = vec4(v_color, u_alpha);
}
```

simple.fs.glsl

Computer Graphics

Lab 3: Scene Graphs

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Per-Fragment Operations

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Blending

Tutorial (coding)

Scene Graphs

Abstraction into Nodes

Scene graph traversal

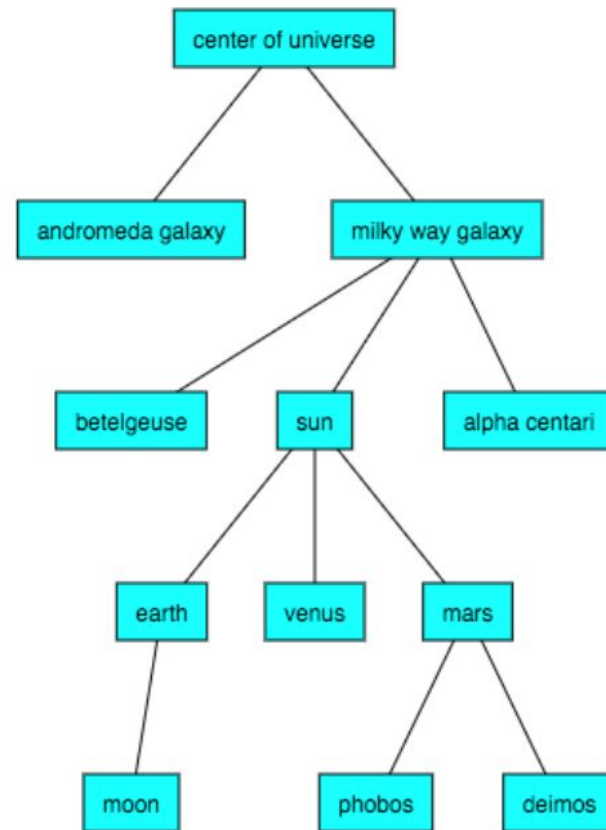
Base node class

Render nodes

Transformation nodes

Implement robot using a scene graph

Tutorial (coding)



Scene Graphs

Tree-like structure (hierarchical structure) for organizing scene
Objects in the scene will be added to the graph

During rendering, the graph will be traversed recursively

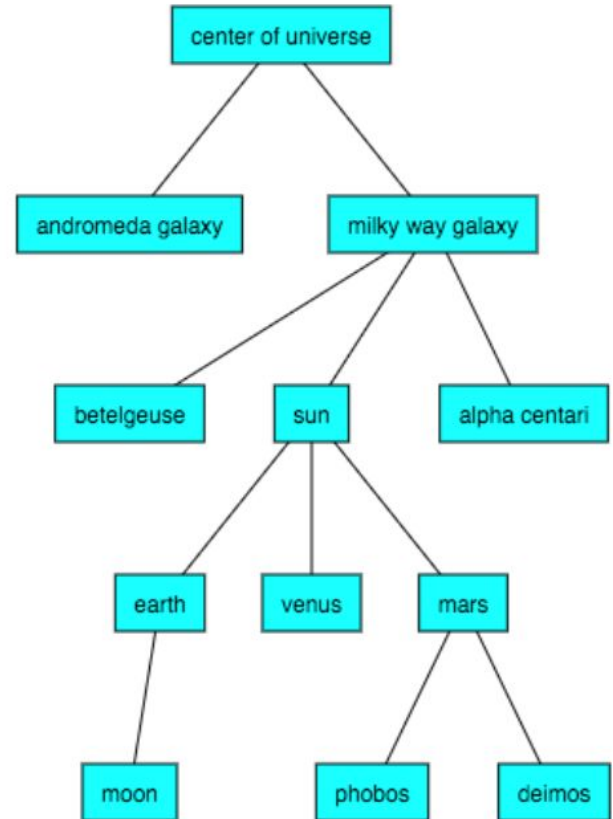
Advantages:

- Propagation of properties

- Unique point of access

- Reusable components

- Abstraction



Scene Graphs: Abstraction into Nodes

Entities in graph are called nodes

Parent-child relationship of nodes

Properties of a node are applied to all children

e.g., rotating the root node will make all sub nodes rotate too

In the case of transformations, each node holds a matrix and all matrices of all sub nodes are multiplied by this matrix

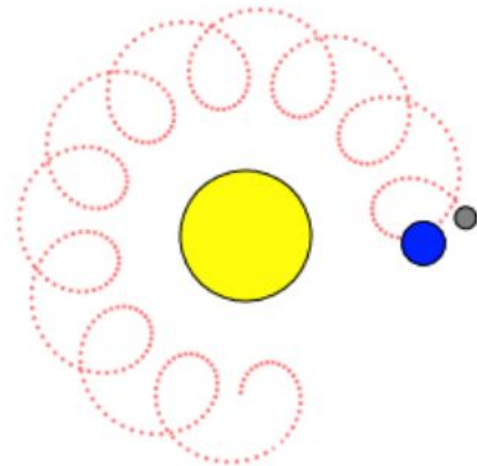
Different types of nodes

Geometry nodes (sphere, models, etc.)

Transformation nodes

Shader nodes (for lighting, materials, etc.)

We will implement all three!



Scene Graph Traversal

Traversal works recursively

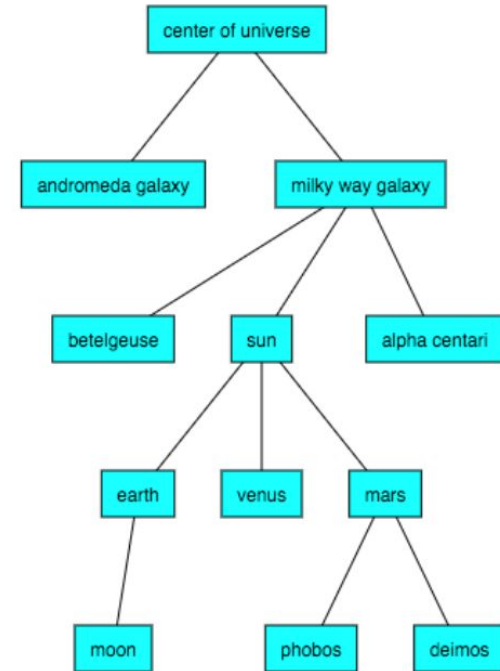
```
worldMatrix = parent(worldMatrix) * self(localMatrix)
```

Matrices are multiplied from top to bottom

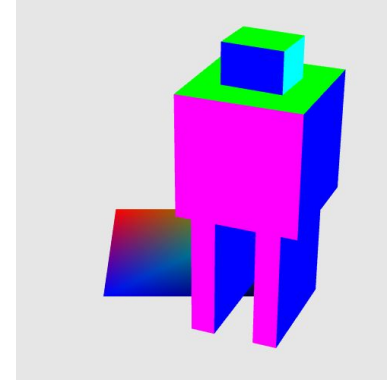
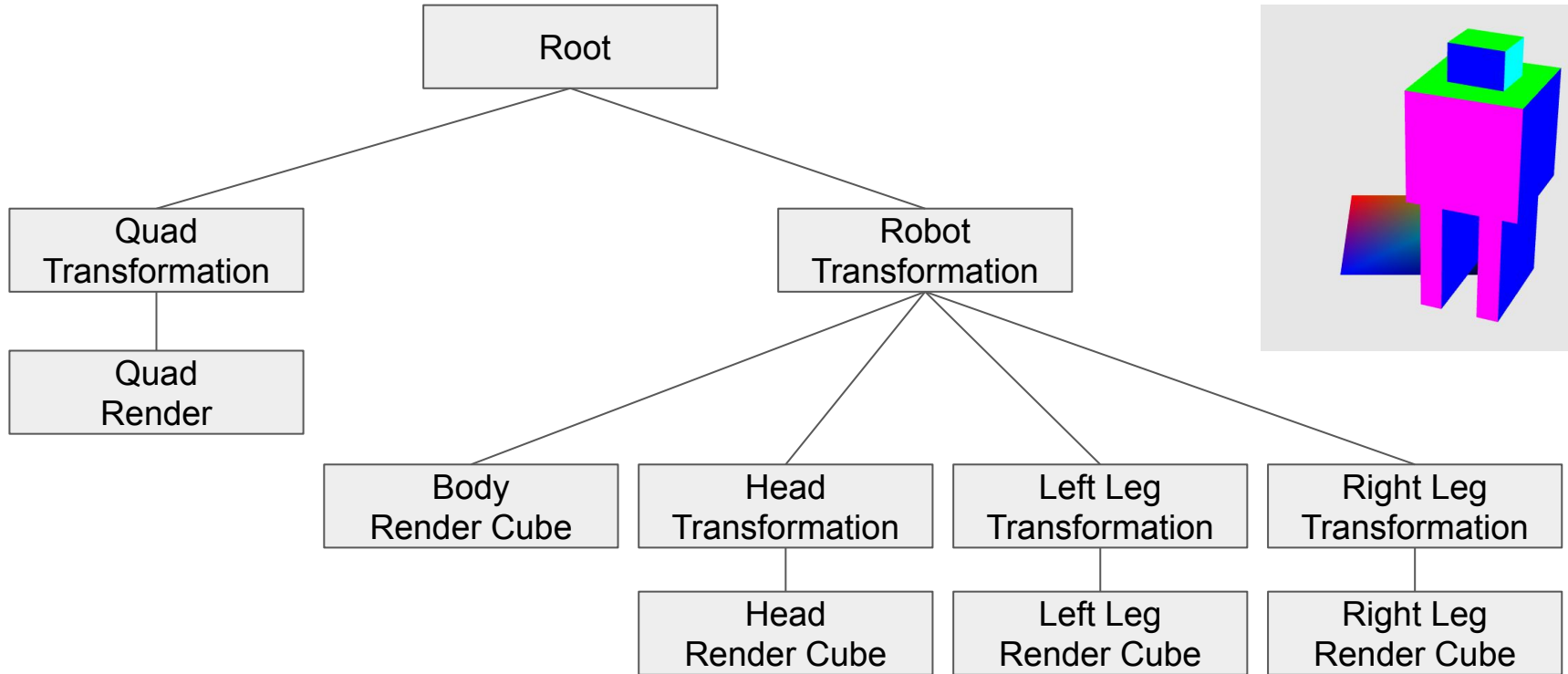
```
worldMatrix = greatGrandParent * grandParent * parent *  
self(localMatrix)
```

Solar system example:

```
worldMatrixForMoon = galaxyMatrix * starMatrix *  
planetMatrix * moonMatrix;
```



A Scene Graph for our Robot



A Basic Node

Needs the functionality to:

- Append a child node

- Remove a child node

- Render node and all its children (recursively)

Also: a Render context

- Stores scene matrix, view matrix, projection matrix and shader

- Gives us access to shader and matrices from inside nodes

Computer Graphics

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Scene Graphs

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Scene graph traversal

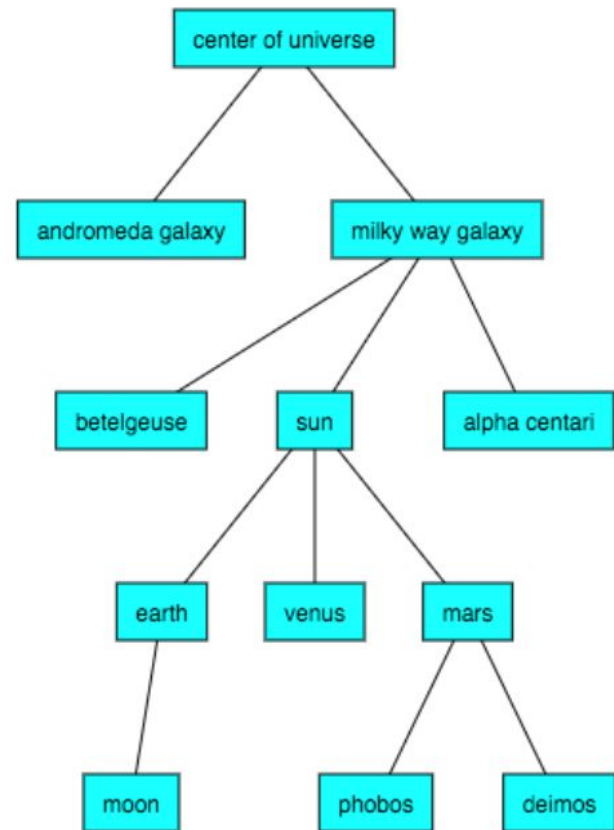
Base node class

Render nodes

Transformation nodes

Implement robot using a scene graph

Tutorial (coding)



Scene Graphs

Tree-like structure (hierarchical structure)

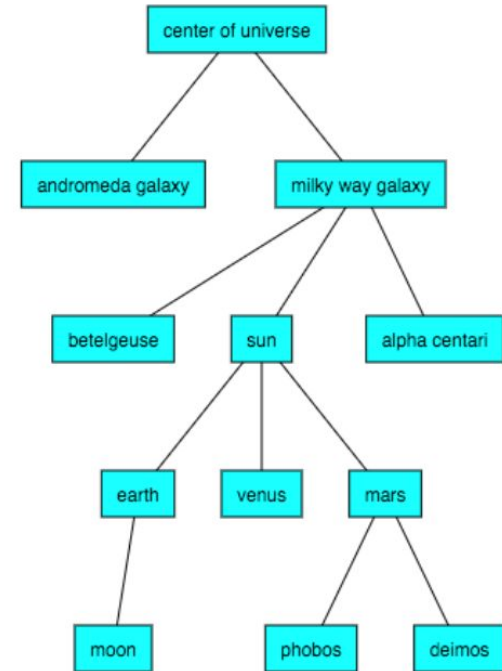
Advantages:

- Propagation of properties

- Unique point of access

- Reusable components

- Abstraction



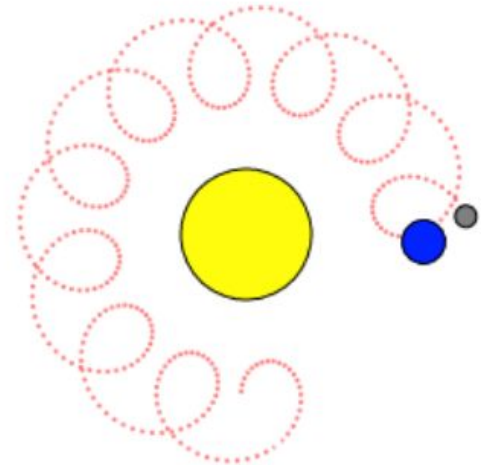
Creating a Node

We need the functionality to:

- Append a child node
- Remove a child node
- Render node and all its children (recursively)

What we also need: Render context

- Stores scene matrix, view matrix, projection matrix, and shader
- Access to shader and matrices inside nodes



Base Node

```
//create scenegraph  
rootNode = new SceneGraphNode();
```

Root

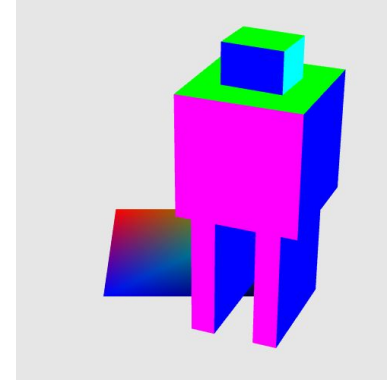
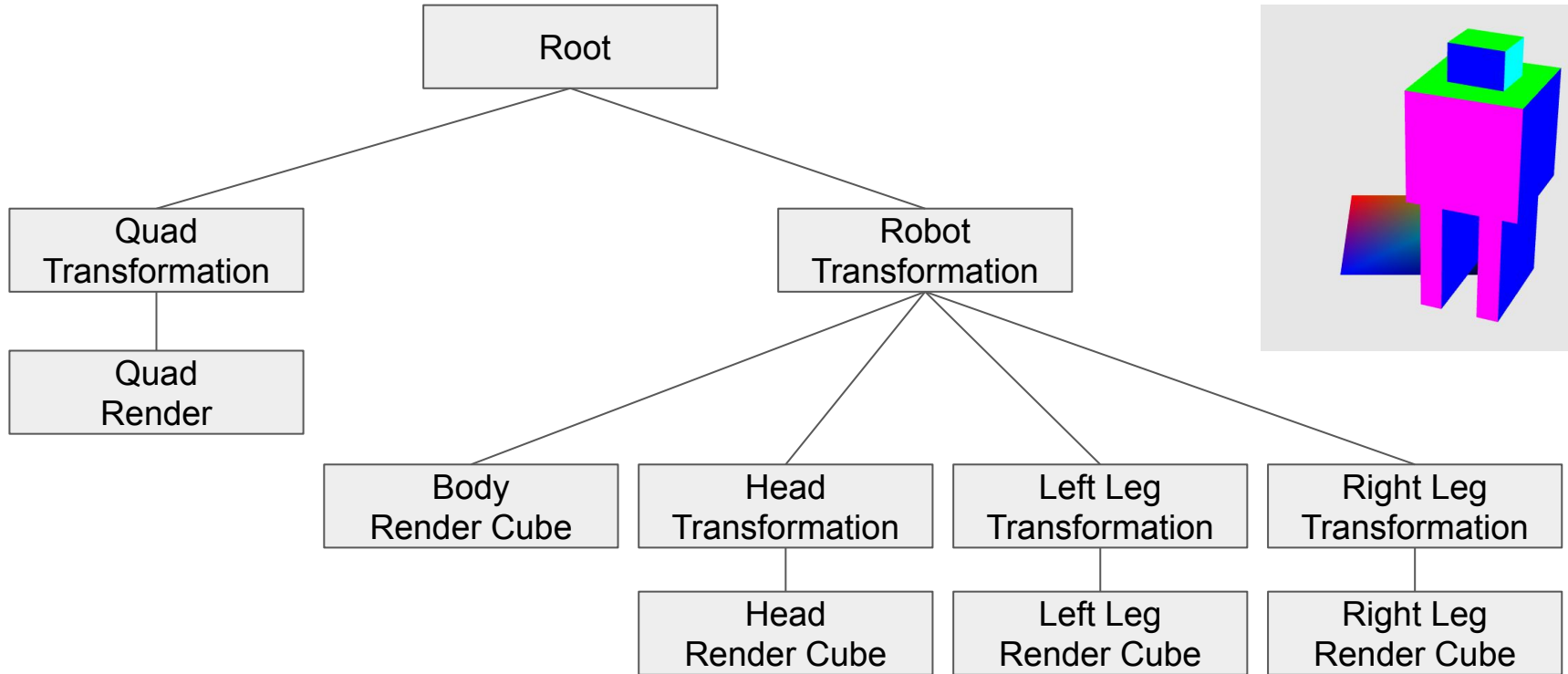
```
/**  
 * base node of the scenegraph  
 */  
class SceneGraphNode {  
  
    constructor() {  
        this.children = [];  
    }  
  
    /**  
     * appends a new child to this node  
     * @param child the child to append  
     * @returns {SceneGraphNode} the child  
     */  
    append(child) {  
        this.children.push(child);  
        return child;  
    }  
  
    /**  
     * removes a child from this node  
     * @param child  
     * @returns {boolean} whether the operation was successful  
     */  
    remove(child) {  
        var i = this.children.indexOf(child);  
        if (i >= 0) {  
            this.children.splice(i, 1);  
        }  
        return i >= 0;  
    };  
  
    /**  
     * render method to render this scenegraph  
     * @param context  
     */  
    render(context) {  
  
        //render all children  
        this.children.forEach(function (c) {  
            return c.render(context);  
        });  
    };  
};  
}
```

Render Context

```
const context = createSceneGraphContext(gl, shaderProgram);
```

```
/**  
 * returns a new rendering context  
 * @param gl the gl context  
 * @param shader the shader program to set the projection uniform  
 * @returns {ISceneGraphContext}  
 */  
function createSceneGraphContext(gl, shader) {  
  
    //create a default projection matrix  
    projectionMatrix = mat4.perspective(mat4.create(), fieldOfViewInRadians, aspectRatio, 0.01, 10);  
    //set projection matrix  
    gl.uniformMatrix4fv(gl.getUniformLocation(shader, 'u_projection'), false, projectionMatrix);  
  
    return {  
        gl: gl,  
        sceneMatrix: mat4.create(),  
        viewMatrix: calculateViewMatrix(),  
        projectionMatrix: projectionMatrix,  
        shader: shader  
    };  
}
```

Let's Make a Scene Graph for our Robot



Task 2: Create a Quad Render Node

Goal: Implement empty `QuadRenderNode` template

Step 0: Comment out `renderQuad` and `renderRobot` calls

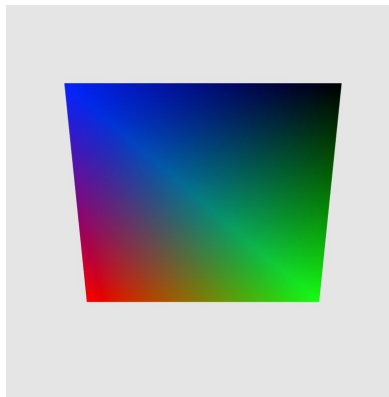
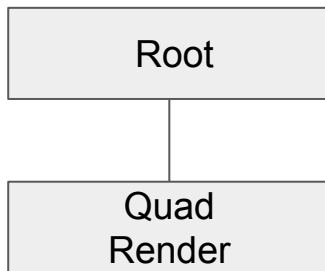
Step 1: Move quad render code to `QuadRenderNode` class

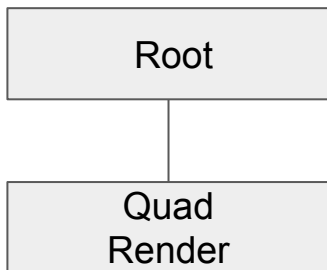
Note: Take `sceneMatrix` and `viewMatrix` from render context (`context`)

Note: Without transformations!

Step 2: Create node and add it to the scene graph

Note: Quad looks distorted because of perspective projection and camera

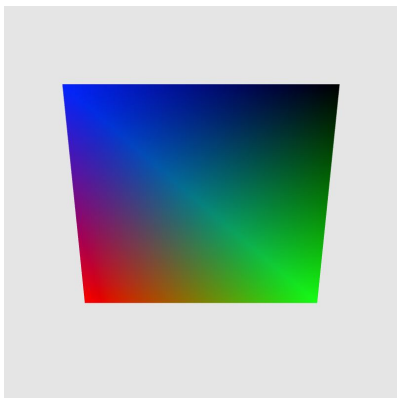




```
//TASK 2-2
```

```
var quadNode = new QuadRenderNode();
rootNode.append(quadNode);
```

main.js



Task 2: Solution

```

class QuadRenderNode extends SceneGraphNode {

  render(context) {

    //TASK 2-1
    //setting the model view and projection for the shader
    setUpModelViewMatrix(context.sceneMatrix, context.viewMatrix);
    gl.uniformMatrix4fv( gl.getUniformLocation(context.shader, 'u_projection'),
                        false, context.projectionMatrix);

    var positionLocation = gl.getAttribLocation(context.shader, 'a_position');
    gl.bindBuffer(gl.ARRAY_BUFFER, quadVertexBuffer);
    gl.vertexAttribPointer(positionLocation, 2, gl.FLOAT, false, 0, 0);
    gl.enableVertexAttribArray(positionLocation);

    var colorLocation = gl.getAttribLocation(context.shader, 'a_color');
    gl.bindBuffer(gl.ARRAY_BUFFER, quadColorBuffer);
    gl.vertexAttribPointer(colorLocation, 4, gl.FLOAT, false, 0, 0);
    gl.enableVertexAttribArray(colorLocation);

    //set alpha value for blending
    //TASK 1-3
    gl.uniform1f(gl.getUniformLocation(context.shader, 'u_alpha'), 1);

    // draw the bound data as 6 vertices = 2 triangles starting at index 0
    gl.drawArrays(gl.TRIANGLES, 0, 6);

    //render children
    super.render(context);
  }
}
  
```

main.js

Transformation Node

Stores transformation matrix

During rendering:

1. Backup current sceneMatrix from context
2. Multiply sceneMatrix with local matrix
3. Render children
4. Restore previous sceneMatrix

```
//TASK 3-0
/**
 * a transformation node, i.e applied a transformation matrix to its successors
 */
class TransformationSceneGraphNode extends SceneGraphNode {
  /**
   * the matrix to apply
   * @param matrix
   */
  constructor(matrix) {
    super();
    this.matrix = matrix || mat4.create();
  }

  render(context) {
    //backup previous one
    var previous = context.sceneMatrix;
    //set current world matrix by multiplying it
    if (previous === null) {
      context.sceneMatrix = mat4.clone(this.matrix);
    }
    else {
      context.sceneMatrix = mat4.multiply(mat4.create(), previous, this.matrix);
    }

    //render children
    super.render(context);
    //restore backup
    context.sceneMatrix = previous;
  }

  setMatrix(matrix) {
    this.matrix = matrix;
  }
}
```

Task 3: Create a Transformation Node

Goal: Apply quad transformations

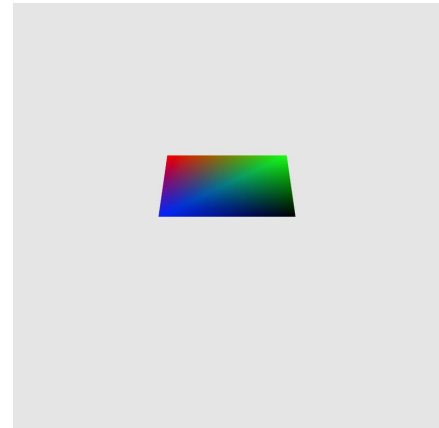
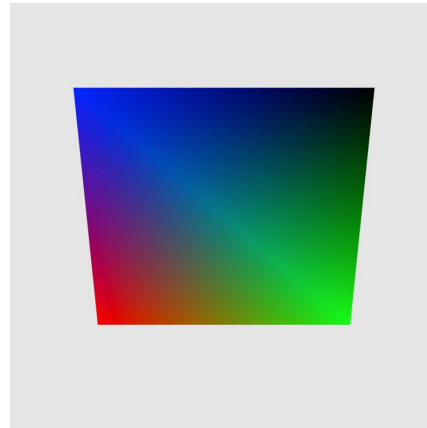
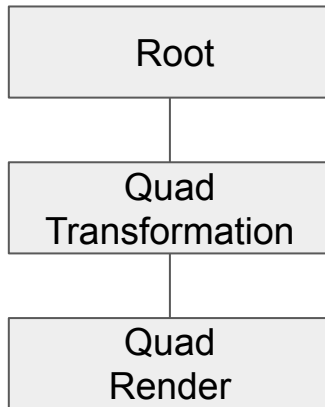
Step 0: Take a look at `TransformationSceneGraphNode`

Step 1: Create local transformation matrix

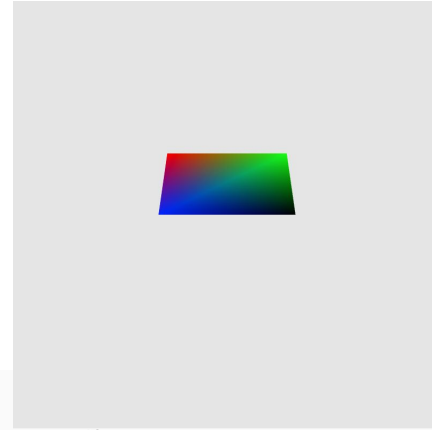
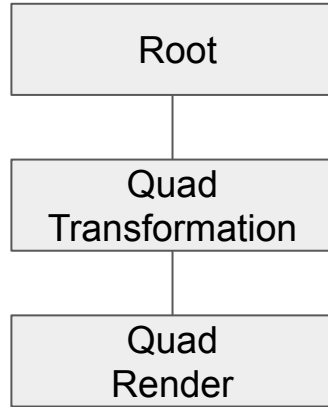
Move transformation code from `renderQuad`

Step 2: Create transformation node and add to scene graph

Hint: Don't forget to update existing scene graph parent-child relationships!



Task 3: Solution



```
//Task 3-1
```

```
var quadTransformationMatrix = glm.rotateX(90);  
quadTransformationMatrix = mat4.multiply(mat4.create(), quadTransformationMatrix, glm.translate(0.0,-0.5,0));  
quadTransformationMatrix = mat4.multiply(mat4.create(), quadTransformationMatrix, glm.scale(0.5,0.5,1));
```

```
//Task 3-2
```

```
var transformationNode = new TransformationSceneGraphNode(quadTransformationMatrix);  
rootNode.append(transformationNode);
```

```
//TASK 2-2
```

```
var quadNode = new QuadRenderNode();  
transformationNode.append(quadNode);
```

main.js

Task 4: Create a Cube Render Node

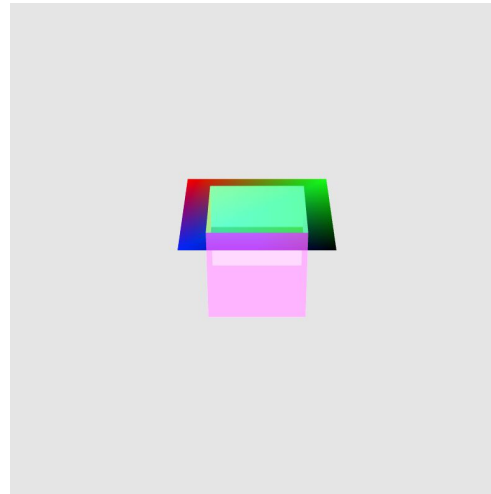
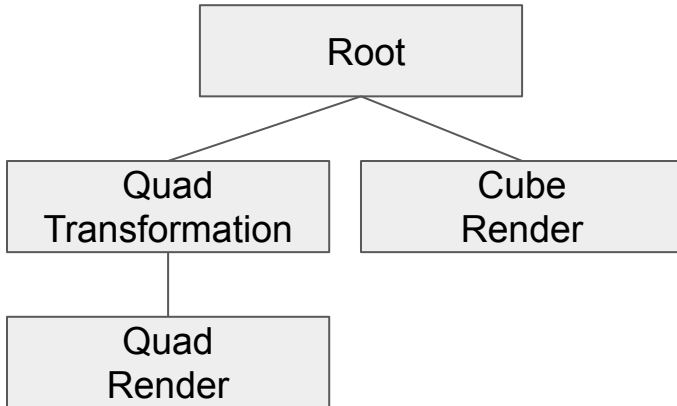
Goal: Render a cube

Step 1: Implement `CubeRenderNode`

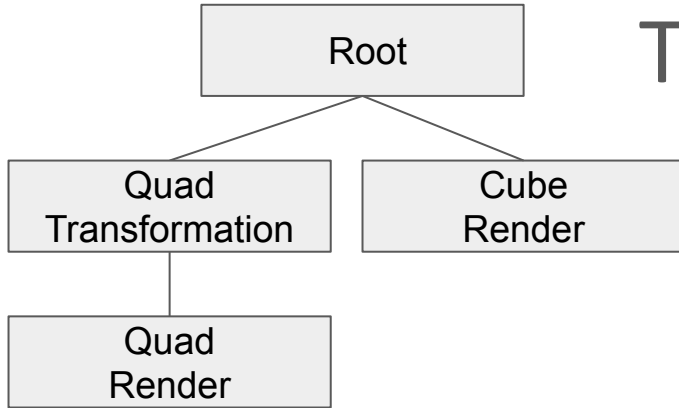
Take `QuadRenderNode` as template

Use cube render code from `renderRobot`

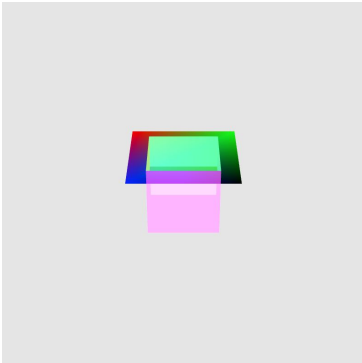
Step 2: Create cube node and add as child of root node



Task 4: Solution



```
//TASK 4-2
var cubeNode = new CubeRenderNode();
rootNode.append(cubeNode);
```



```
//TASK 4-1
/**
 * a cube node that renders a cube at its local origin
 */
class CubeRenderNode extends SceneGraphNode {
  render(context) {
    //setting the model view and projection for the shader
    setUpModelViewMatrix(context.sceneMatrix, context.viewMatrix);
    gl.uniformMatrix4fv( gl.getUniformLocation(context.shader, 'u_projection'),
                        false, context.projectionMatrix);

    var positionLocation = gl.getAttribLocation(context.shader, 'a_position');
    gl.bindBuffer(gl.ARRAY_BUFFER, cubeVertexBuffer);
    gl.vertexAttribPointer(positionLocation, 3, gl.FLOAT, false,0,0) ;
    gl.enableVertexAttribArray(positionLocation);

    var colorLocation = gl.getAttribLocation(context.shader, 'a_color');
    gl.bindBuffer(gl.ARRAY_BUFFER, cubeColorBuffer);
    gl.vertexAttribPointer(colorLocation, 3, gl.FLOAT, false,0,0) ;
    gl.enableVertexAttribArray(colorLocation);

    //set alpha value for blending
    //TASK 1-3
    gl.uniform1f(gl.getUniformLocation(context.shader, 'u_alpha'), 0.5);

    gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, cubeIndexBuffer);
    gl.drawElements(gl.TRIANGLES, cubeIndices.length, gl.UNSIGNED_SHORT, 0);

    //render children
    super.render(context);
  }
}
```

Shader Node

Holds shader program as variable

Allows us to use multiple shaders

During rendering:

1. Backup current `shader` from context
2. Use program (and set projection)
3. Render children
4. Restore previous `shader`

```
/**  
 * a shader node sets a specific shader for the successors  
 */  
class ShaderSceneGraphNode extends SceneGraphNode {  
  /**  
   * constructs a new shader node with the given shader program  
   * @param shader the shader program to use  
   */  
  constructor(shader) {  
    super();  
    this.shader = shader;  
  }  
  
  render(context) {  
    //backup previous one  
    var backup = context.shader;  
    //set current shader  
    context.shader = this.shader;  
    //activate the shader  
    context.gl.useProgram(this.shader);  
    //render children  
    super.render(context);  
    //restore backup  
    context.shader = backup;  
    //activate the shader  
    context.gl.useProgram(backup);  
  }  
};
```


Task 5: Adding a Shader Node

Goal: Assign yellow color to floor quad

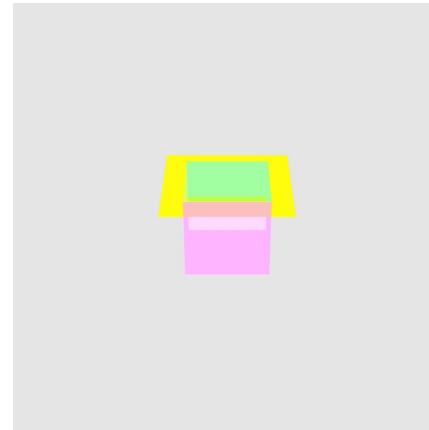
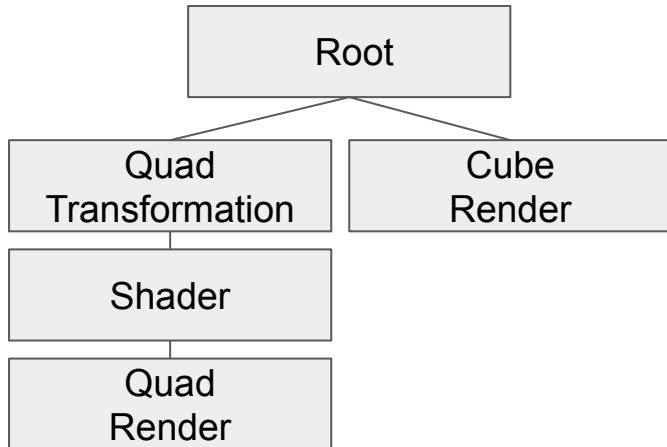
Step 1: Duplicate `simple.vs.glsl` shader and rename it

Step 2: Modify shader to apply static yellow color (R:1, G:1, B:0)

Step 3: Load new vertex shader as resource in `loadResources`

Step 4: Create new shader node and add it before the quad node

- Note: create new shader program and pass it to constructor of shader node

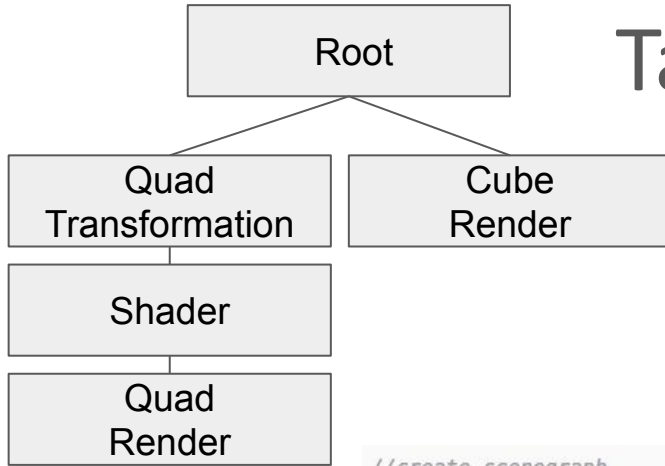


Task 5-1 and 5-2: Solution

```
//like a C program main is the main function  
void main() {  
  
    gl_Position = u_projection * u_modelView  
        * vec4(a_position, 1);  
  
    //TASK 5-2  
    //we don't use a_color anymore  
    a_color;  
  
    //setting a static color (yellow) to the output varying color  
    v_color = vec3(1,1,0);  
}
```

static_color.vs.glsl

Task 5-3 and 5-4: Solution



```

//load the shader resources using a utility function
loadResources({
  vs: 'shader/simple.vs.glsl',
  fs: 'shader/simple.fs.glsl',
  //TASK 5-3
  staticcolorvs: 'shader/static_color.vs.glsl'
}).then(function (resources /*an object containing our keys with the loaded resources*/) {
  init(resources);

  //render one frame
  render();
});
  
```

main.js

```

//create scenegraph
rootNode = new SceneGraphNode();

//Task 3-1
var quadTransformationMatrix = glm.rotateX(90);
quadTransformationMatrix = mat4.multiply(mat4.create(), quadTransformationMatrix, glm.translate(0.0,-0.5,0));
quadTransformationMatrix = mat4.multiply(mat4.create(), quadTransformationMatrix, glm.scale(0.5,0.5,1));

//Task 3-2
var transformationNode = new TransformationSceneGraphNode(quadTransformationMatrix);
rootNode.append(transformationNode);

//TASK 5-3
var staticColorShaderNode = new ShaderSceneGraphNode(createProgram(gl, resources.staticcolorvs, resources.fs));
transformationNode.append(staticColorShaderNode);

//TASK 2-2
var quadNode = new QuadRenderNode();
staticColorShaderNode.append(quadNode);
  
```

main.js

Reference Scene Graph Implementation

Frameworks typically provide a scene graph implementation

Example: Three.js

Our framework provides the following (and more) nodes:

`SGNode` (base class)

`TransformationSGNode`

`ShaderSGNode`

`RenderSGNode`

In upcoming labs, we will use the framework's scene graph implementation



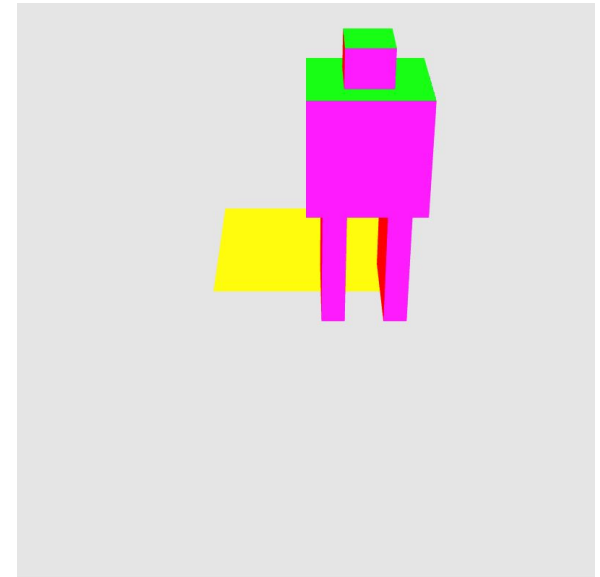
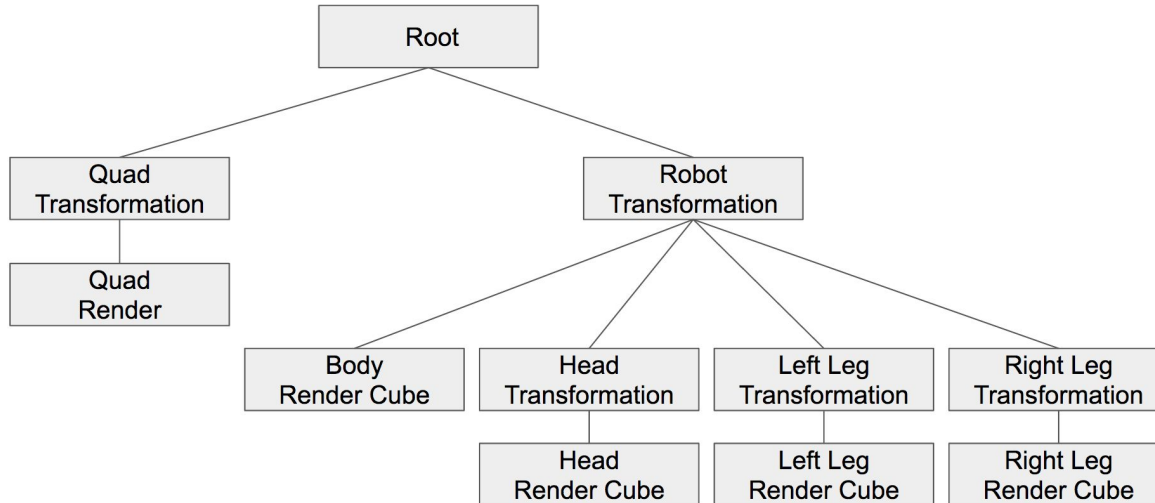
Use framework nodes in your CG project!

Task 6: Create Robot (At Home)

Goal: Rebuild robot from last lab as a scene graph

Step 1: Construct a robot scene graph in `createRobot` function

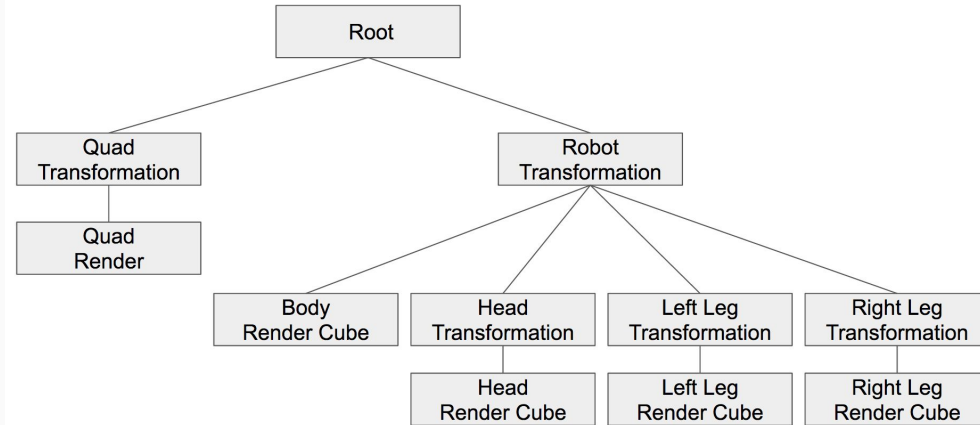
Step 2: Update rotation in `render` function



Task 6-1: Solution

```
function createRobot(rootNode) {  
  
  //TASK 6  
  
  //transformations of whole body  
  var robotTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.rotateY(animatedAngle/2));  
  robotTransformationMatrix = mat4.multiply(mat4.create(), robotTransformationMatrix, glm.translate(0.3,0.9,0));  
  robotTransformationNode = new TransformationSceneGraphNode(robotTransformationMatrix);  
  rootNode.append(robotTransformationNode);  
  
  //body  
  cubeNode = new CubeRenderNode();  
  robotTransformationNode.append(cubeNode);  
  
  //transformation of head  
  var headTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.rotateY(animatedAngle));  
  headTransformationMatrix = mat4.multiply(mat4.create(), headTransformationMatrix, glm.translate(0.0,0.4,0));  
  headTransformationMatrix = mat4.multiply(mat4.create(), headTransformationMatrix, glm.scale(0.4,0.33,0.5));  
  headTransformationNode = new TransformationSceneGraphNode(headTransformationMatrix);  
  robotTransformationNode.append(headTransformationNode);  
  
  //head  
  cubeNode = new CubeRenderNode();  
  headTransformationNode.append(cubeNode);  
  
  //transformation of left leg  
  var leftLegTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.translate(0.16,-0.6,0));  
  leftLegTransformationMatrix = mat4.multiply(mat4.create(), leftLegTransformationMatrix, glm.scale(0.2,1,1));  
  var leftLegTransformationNode = new TransformationSceneGraphNode(leftLegTransformationMatrix);  
  robotTransformationNode.append(leftLegTransformationNode);  
  
  //left leg  
  cubeNode = new CubeRenderNode();  
  leftLegTransformationNode.append(cubeNode);  
  
  //transformation of right leg  
  var rightLegTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.translate(-0.16,-0.6,0));  
  rightLegTransformationMatrix = mat4.multiply(mat4.create(), rightLegTransformationMatrix, glm.scale(0.2,1,1));  
  var rightLegTransformationNode = new TransformationSceneGraphNode(rightLegTransformationMatrix);  
  robotTransformationNode.append(rightLegTransformationNode);  
  
  //right leg  
  cubeNode = new CubeRenderNode();  
  rightLegTransformationNode.append(cubeNode);  
}
```

main.js



Task 6-2: Solution

```
//TASK 6-2
//update transformation of robot for rotation animation
var robotTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.rotateY(animatedAngle/2));
robotTransformationMatrix = mat4.multiply(mat4.create(), robotTransformationMatrix, glm.translate(0.3,0.9,0));
robotTransformationNode.setMatrix(robotTransformationMatrix);

var headTransformationMatrix = mat4.multiply(mat4.create(), mat4.create(), glm.rotateY(animatedAngle));
headTransformationMatrix = mat4.multiply(mat4.create(), headTransformationMatrix, glm.translate(0.0,0.4,0));
headTransformationMatrix = mat4.multiply(mat4.create(), headTransformationMatrix, glm.scale(0.4,0.33,0.5));
headTransformationNode.setMatrix(headTransformationMatrix);
```

main.js - in render function

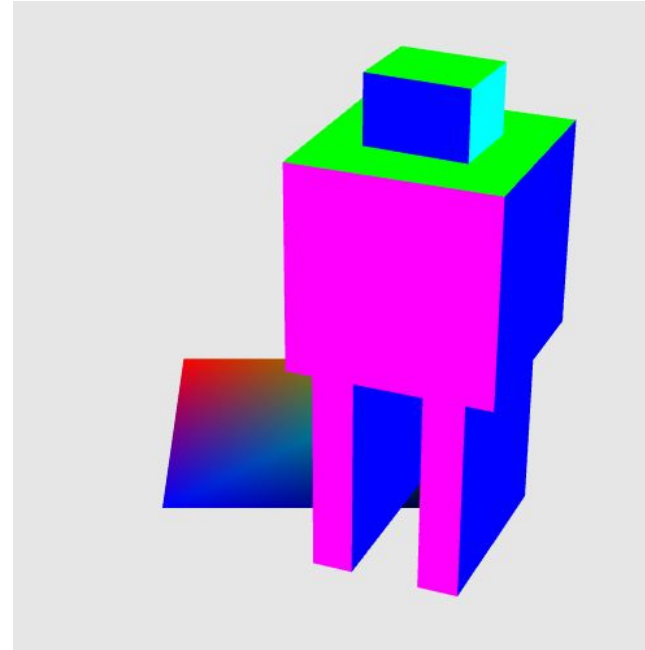
Recap

Per-Fragment Operations

- Depth Handling
- Blending
- Tutorial (coding)

Scene Graphs

- Abstraction into Nodes
- Scene graph traversal
- Base node class
- Render nodes
- Transformation nodes
- Implement robot using a scene graph
- Tutorial (coding)



Next Time

Illumination and shading

Light

Material

