

Seeing through Forest

Oliver Bimber



ICH SEHE WAS,
WAS DU NICHT SIEHST



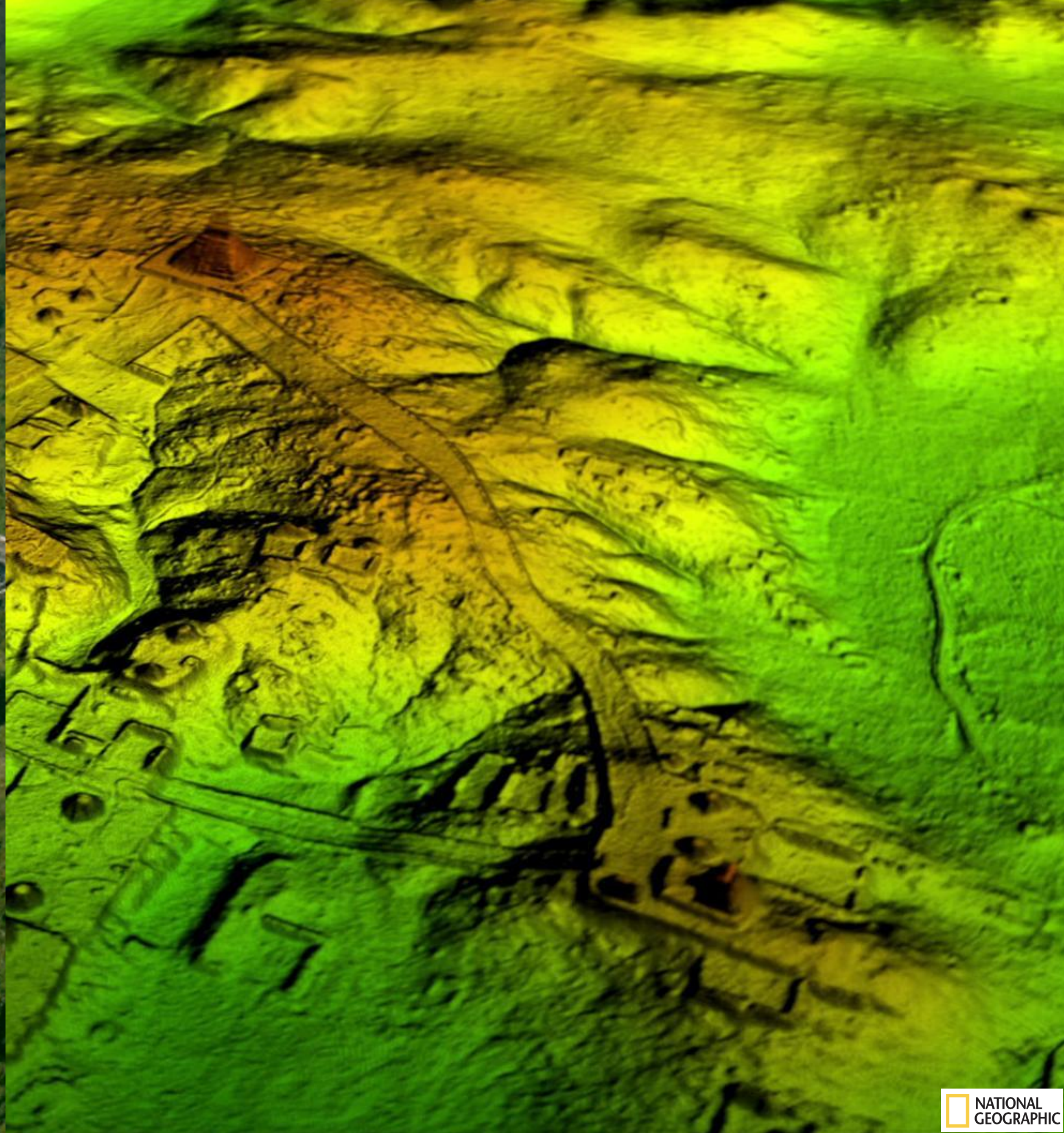
*Search and Rescue with Airborne Optical Sectioning,
Nature Machine Intelligence 2020*

nature
machine
intelligence

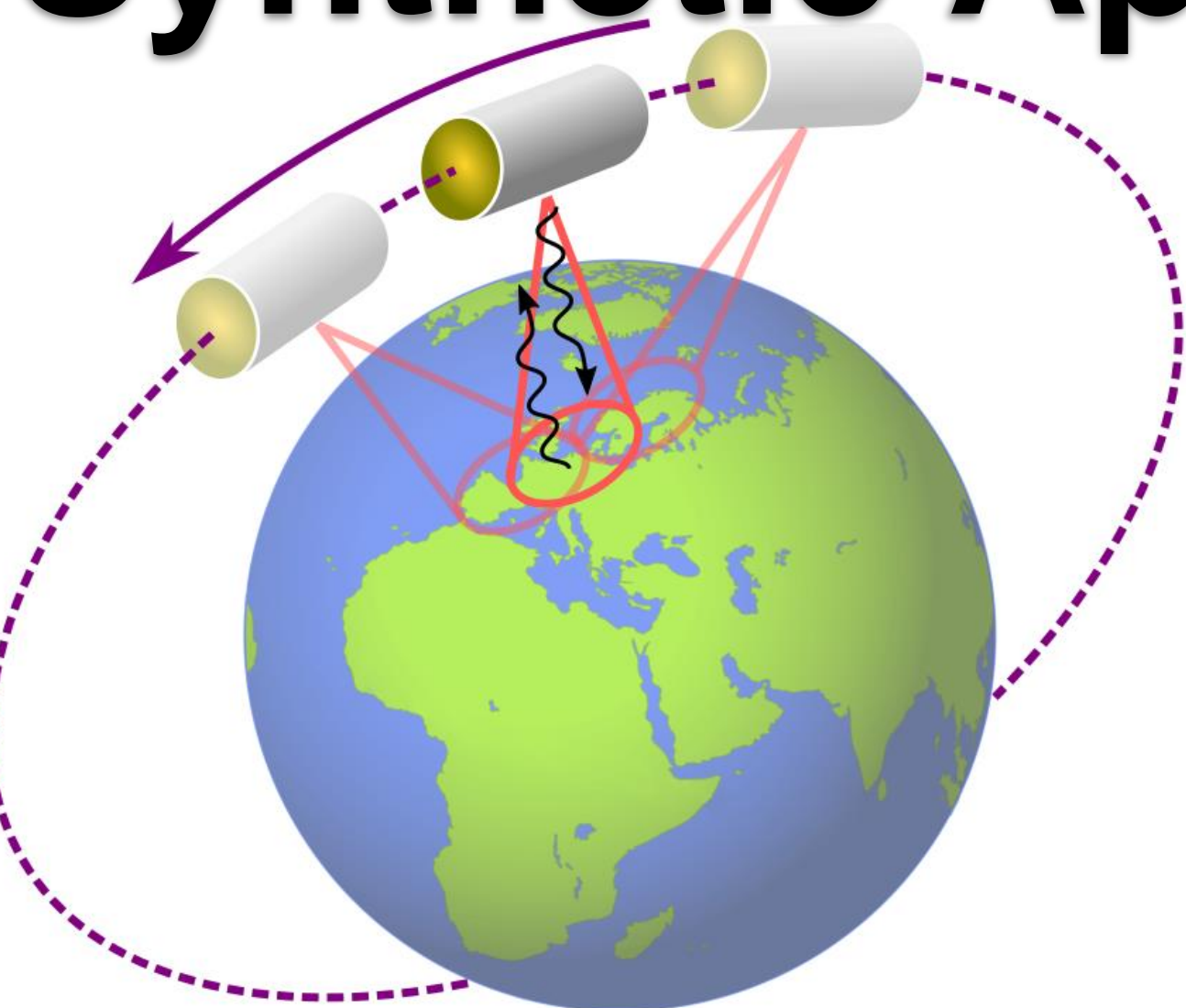


autonomous drone equipped with RGB and thermal cameras

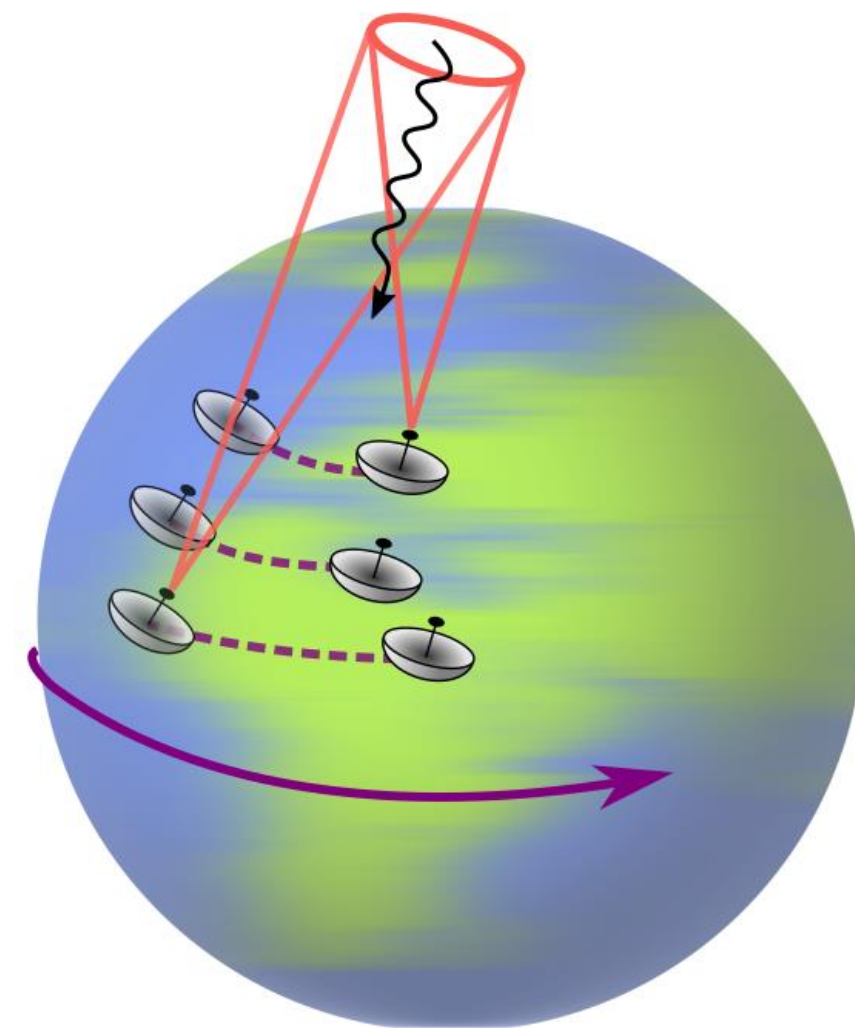
LiDAR



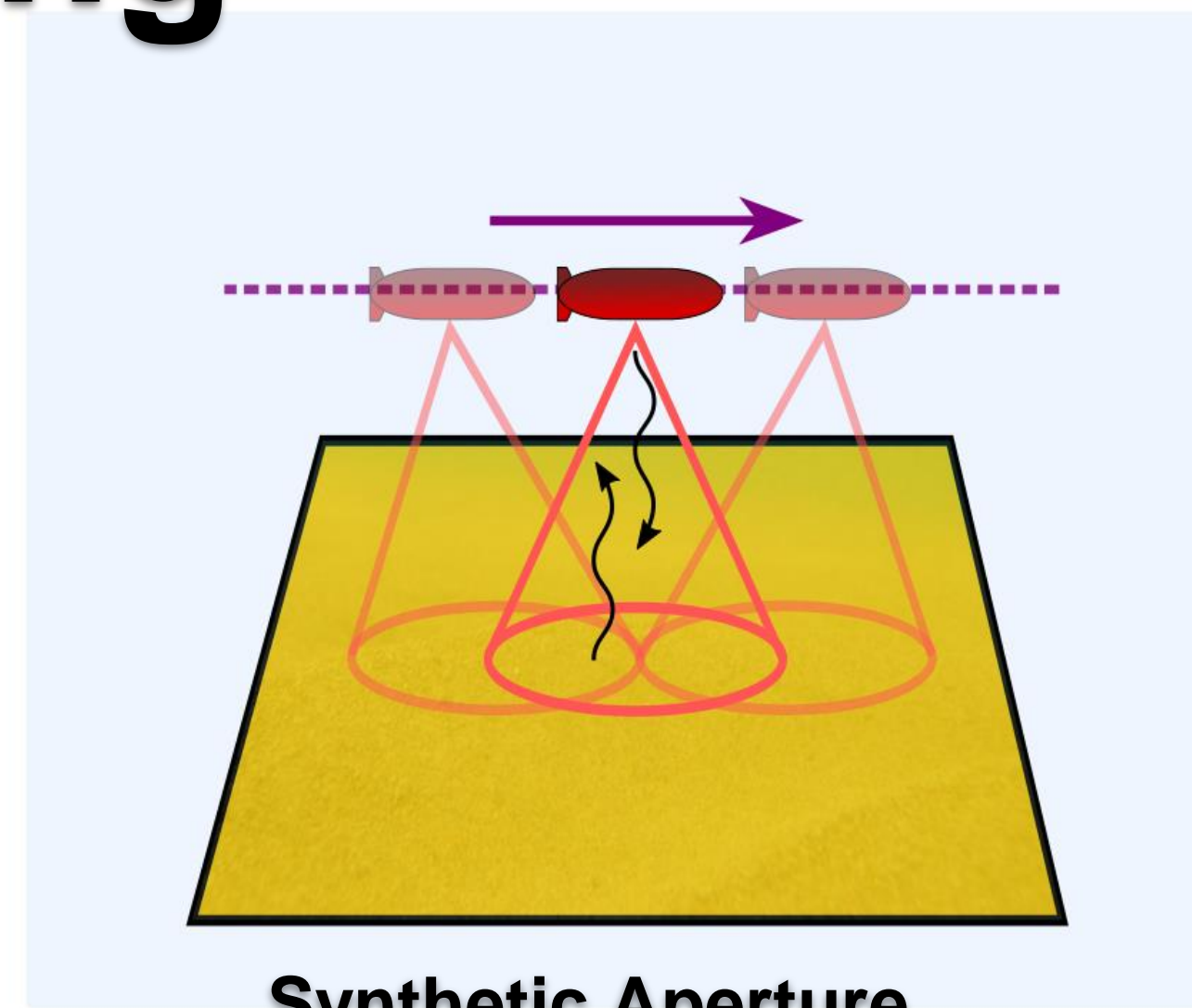
Synthetic Aperture Sensing



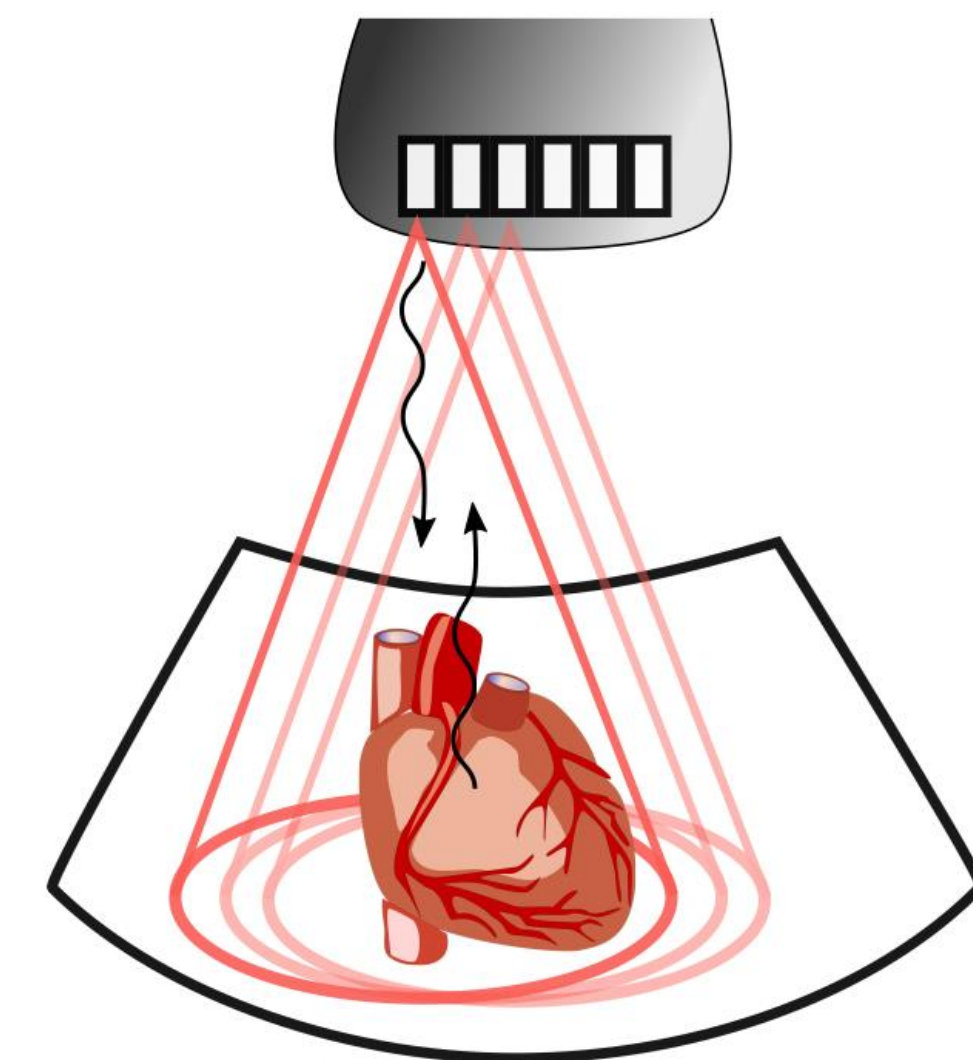
Synthetic Aperture Radar (SAR)



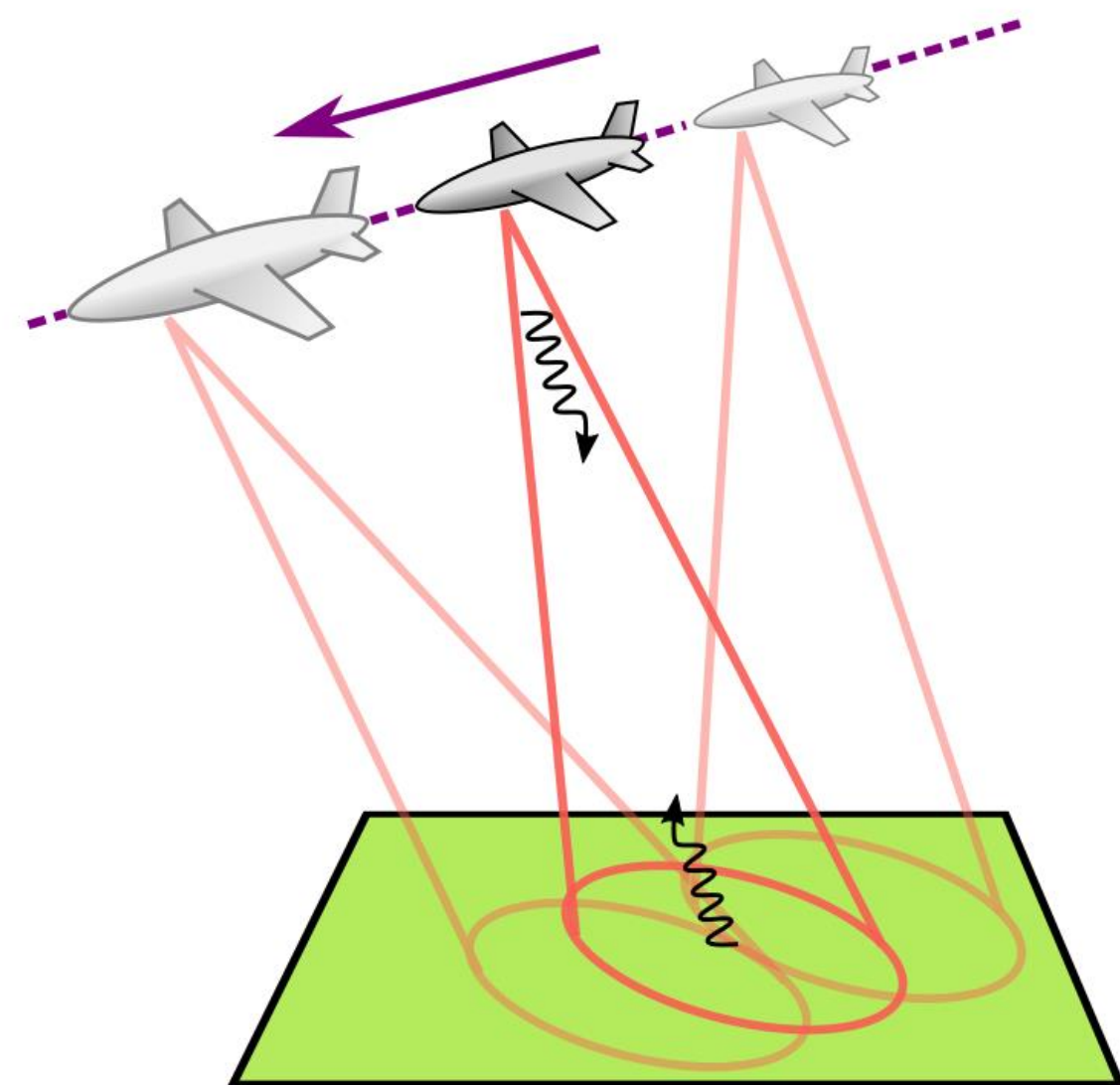
Synthetic Aperture Radio Telescopes (SART)



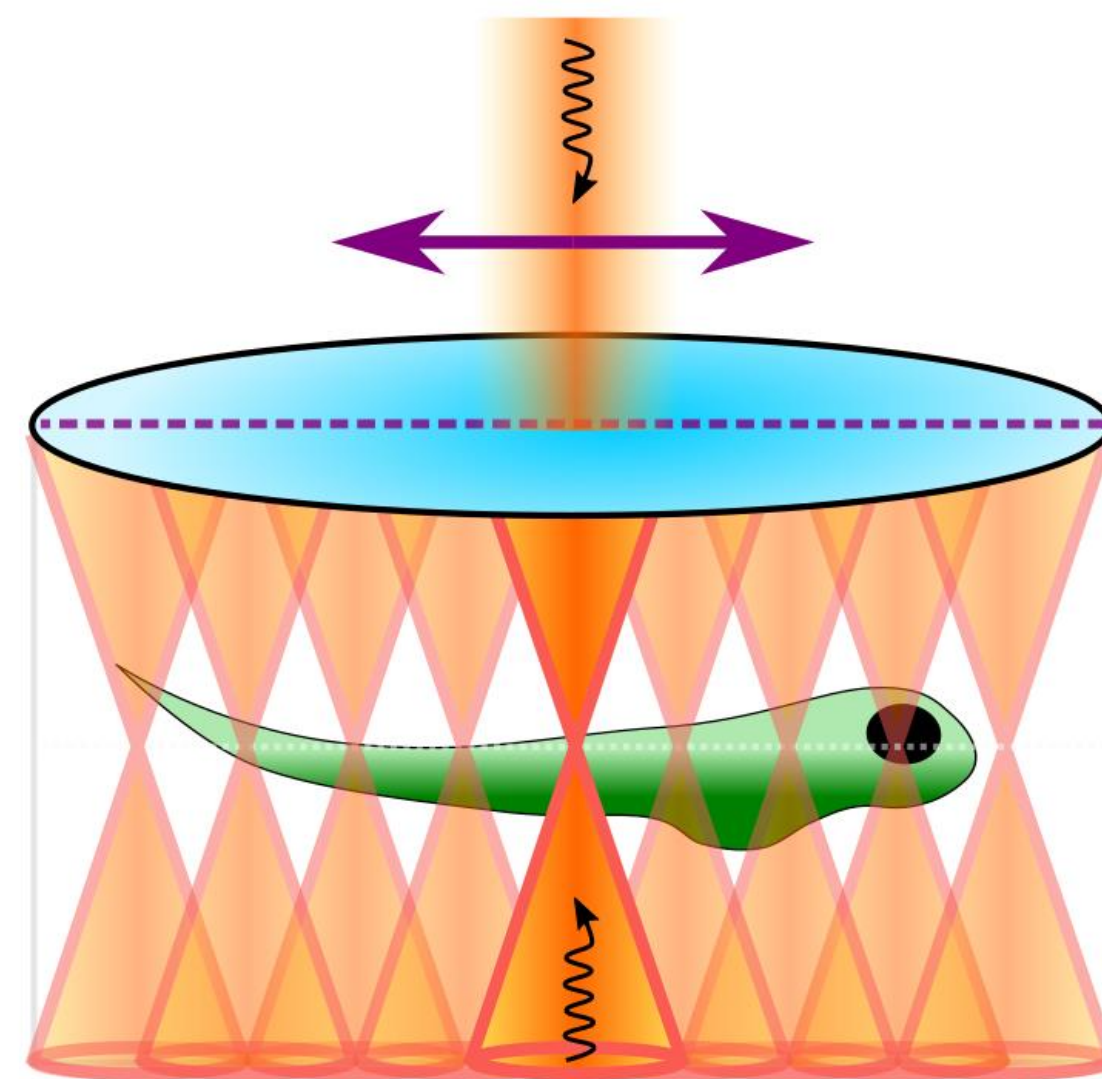
Synthetic Aperture Sonar (SAS)



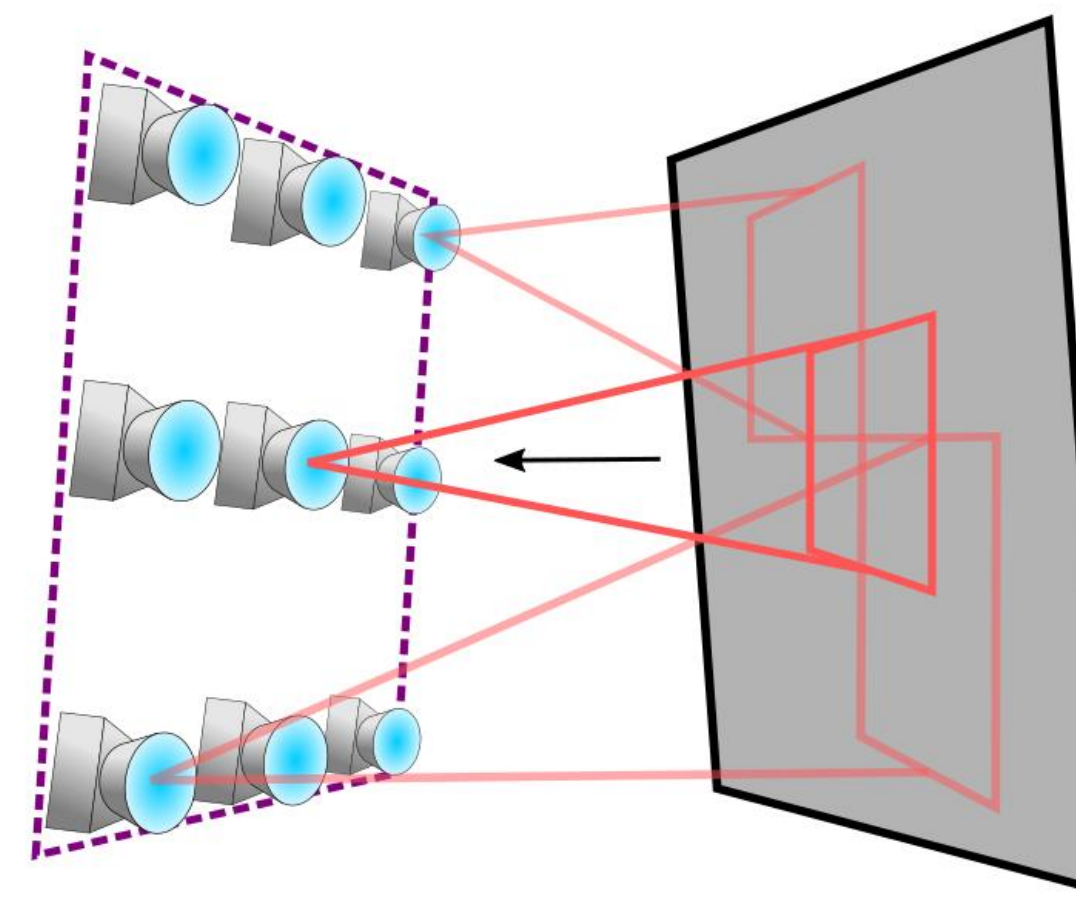
Synthetic Aperture Ultrasound (SAU)



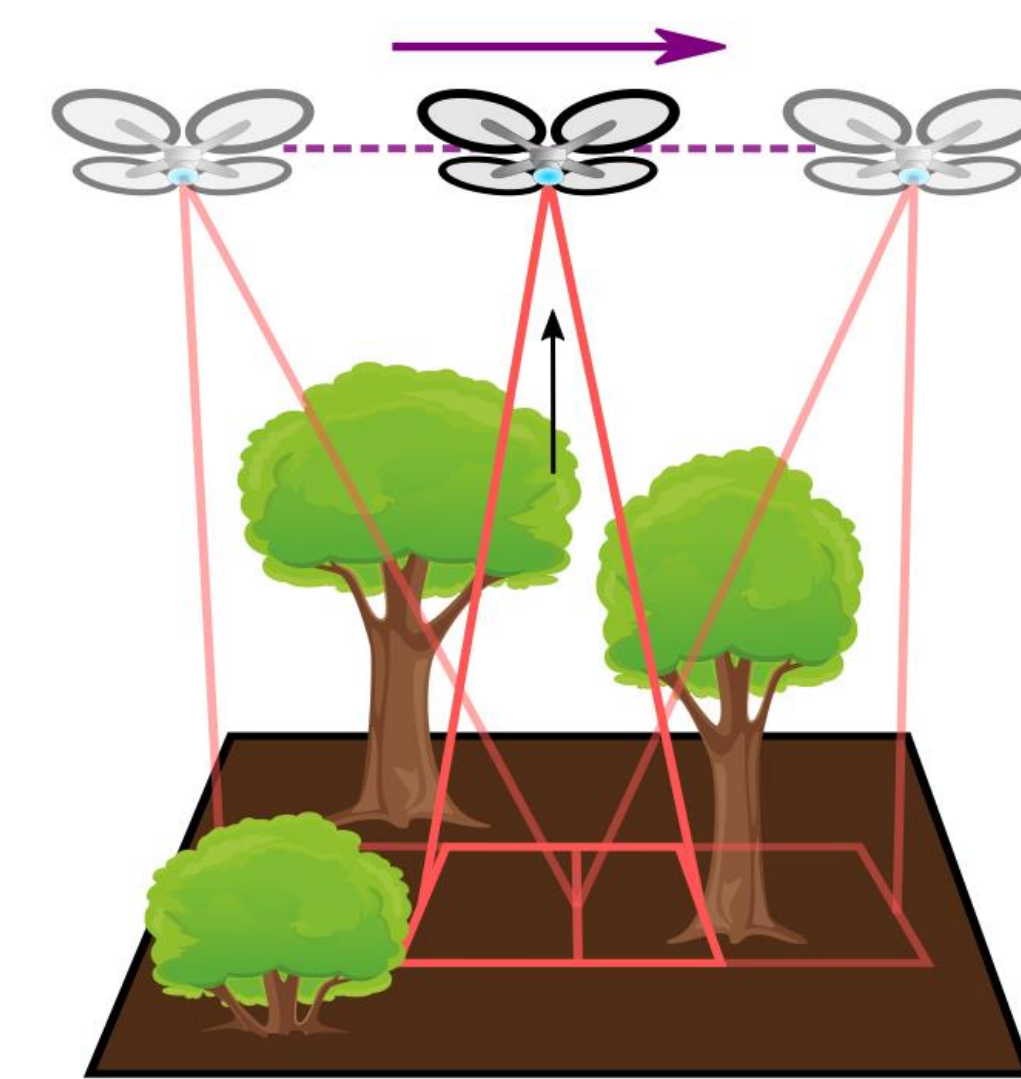
**synthetic aperture LiDAR (SAL)
synthetic aperture
imaging laser (SAIL)**



**Interferometric Synthetic Aperture
Microscopy (ISAM)**

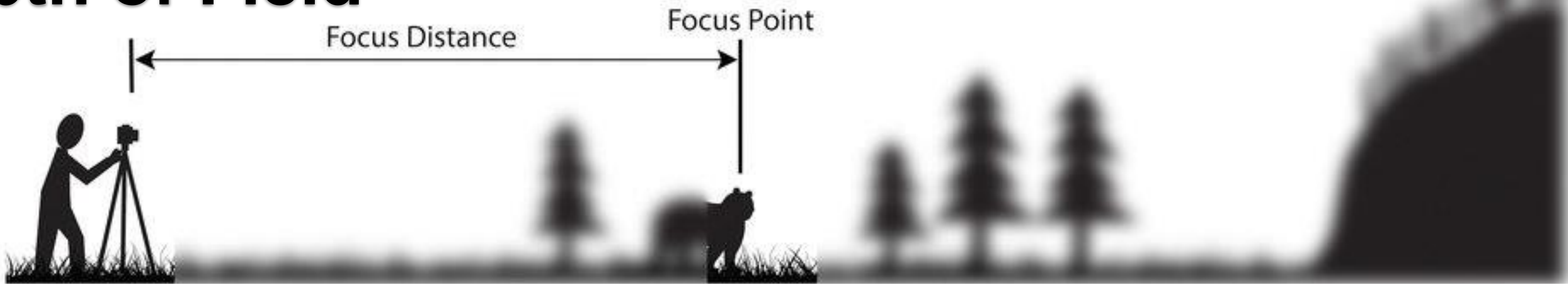


**Structured Light-Field
Imaging (SLFI)**



Airborne Optical Sectioning

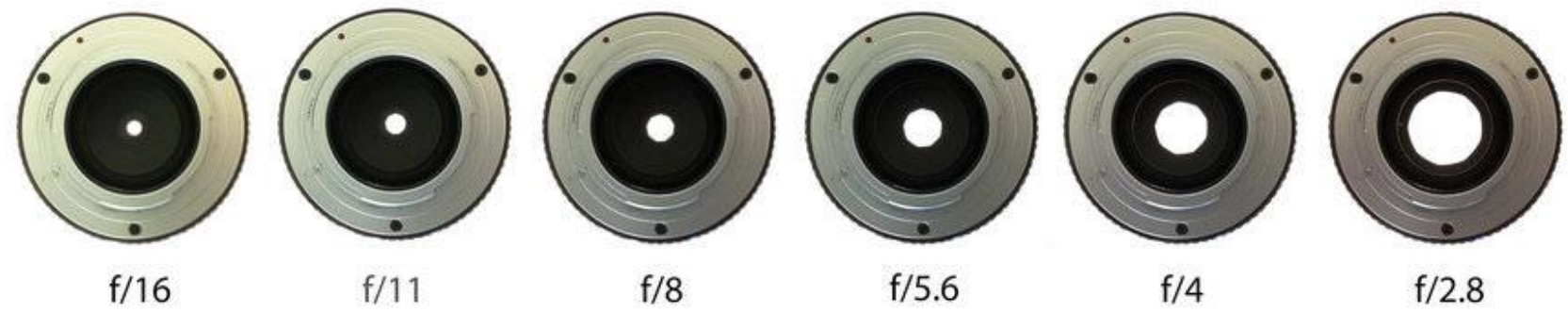
Depth of Field



Narrow Depth of Field

What if the aperture/lens is several meters in diameter?

Aperture Scale - Some Common Terminology

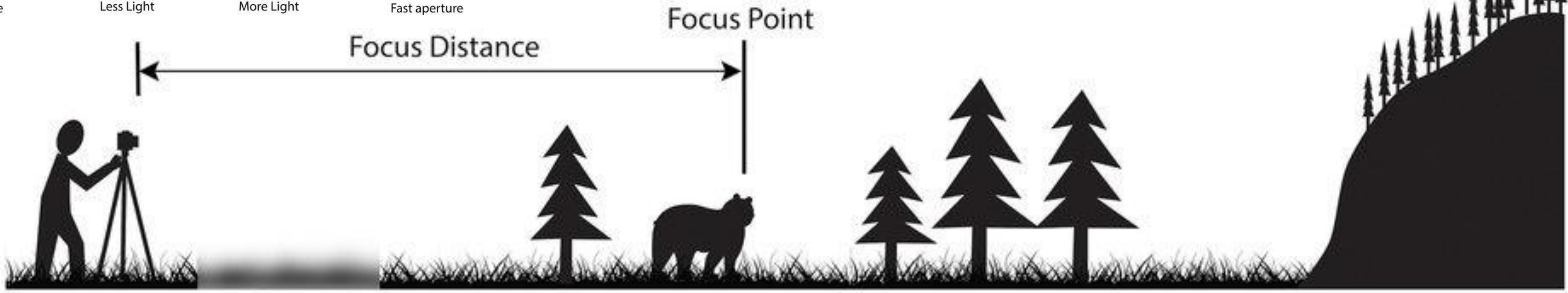


Small aperture
Closed down
Stopped down
Slow aperture

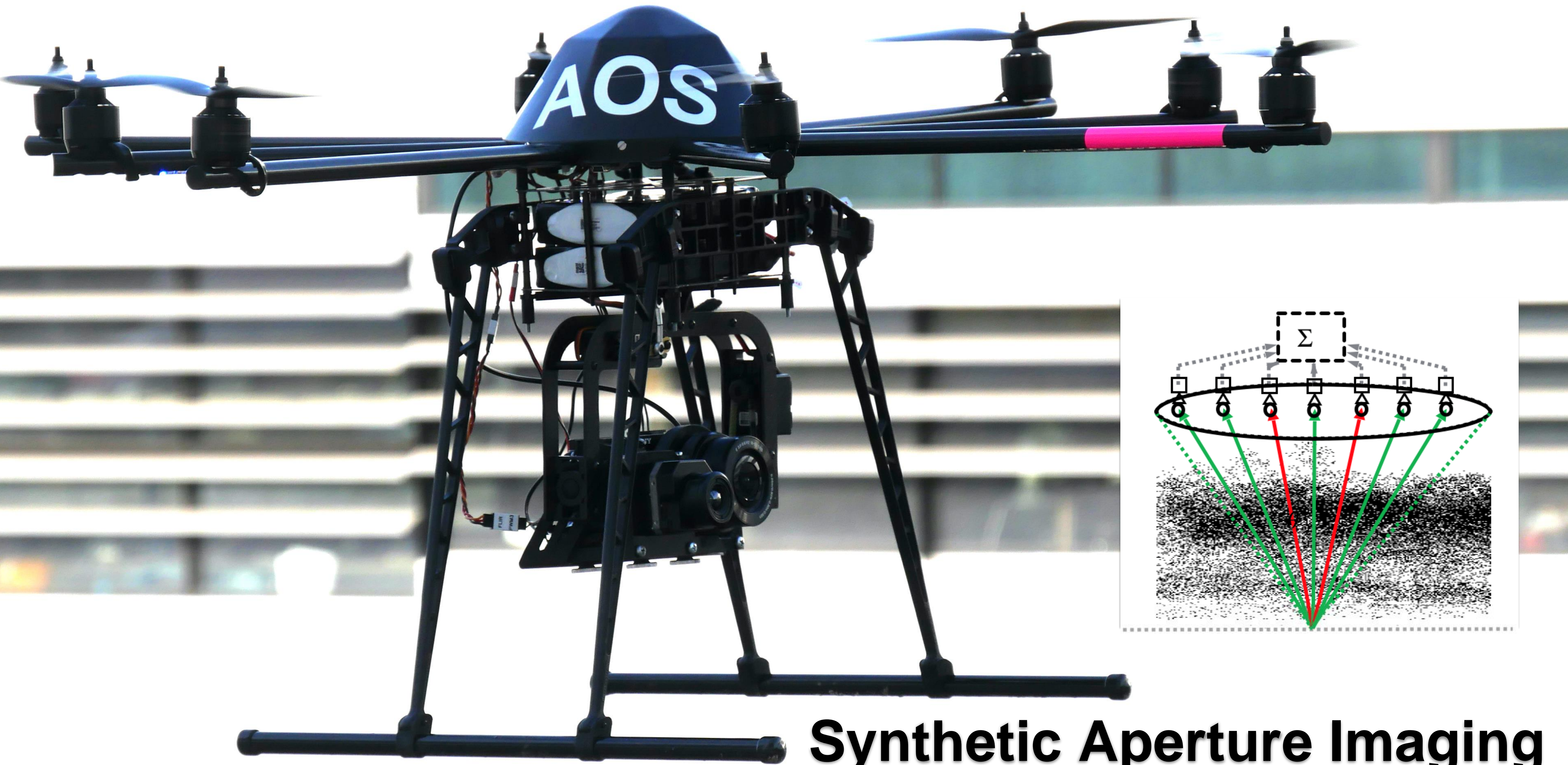
← More Depth of Field
Less Light

→ Less Depth of Field
More Light

Large aperture
Wide open
Wide aperture
Fast aperture



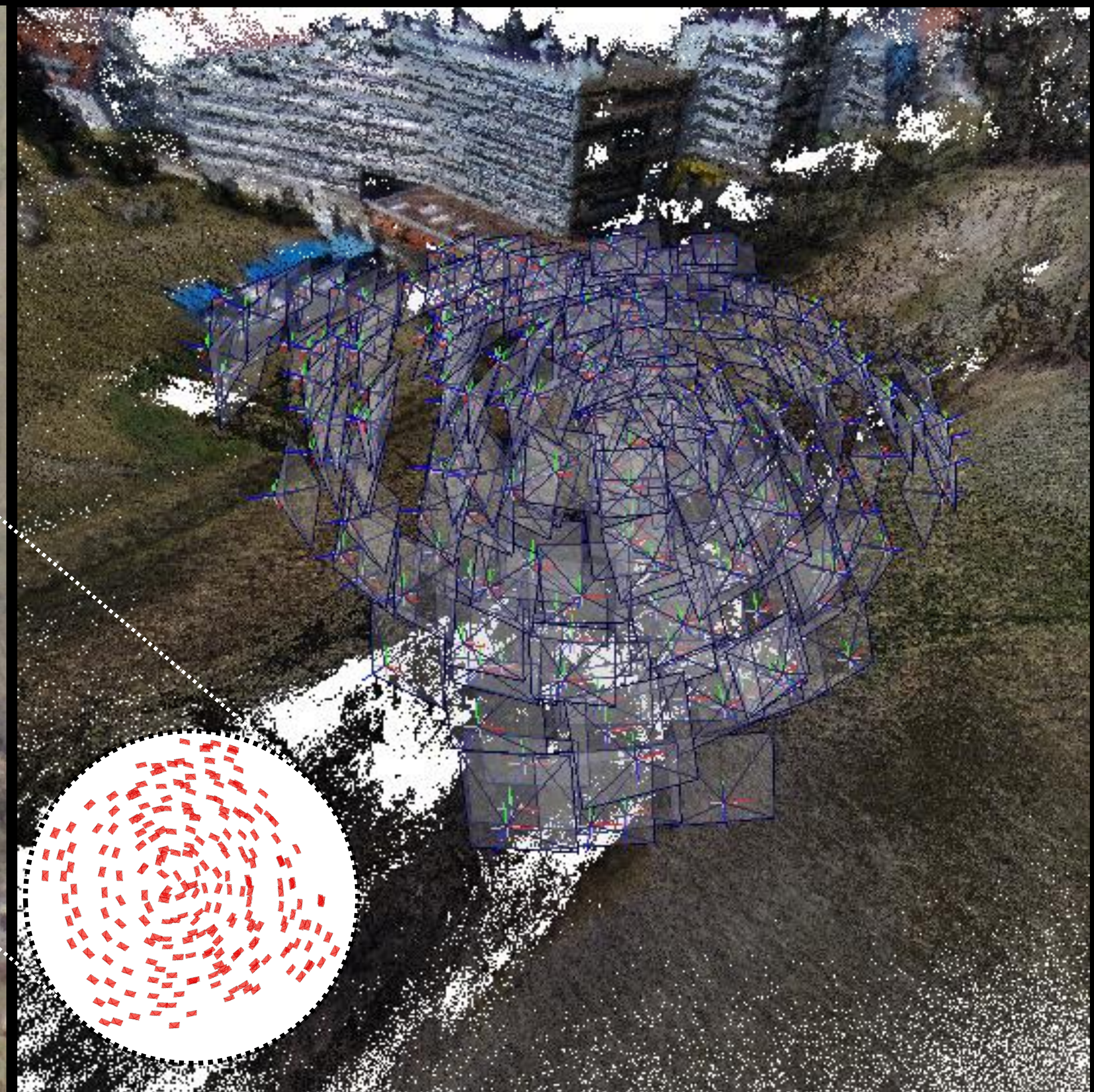
Large Depth of Field



**Synthetic Aperture Imaging
(unstructured Light-Field)**



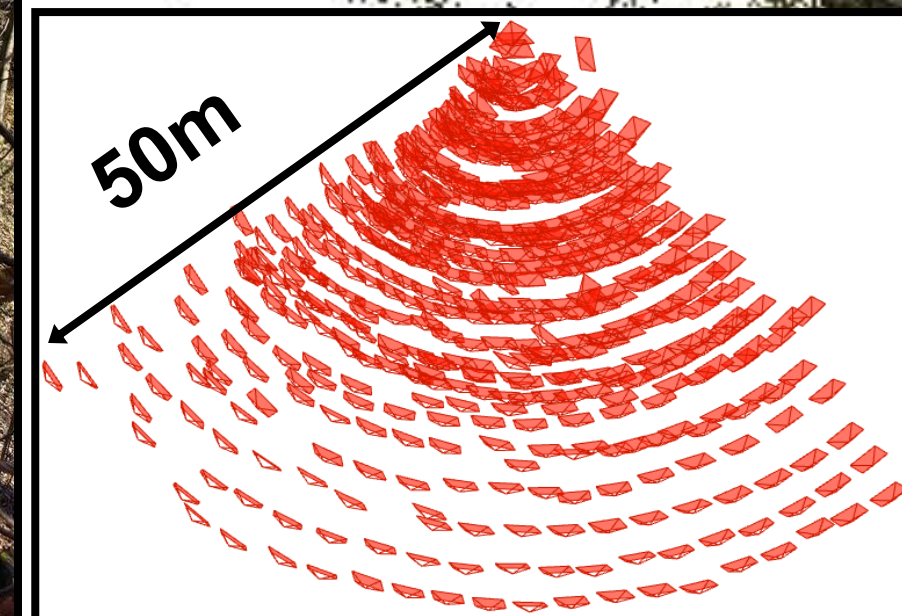
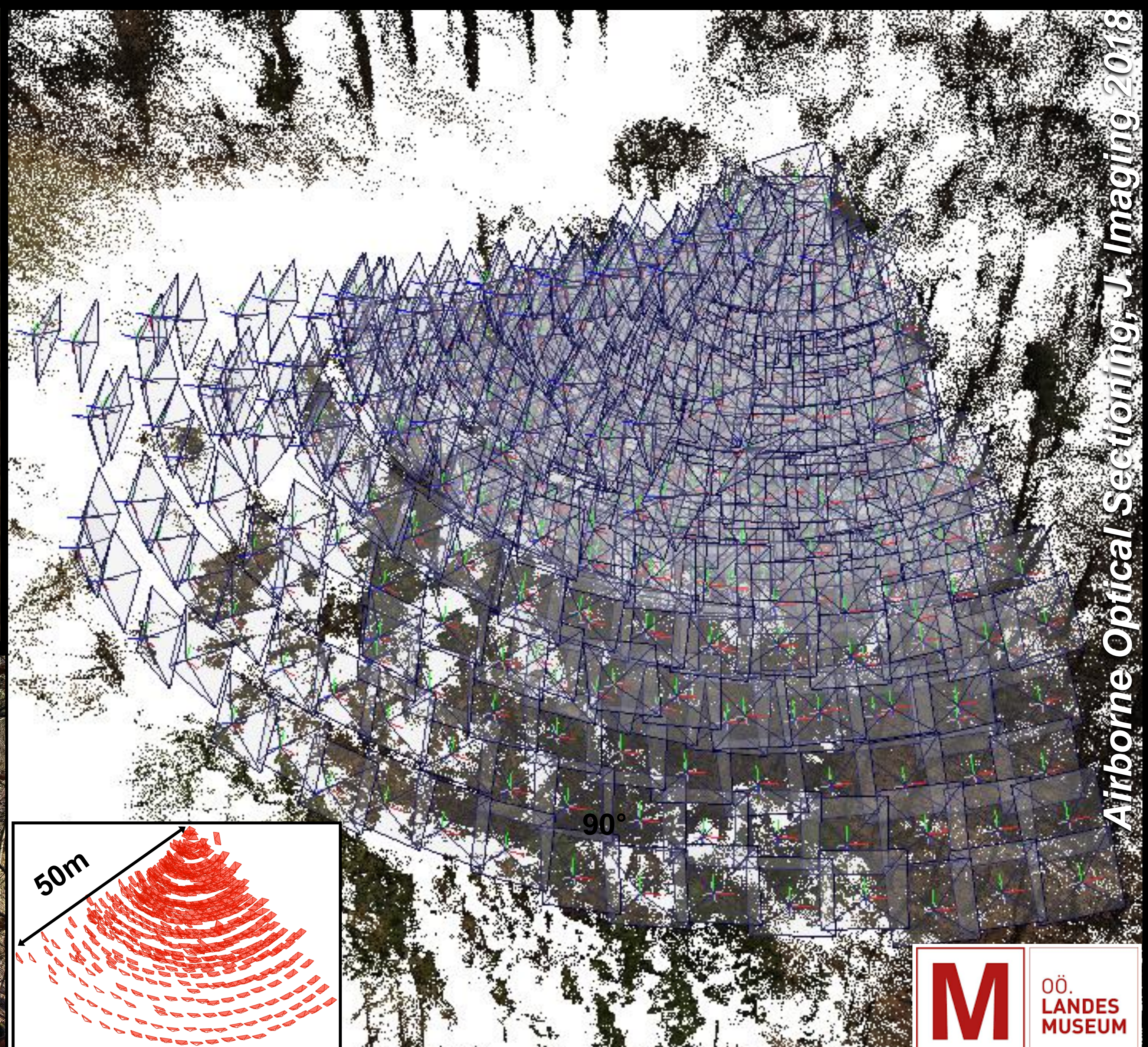
Airborne Optical Sectioning, J. Imaging 2018



Airborne Optical Sectioning, J. Imaging 2018



Airborne Optical Sectioning, J. Imaging 2018

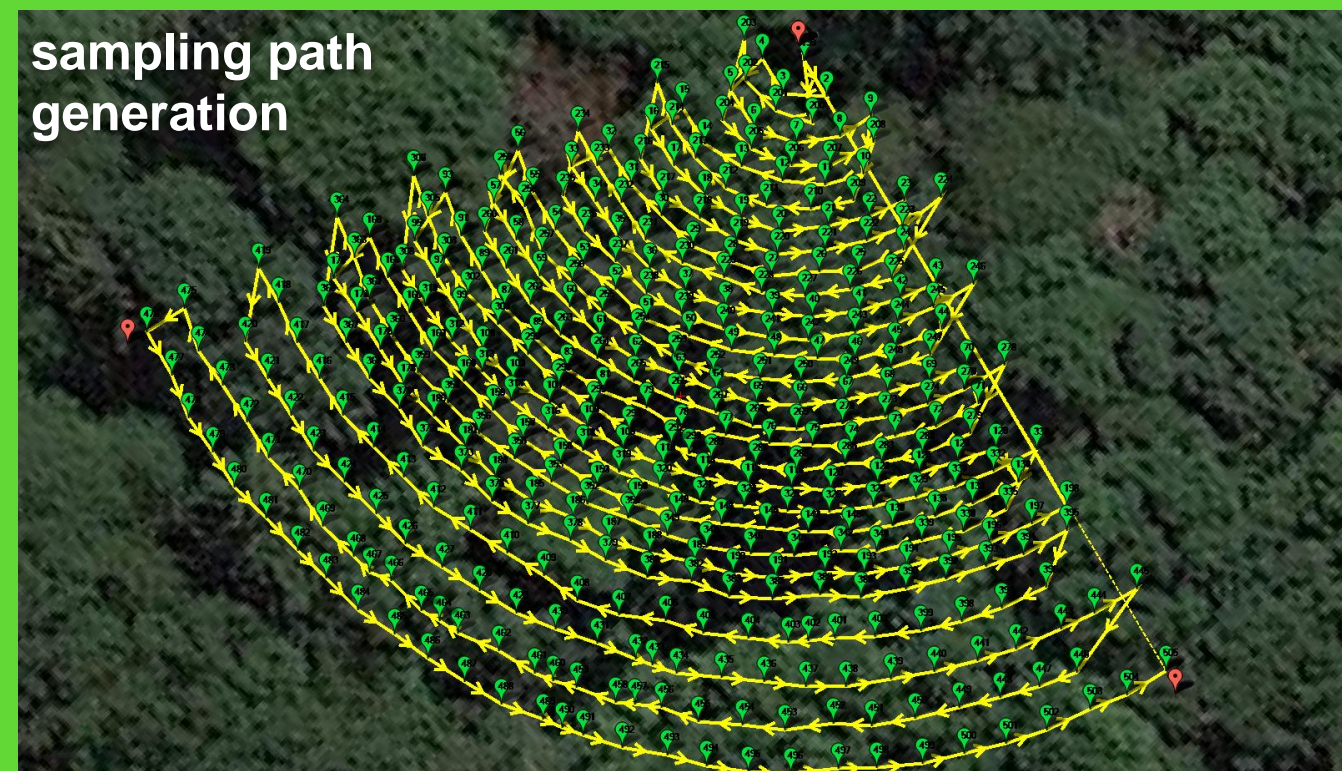
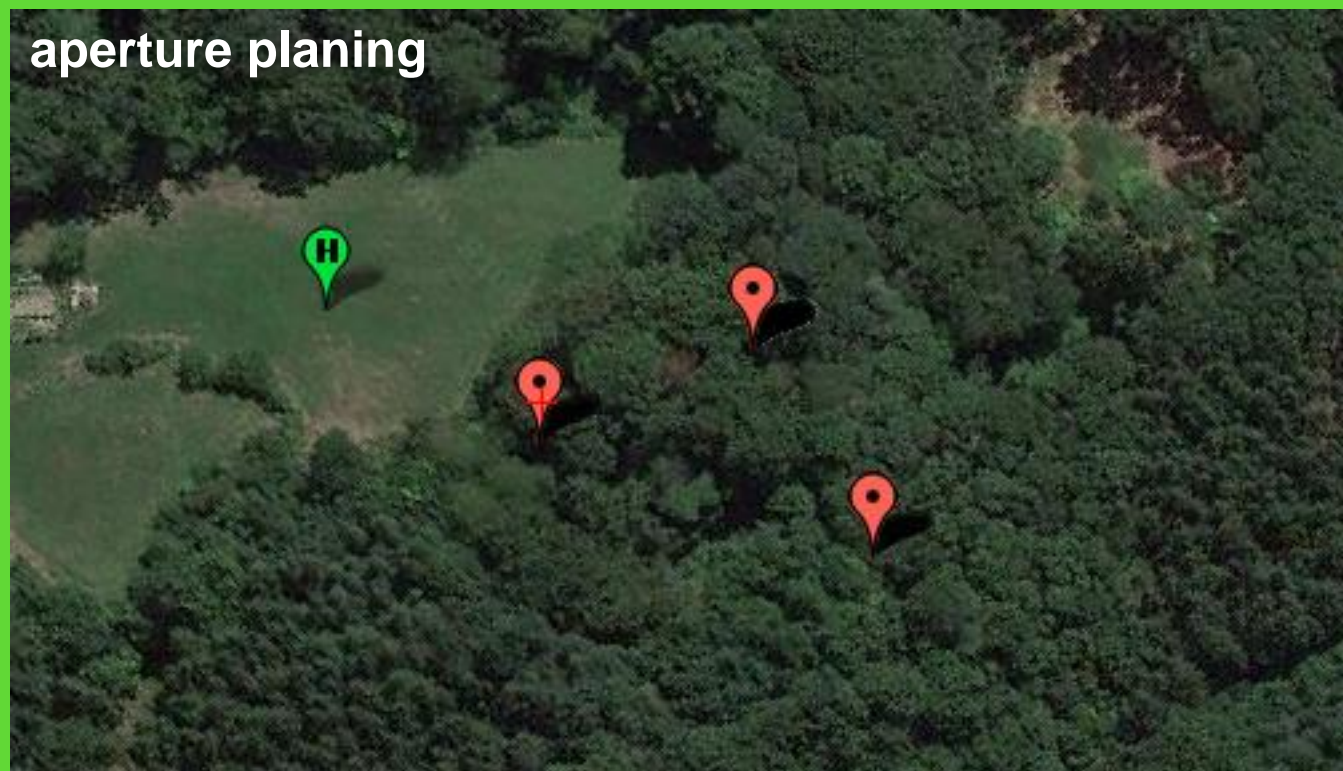




Airborne Optical Sectioning, J. Imaging 2018

Process

flight planning



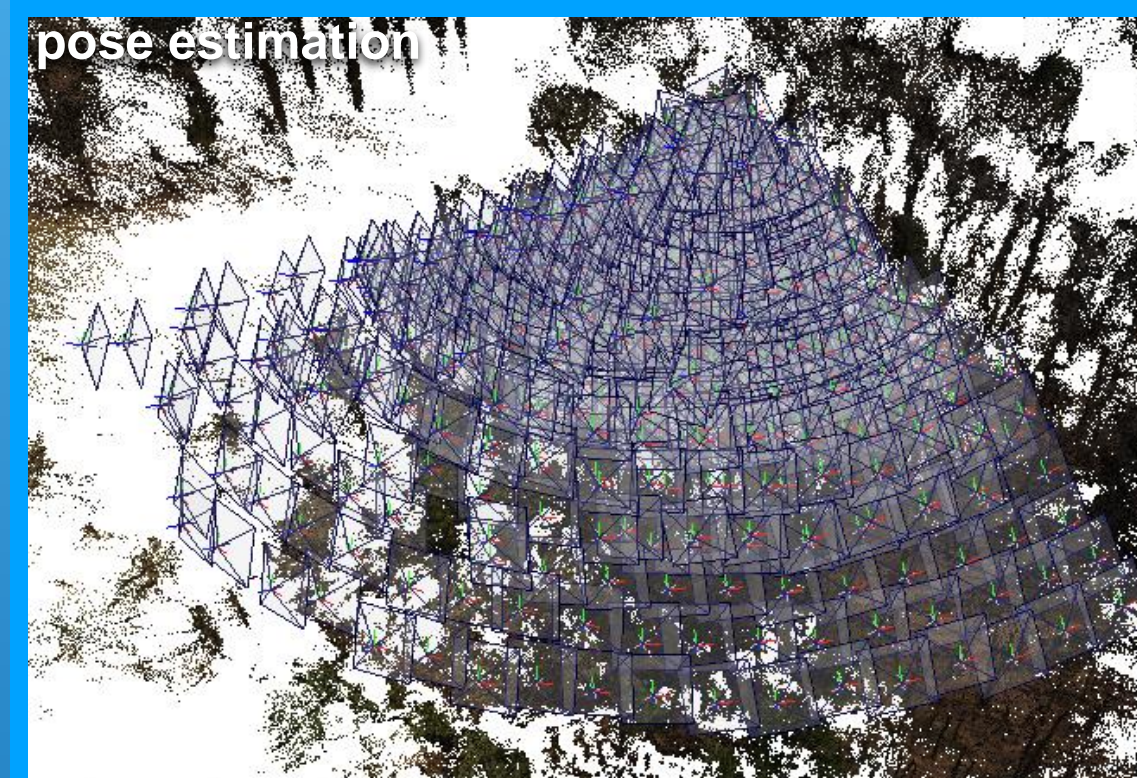
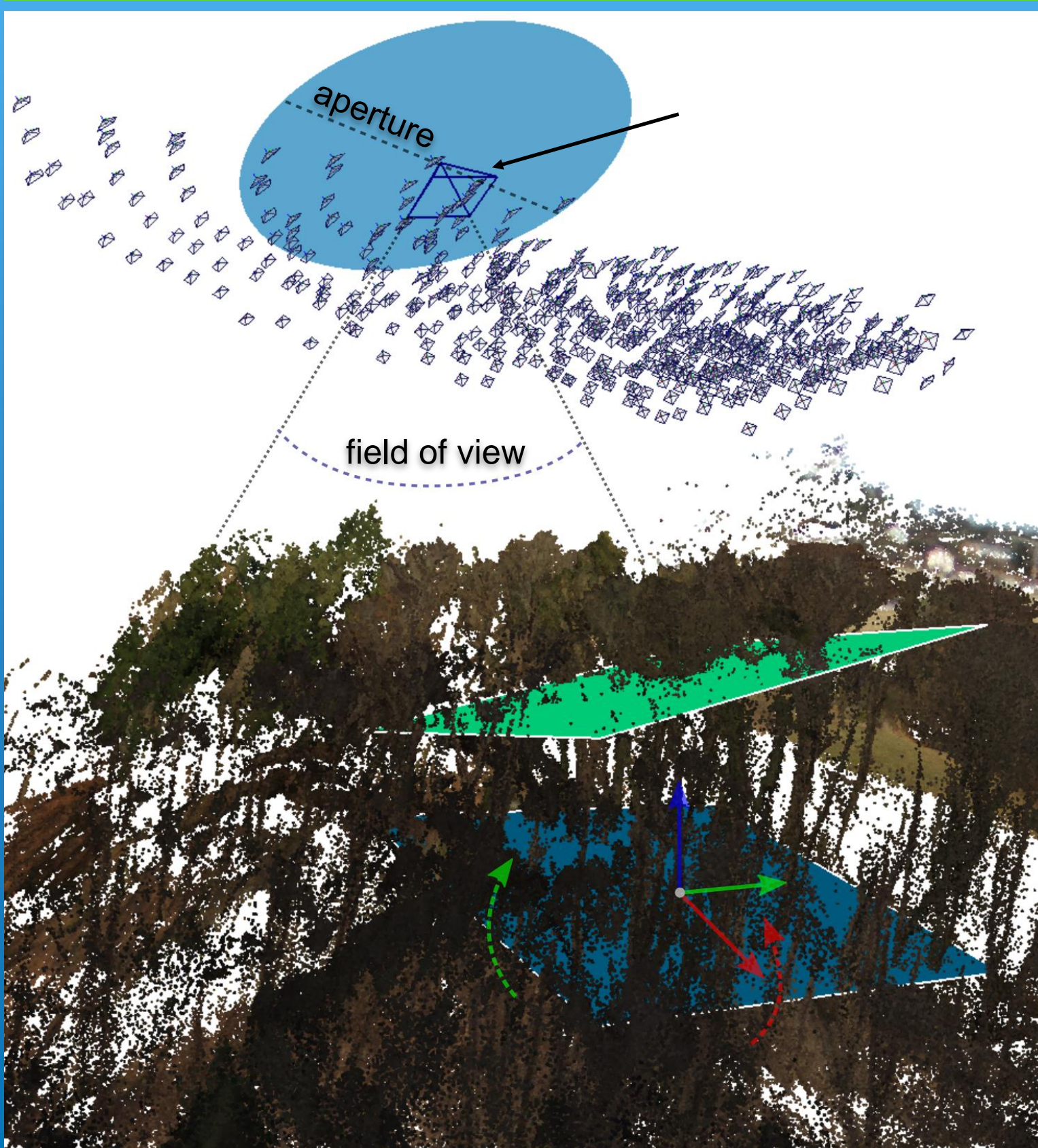
geo-coordinates of aperture outline
(longitude, latitud, altitude)

waypoint protocol (QGC)

autonomous scanning



omnidirectional images



drone poses

rectified images

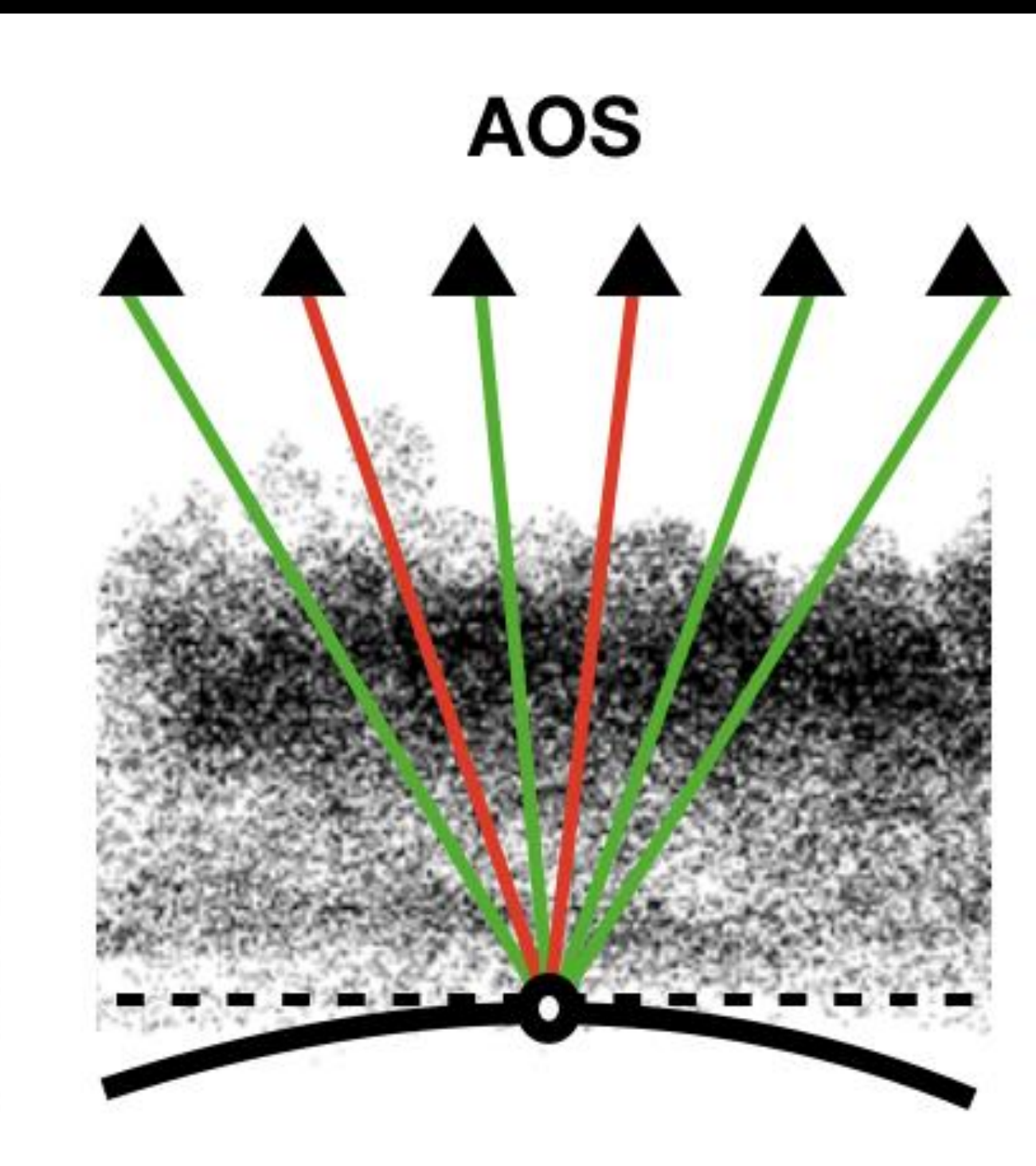
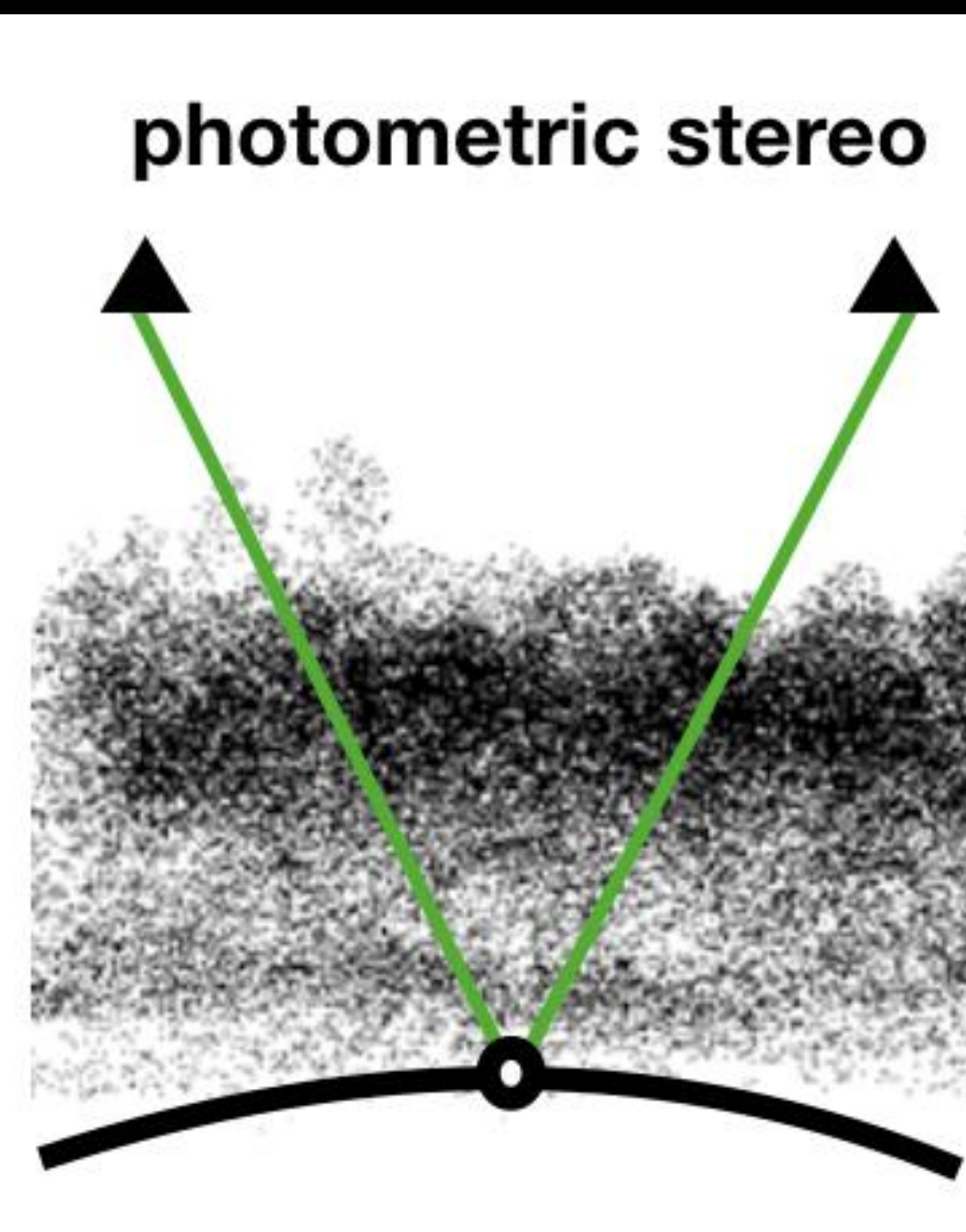
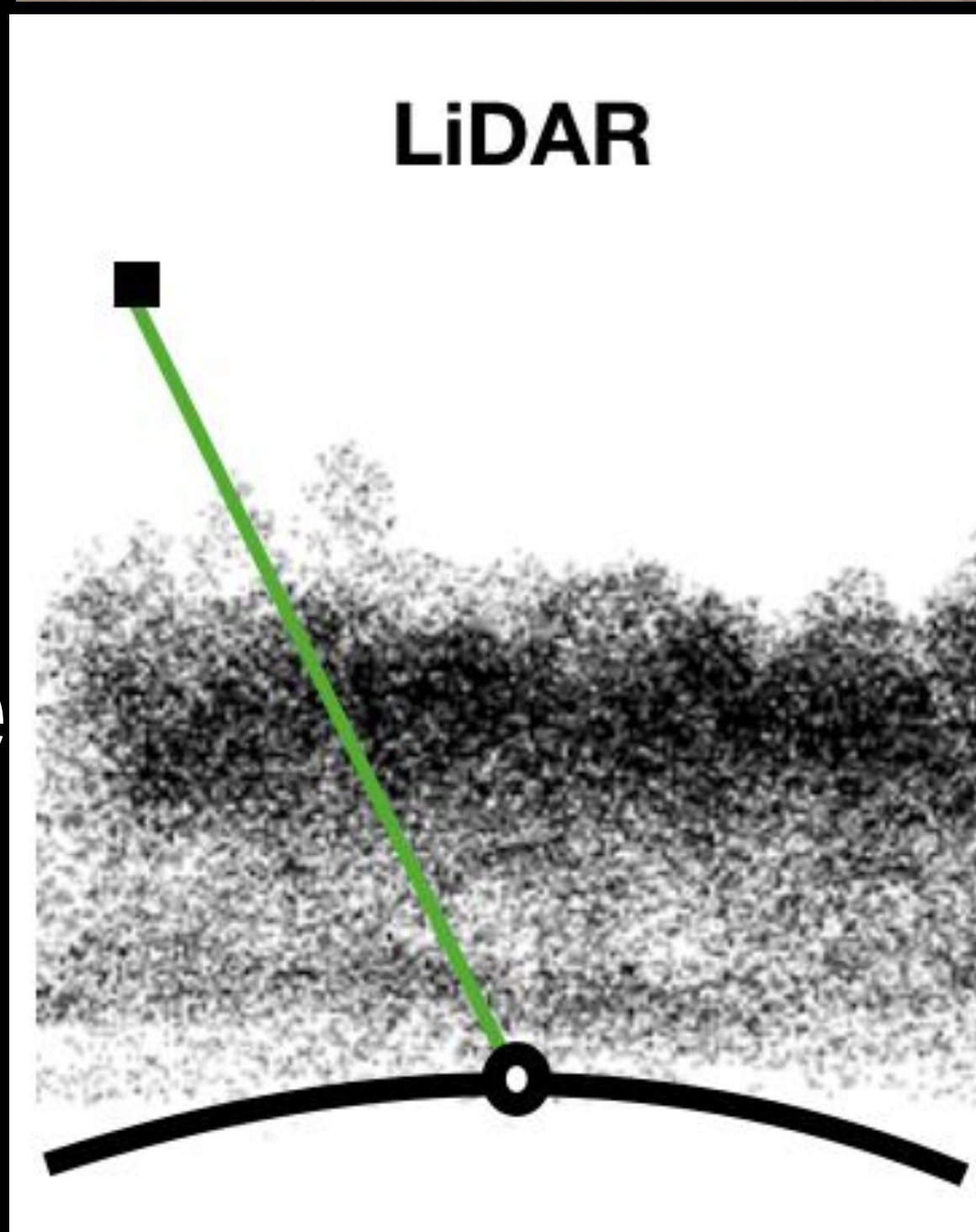
camera calibration parameters

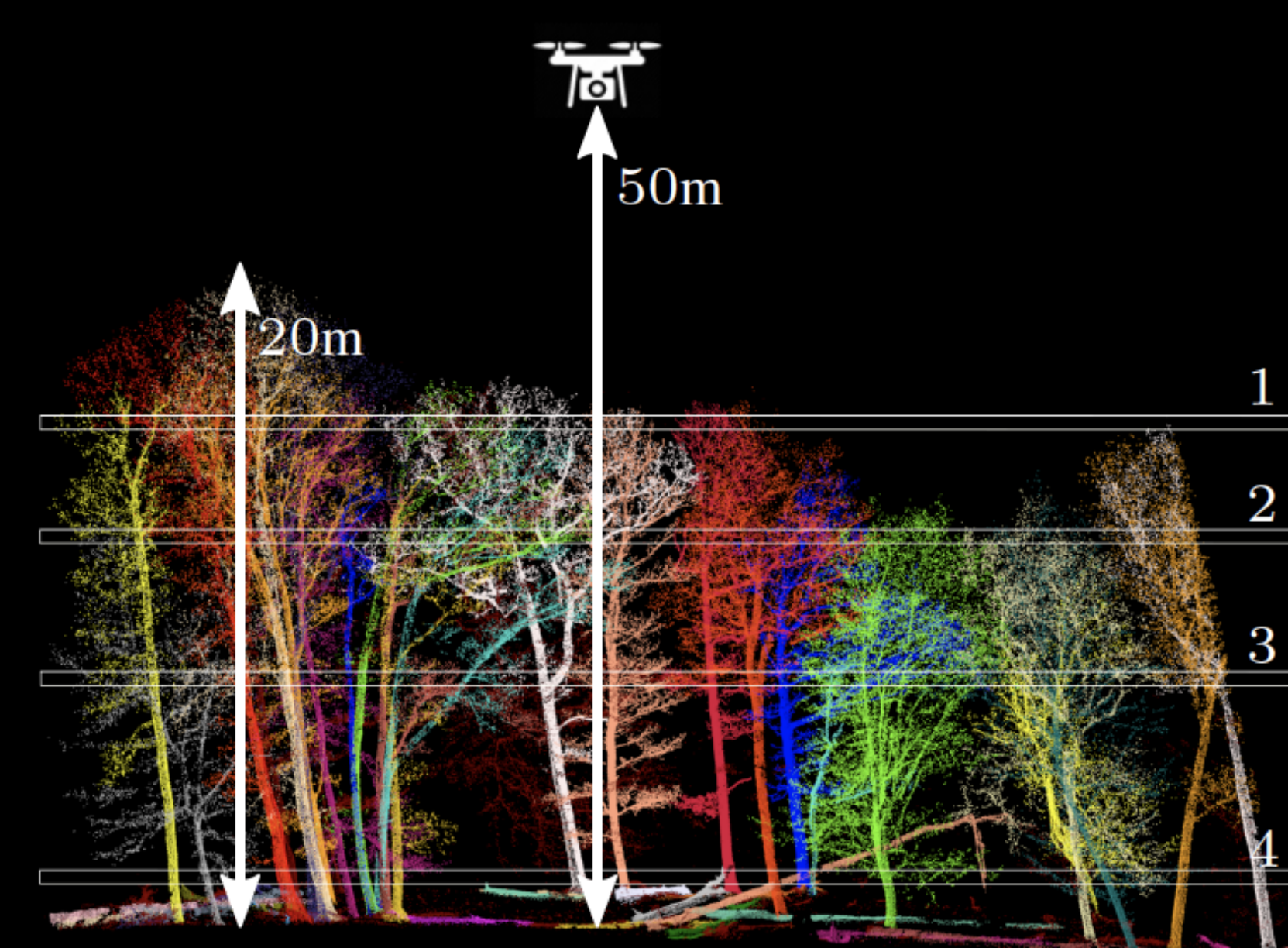
post-processing

*Synthetic Aperture Imaging with Drones,
IEEE CG&A 2019*



Does the aperture really have to be large and densely sampled?



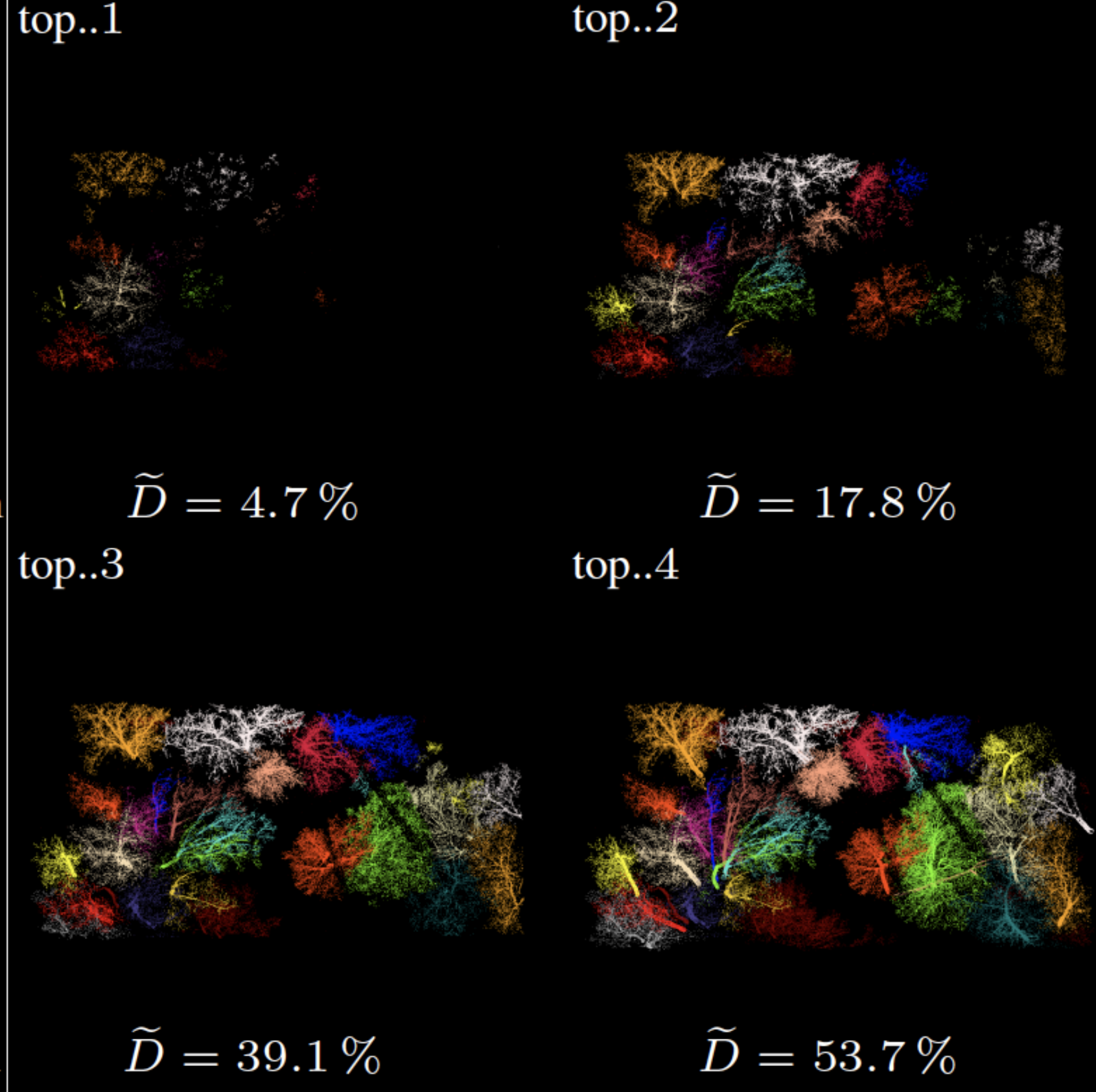
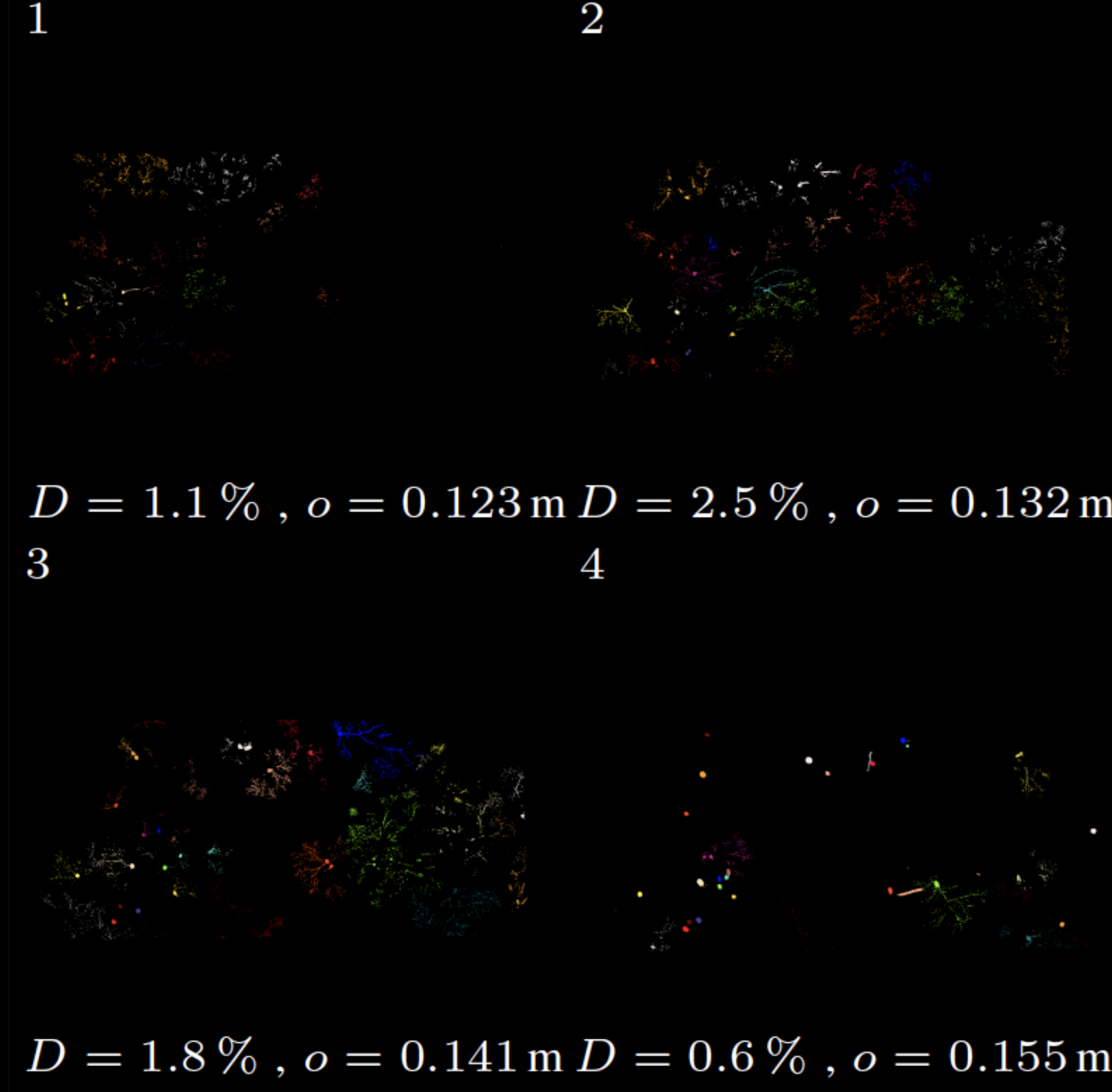


average over entire height range :

$$D = 0.95 \% \text{ (average)}$$

$$\tilde{D} = 56.7 \% \text{ (integral)}$$

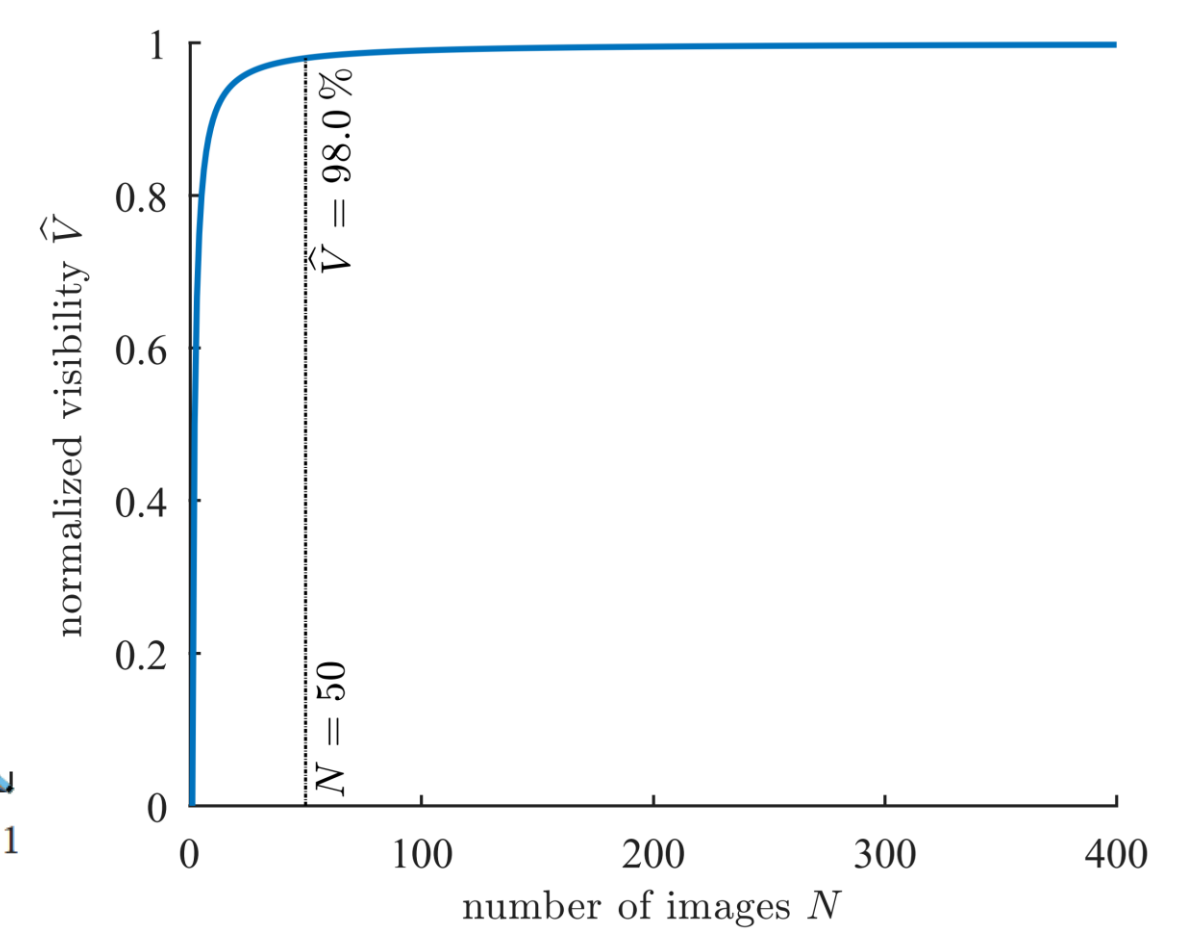
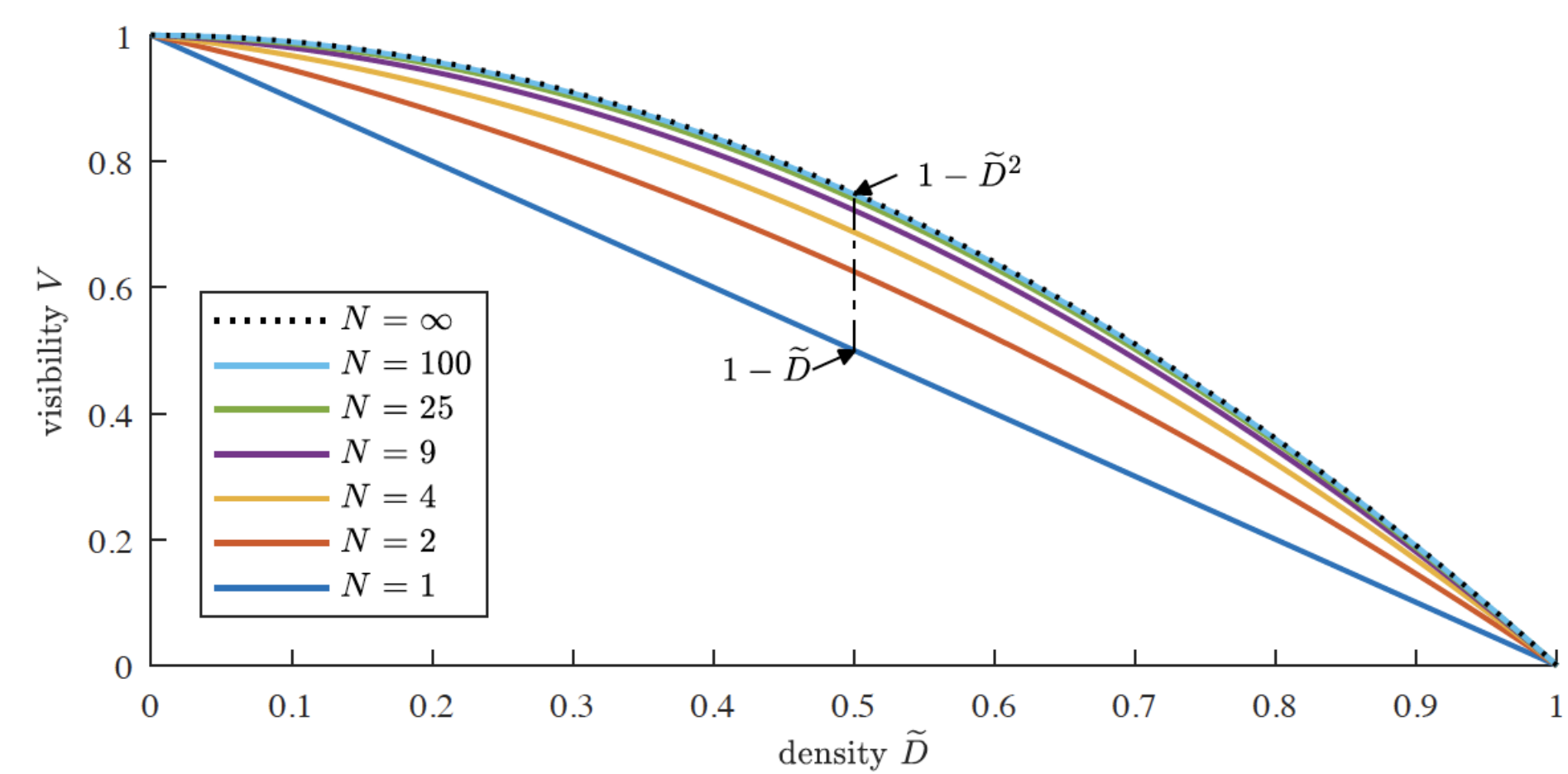
$$o = 0.138 \text{ m (average)}$$



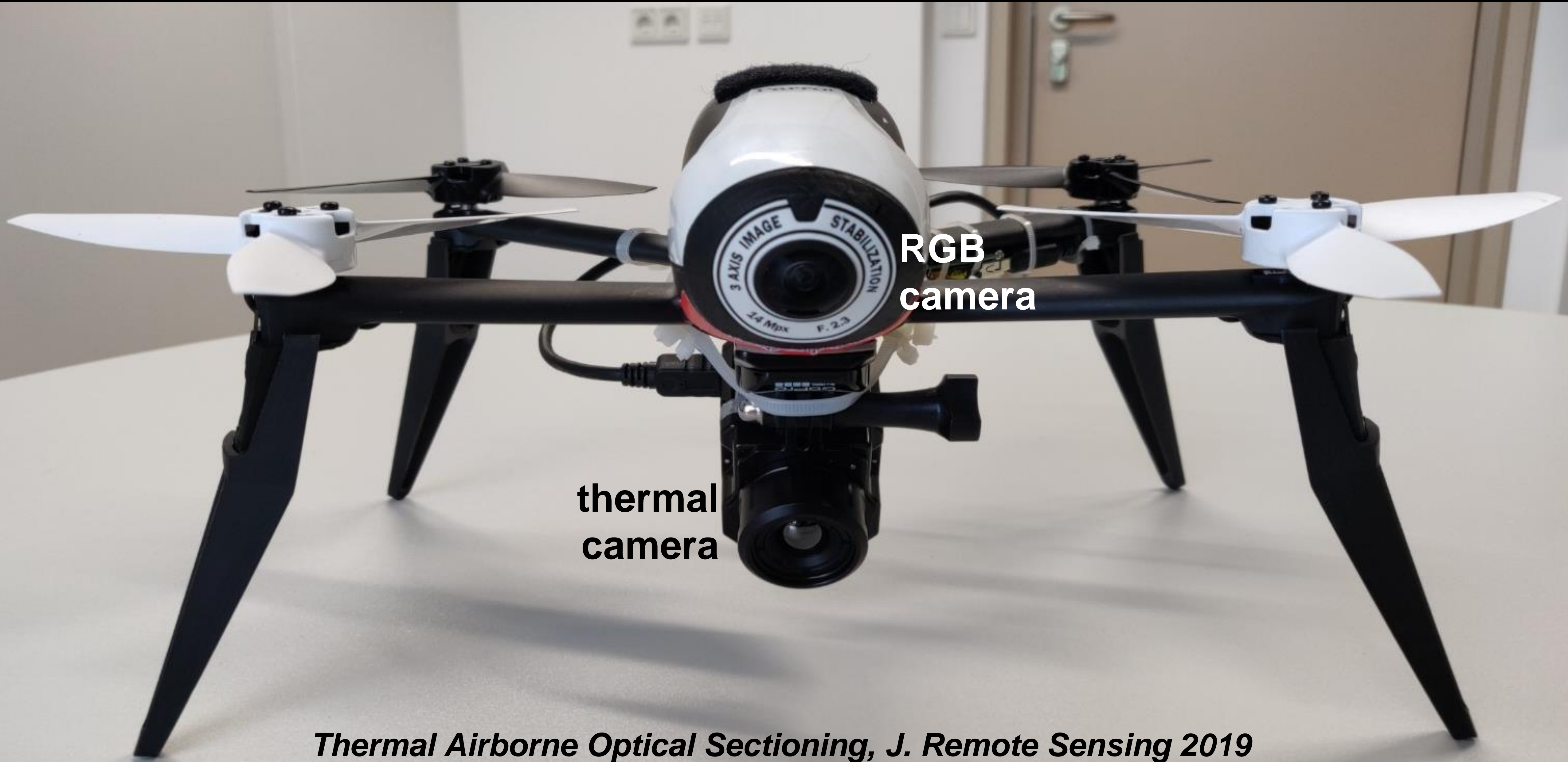
(1) There exists a limit to the baseline (distance) of sample positions. The minimal (optimal) baseline is the one that results in a disparity equal to the projected occluder size. Larger baselines do not improve visibility.

(2) There exists a limit to achievable visibility improvement that depends on the density of the occluder volume. The maximum visibility gain is achieved at a density of 50%.

(3) The (to the possible range normalized) visibility gain is independent of the occlusion density. It is directly correlated to a fixed number of samples.

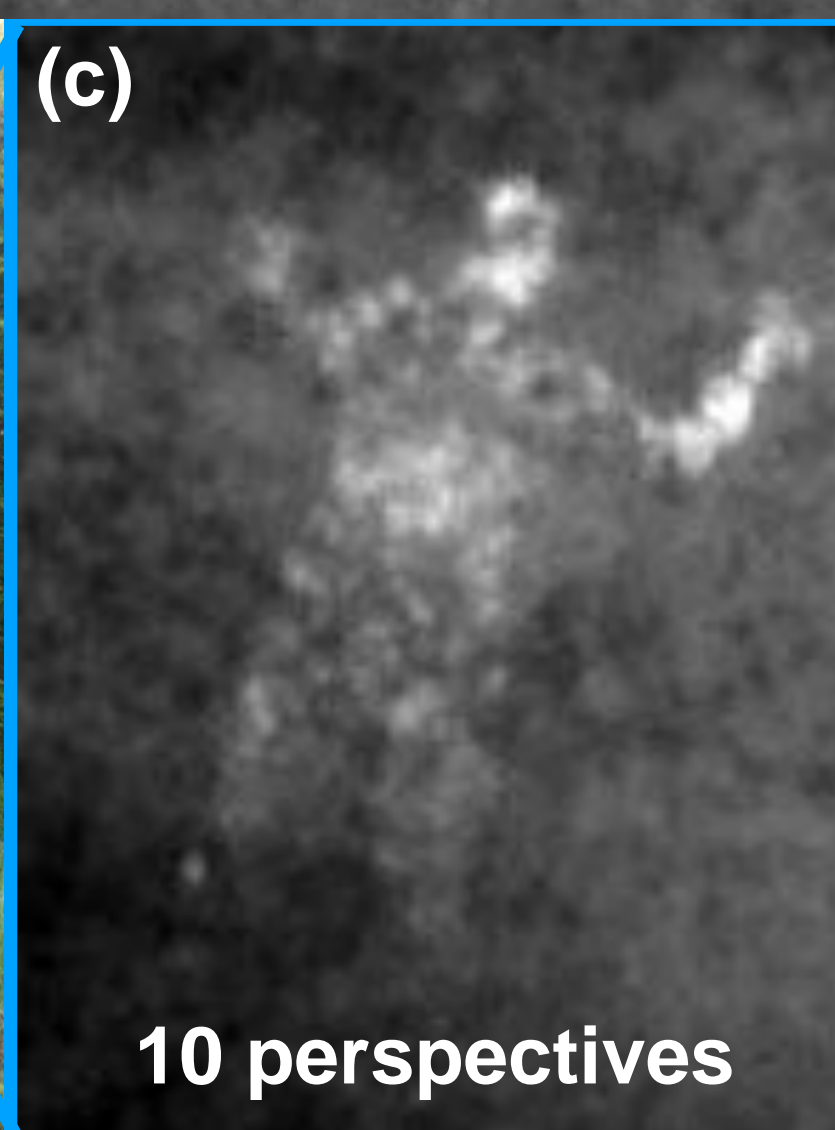
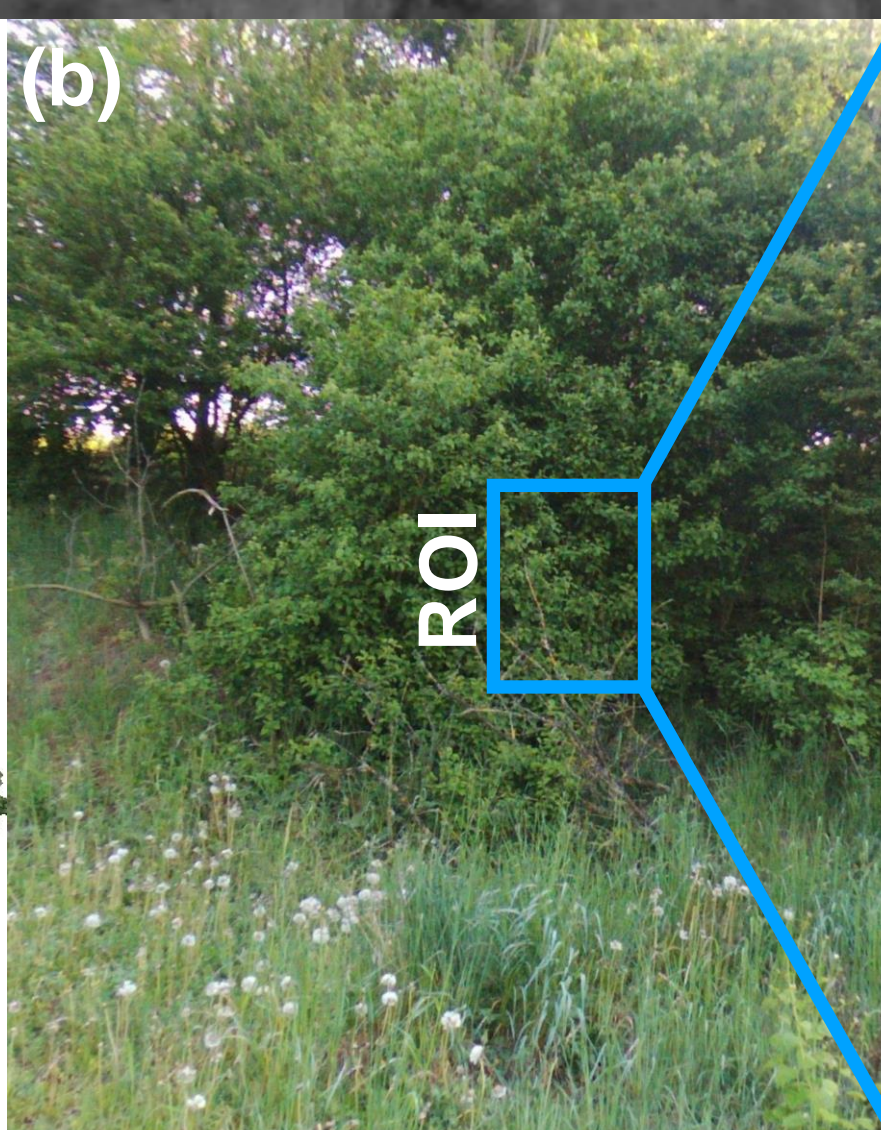
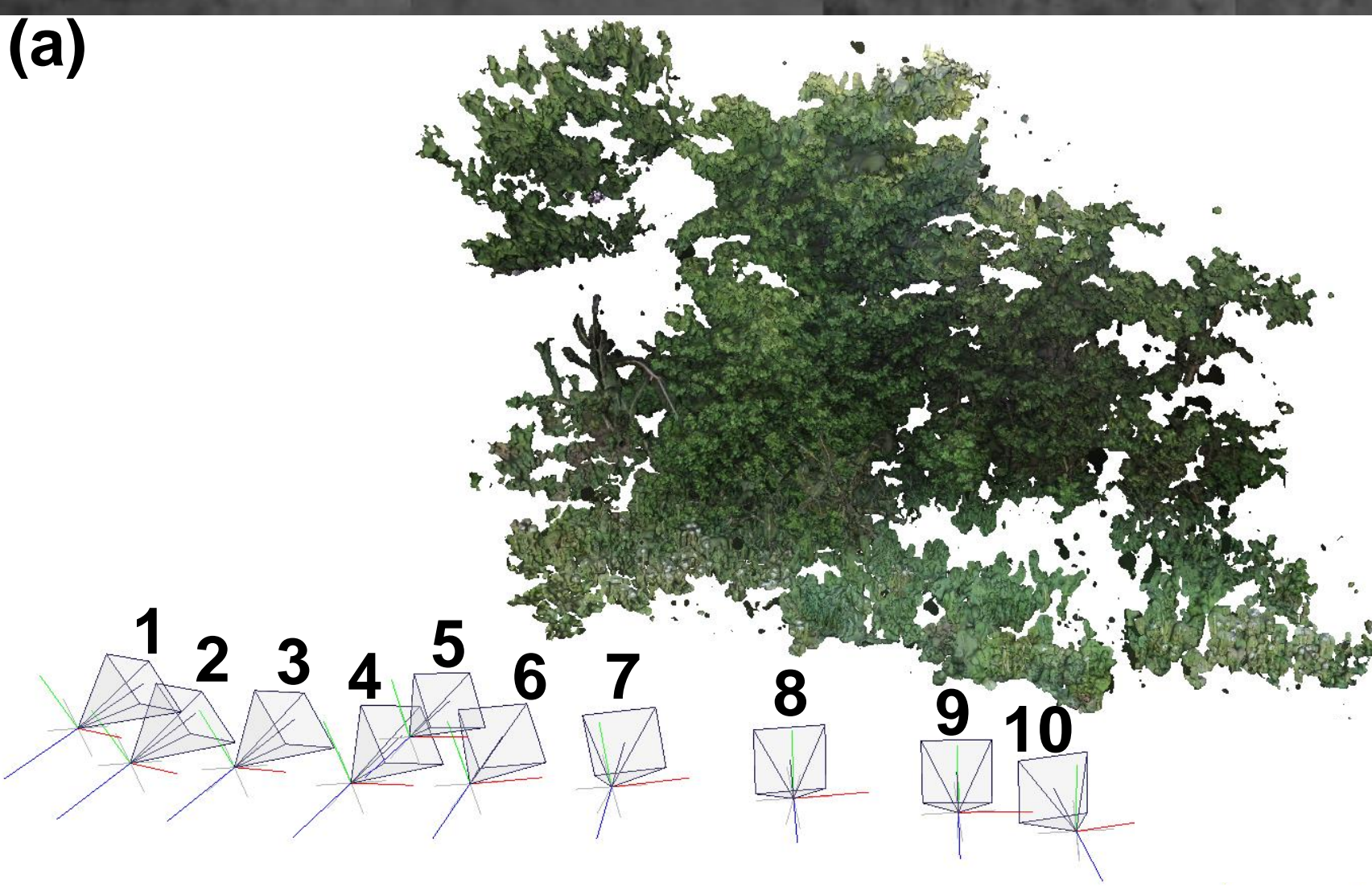
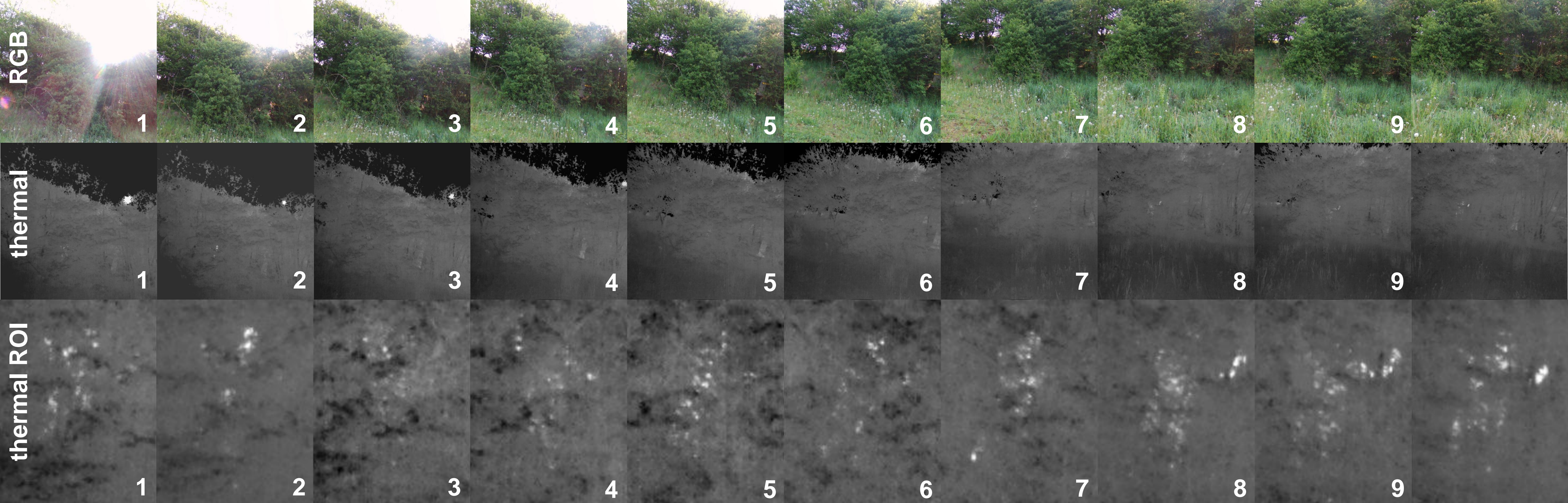


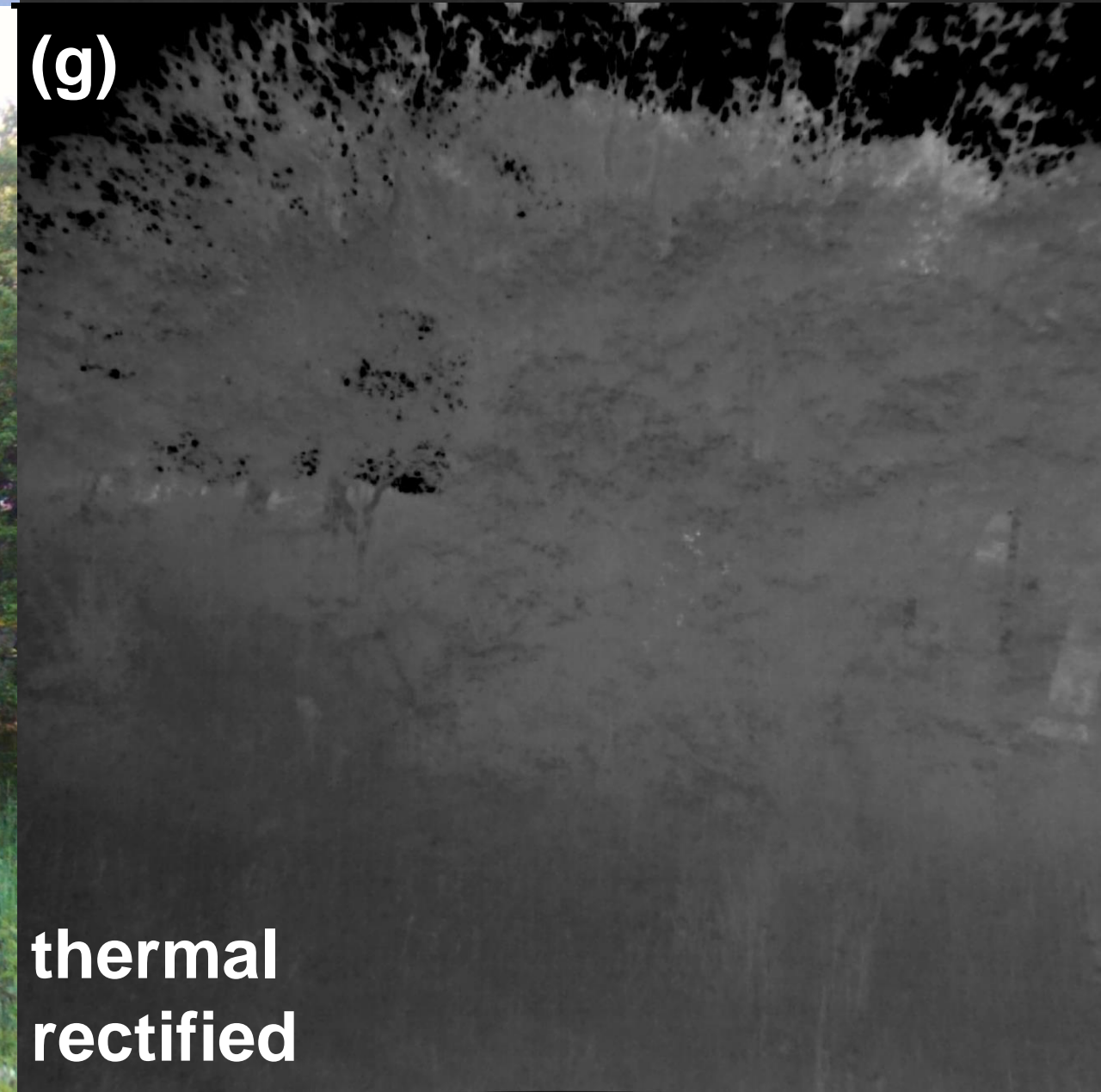
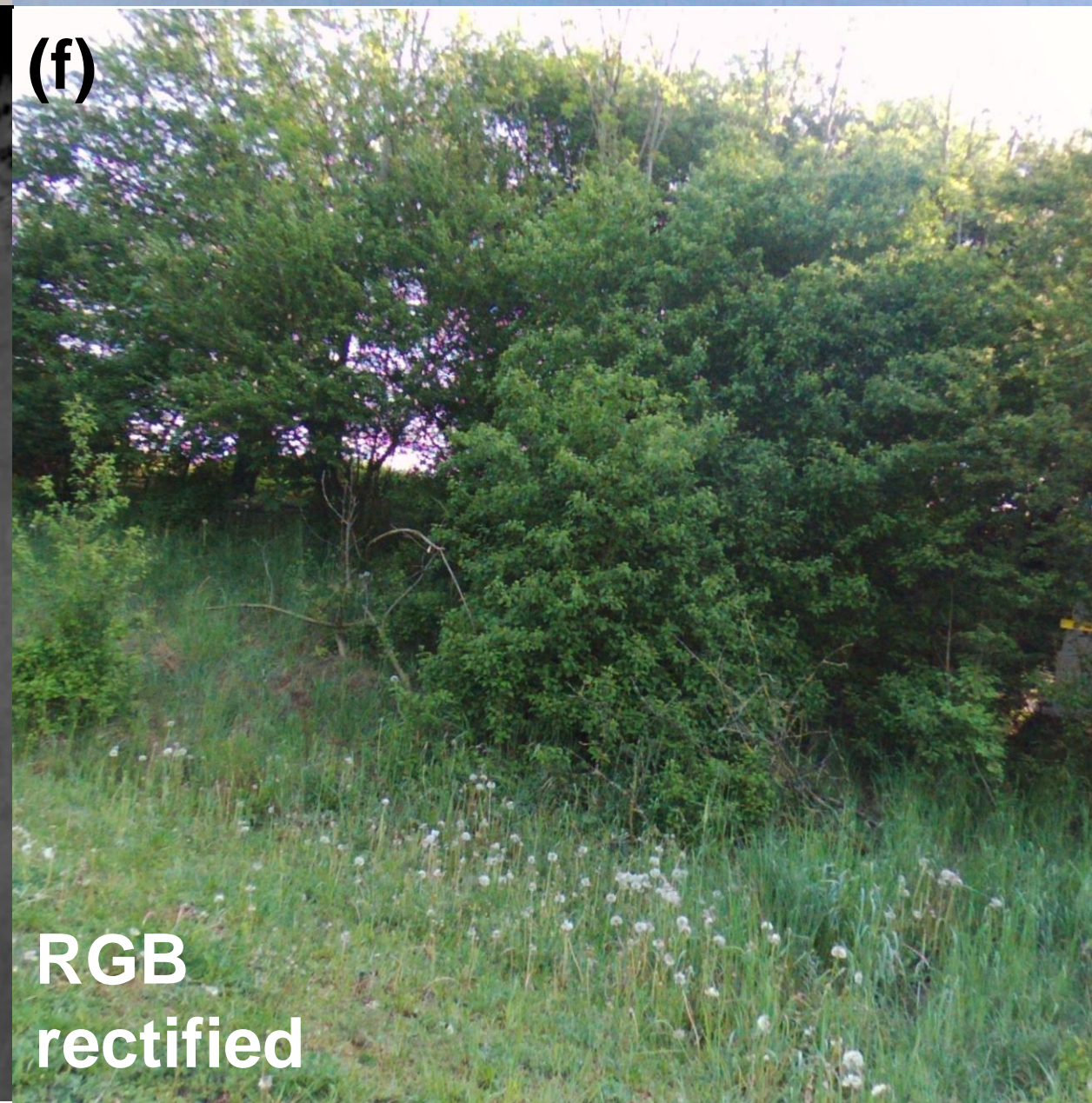
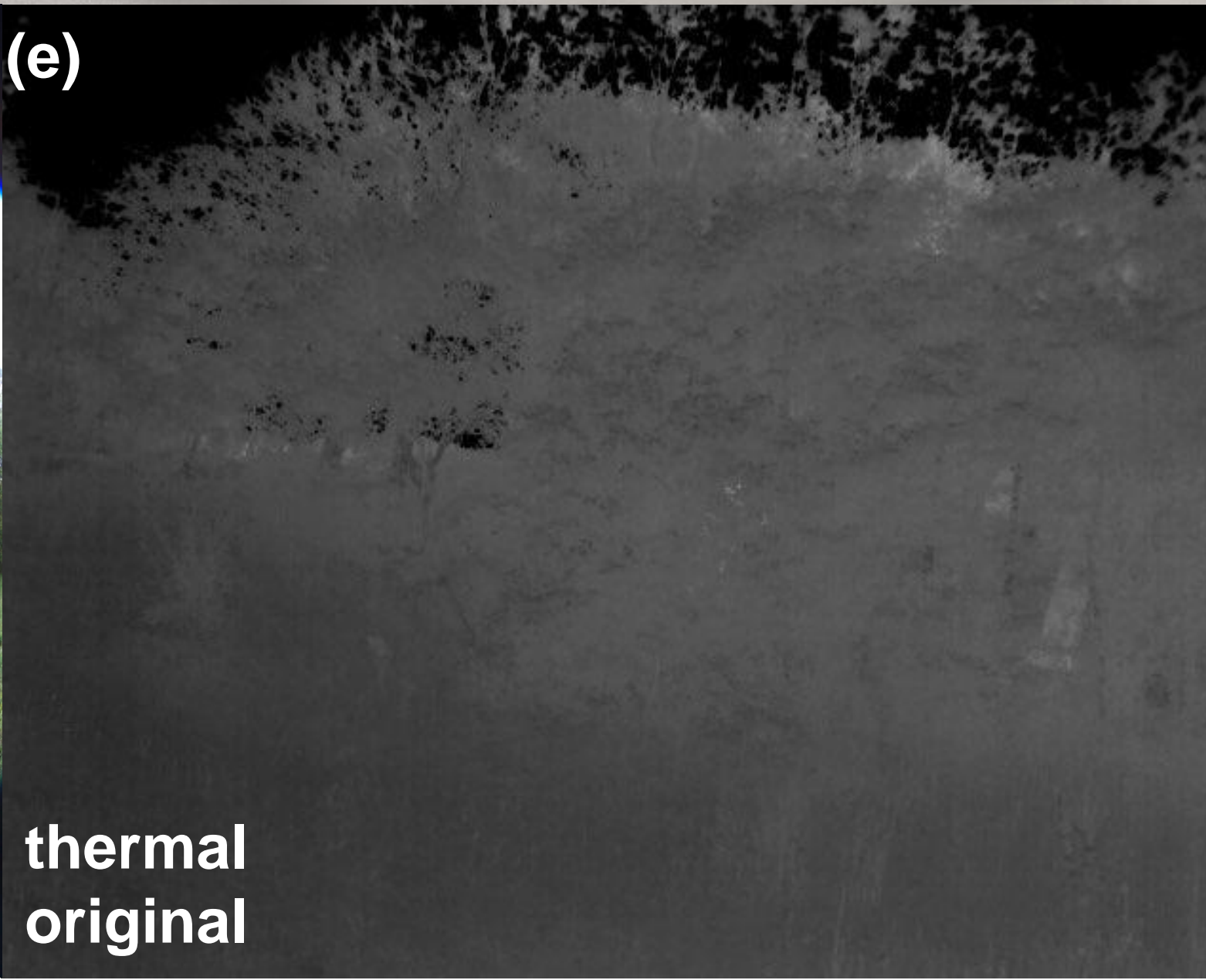
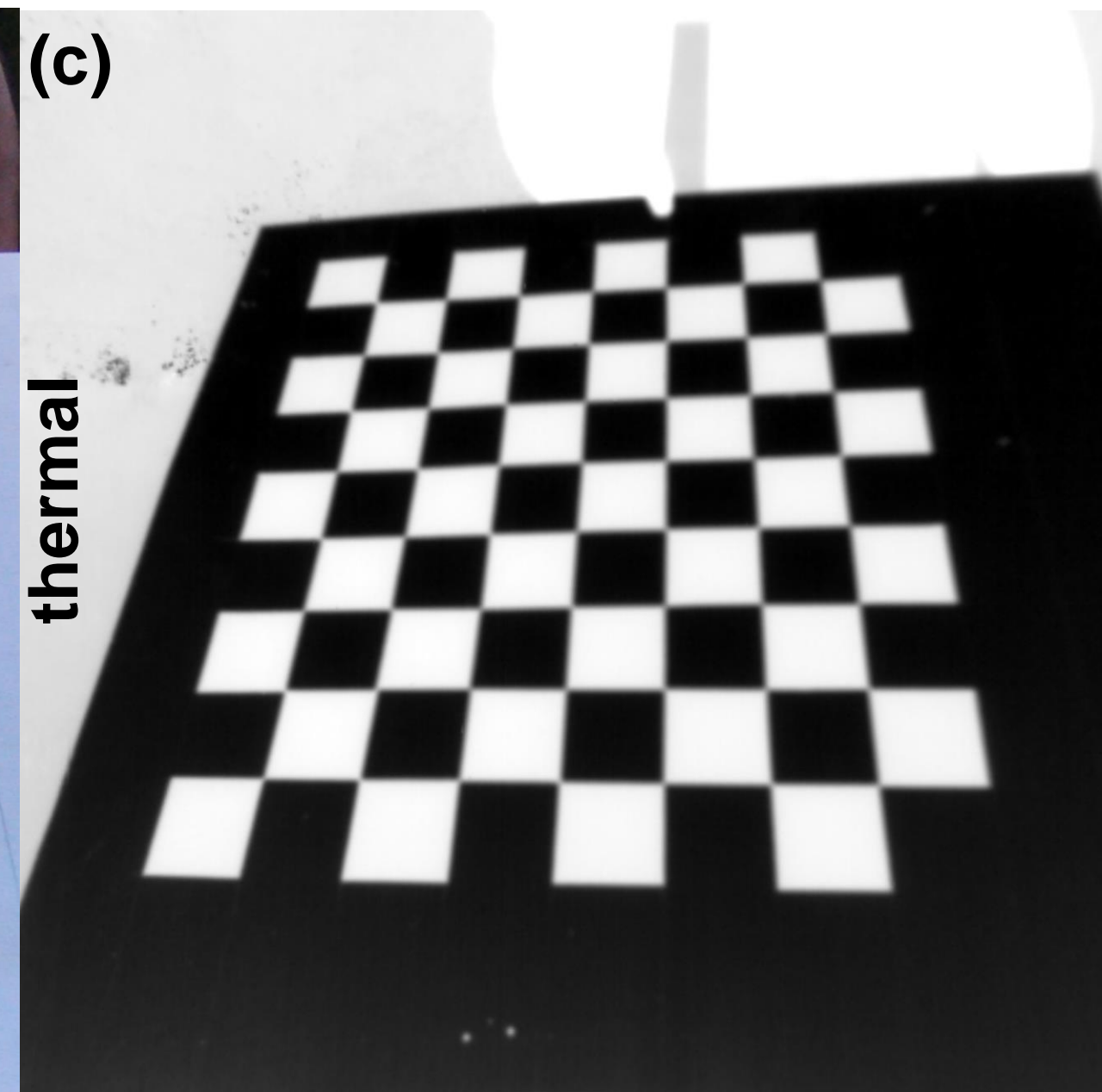
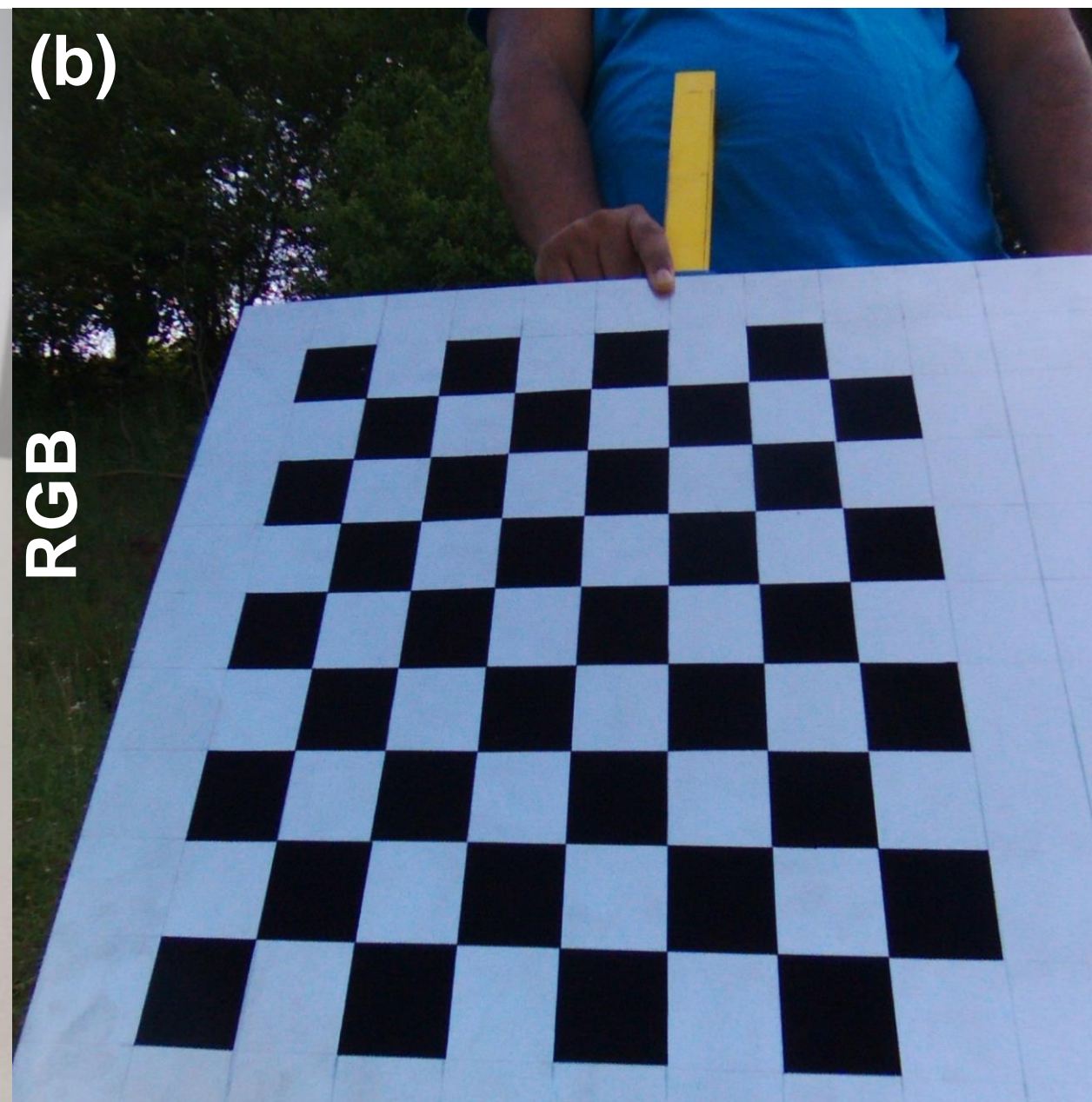
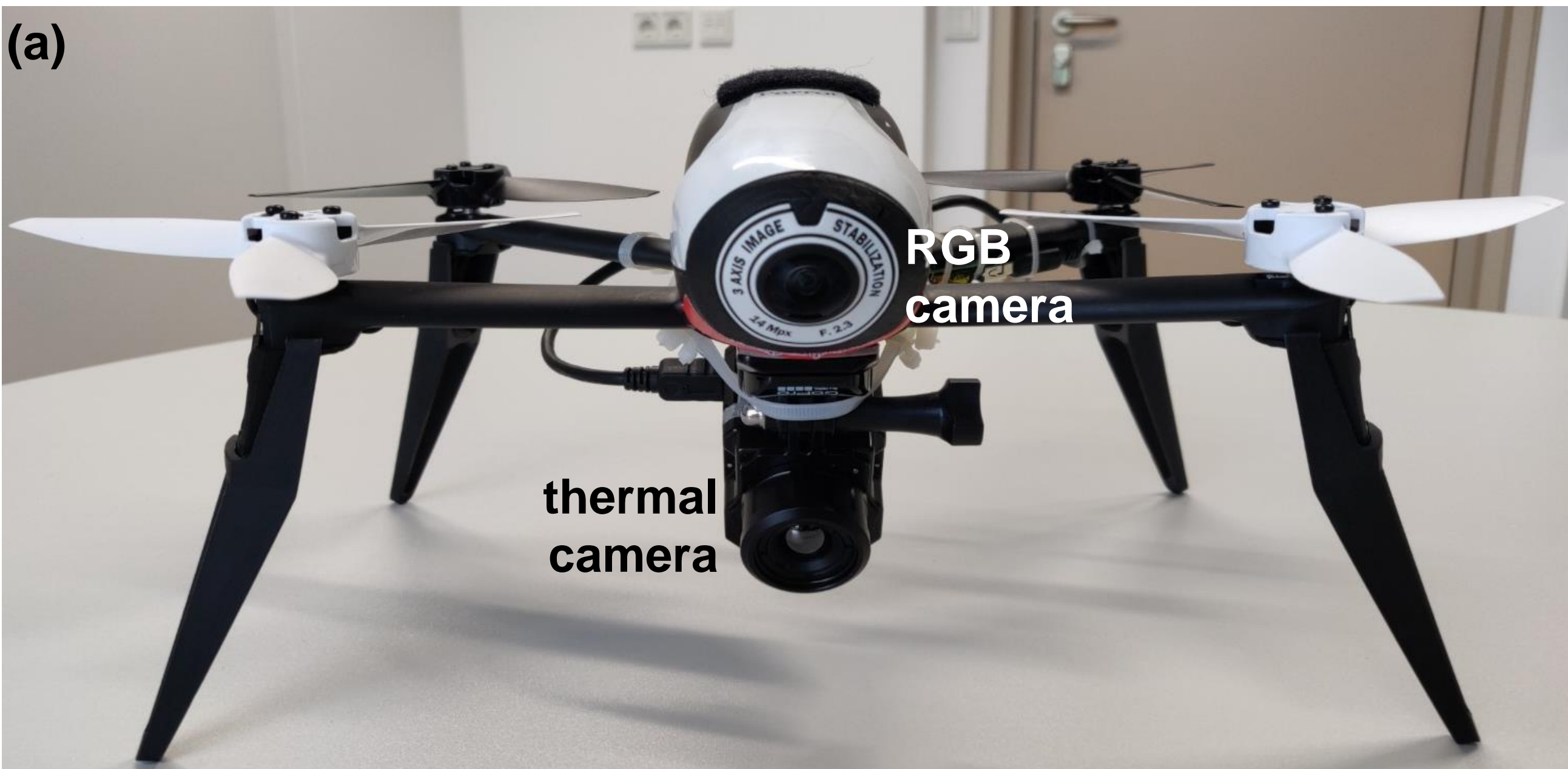
Thermal Airborne Optical Sectioning (TAOS)



***Thermal Airborne Optical Sectioning,
J. Remote Sensing 2019***









AOS

*redundant OktoXL 6S12
with synchronised Flir Vue Pro and
Sony A6000 (1.2m diameter, 5kg)*





Airborne Optical Sectioning for Nesting Observation, Nature SciRep, 2020

