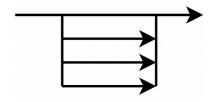
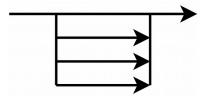
Pthreads Basics

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POSIX Threads

POSIX: Portable Operating System Interface IEEE standards defining API of software for UNIX-like operating systems POSIX threads (Pthreads) standard approved 1995, amendments functions for creating threads synchronizing threads thread interaction opaque data types for thread identifiers synchronization constructs attributes header file pthread.h

compilation: gcc -pthread -o prog prog.c

References:

D. R. Butenhof, *Programming with POSIX Threads*, Addison-Wesley, 1997 http://opengroup.org/onlinepubs/007908799/xsh/pthread.h.html

(P)Threads in Linux

How can a thread-library be implemented?

Abstraction levels:

threads: created by a user program

kernel entity: "process", scheduled by operating system

processor: physical device, gets assigned kernel entities by scheduler

Design decision: how to map threads to kernel entities?

M-to-1:

all threads of process mapped to one kernel entity fast scheduling (in library), but no parallelism

M-to-N:

threads of process mapped to different kernel entities two-level scheduling (library and kernel) incurs overhead, but allows parallelism

1-to-1:

each thread mapped to one kernel entity

scheduling in kernel, less overhead than in M-to-N case, allows parallelism used in most modern Linux systems: *Native POSIX Threads Library (NPTL)*

Pthread Lifecycle: States

Ready

able to run, waiting for processor

Running

on multiprocessor possibly more than one at a time

Blocked

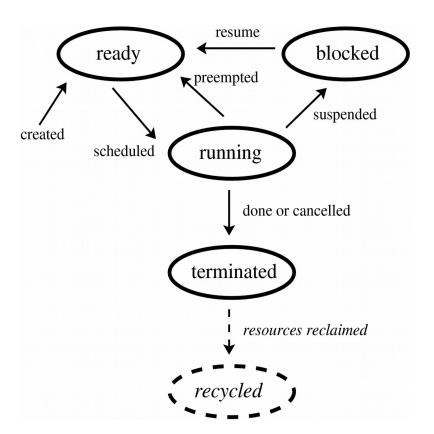
thread is waiting for a shared resource

Terminated

system resources partially released but not yet fully cleaned up thread's own memory is obsolete can still return value

(Recycled)

all system resources fully cleaned up controlled by the operating system



Pthread Creation

```
int pthread create(arg0, arg1, arg2, arg3)
    arg0: pthread t *tid ptr
        where to store thread ID of type pthread t
    arg1: const pthread att t *attr
        may set certain attributes at startup
        ignored for the moment: always pass NULL \rightarrow set default attributes
    arg2: void *(*start)(void *)
        pointer to thread's startup function
        takes exactly one void* as argument
    arg3: void *arg
        actual parameter of thread's startup function
    returns zero on success, else error code
thread ID is stored in *tid ptr
    pthread t pthread self() returns ID of current thread
    int pthread equal(pthread t tid1, pthread t tid2) compares IDs
Example: helloworld
```

main-Thread

Process creates thread which executes main-function \rightarrow "main-thread"

main-thread behaves slightly differently from ordinary threads:

termination of main-thread by returning from main causes process to terminate all threads of process terminate Example: helloworld

calling pthread_exit(...) in main-thread causes process to continue

all created threads continue

recall lifecycle: main-thread terminates \rightarrow resources partially released

Attention: stack may be released!

memory errors: dereferencing pointers into main-thread's (released) stack

Example: helloworld_buggy

Pthread Termination

```
generally: thread terminates if startup function returns
int pthread exit(void *value ptr)
    causes thread to terminate (special semantics in main-thread)
    implicitly called if thread's startup function returns (except in main-thread)
    value ptr is the thread's return value (see pthread join(...))
int pthread detach(pthread_t tid)
    resources of tid can be reclaimed after tid has terminated
    default: not detached
    any thread can detach any thread (including itself)
int pthread join(pthread t tid, void **value)
    returns when tid has terminated (or already terminated), caller blocks
    optionally stores tid's return value in *value
        return value from calling pthread exit(...) or returning from startup function
    joined thread will be implicitly detached
    detached threads can not be joined
```

Pthread Termination - Examples

Example: helloworld_join

Returning values from threads

returning values from threads via pthread_join(...)

example: returnval

but: waiting for termination often not needed

good practice to release system resources as early as possible

alternative to pthread_join(...): custom return mechanism

threads store their return values on the heap

Example: returnval_heap

problem: need to notify main-thread somehow that all threads have written results

error: joining a detached thread

resources are (may be or not) already released

join should fail

Example: returnval_buggy

error: returning pointer to local variable

Example: returnval_buggy

Pthread Lifecycle Revisited (1/2)

Creation

process creation \rightarrow main-thread creation

pthread_create(...): new threads are ready

<u>no</u> synchronization between pthread_create(...) and new thread's execution

Startup

main-thread's main function called after process creation newly created threads execute startup function

Running

ready threads are eligible to acquire processor \rightarrow will be running scheduler assigns timeslice to ready thread \rightarrow threads will be preempted switching threads \rightarrow context (registers, stack, pc) must be saved

Blocking

running threads may block, e.g. to wait for shared resource blocking threads become ready (not running) again

Pthread Lifecycle Revisited (2/2)

Termination

generally: when thread returns from startup function

pthread_exit

can also explicitly be cancelled by pthread_cancel(...)

(optional cleanup handlers are called)

only thread's ID and return value remain valid, other resources might be released terminated threads can still be joined or detached

joined threads will be implicitly detached, i.e. all its system resources will be released

Recycling

occurs immediately for terminated, detached threads \rightarrow all resources released

Creating and Using Threads: Pitfalls

Sharing pointers into stack memory of threads perfectly alright, but handle with care passing arguments returning values Resources of terminated, non-detached threads can not fully be released large number of threads \rightarrow performance problems? should join or detach threads Relying on the speed/order of individual threads do not make any assumptions! need mechanism to notify threads that certain conditions are true example: returnval heap must prevent threads from modifying shared data concurrently example: sum

→ Synchronization